

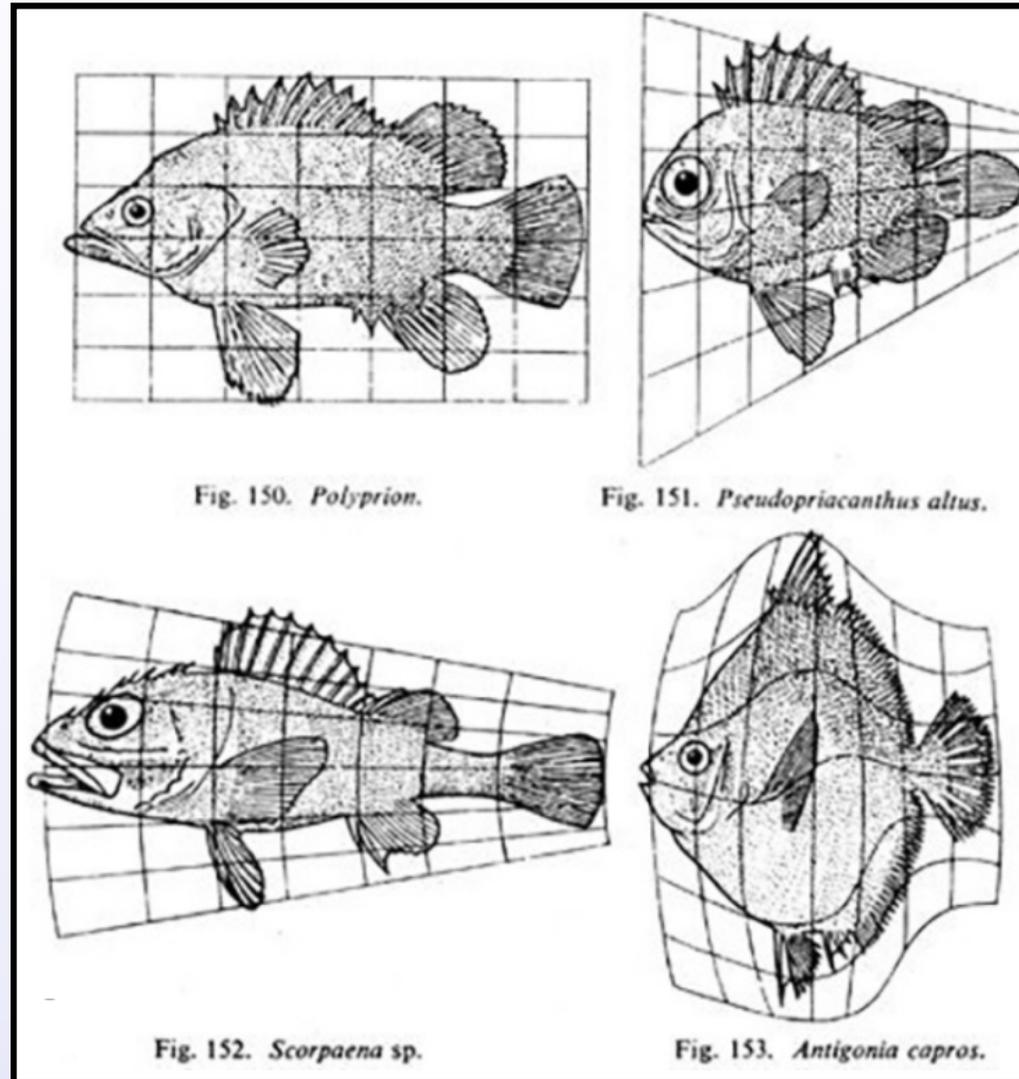


University of Geneva,
Switzerland

From active nematic surfaces to biological
morphogenesis

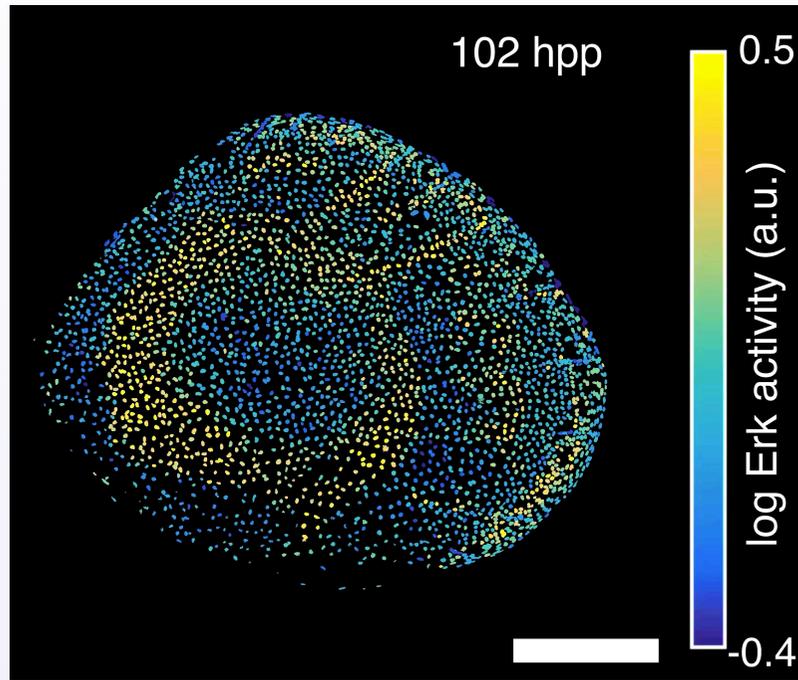
Guillaume Salbreux

Diversity of shapes in biology



[On growth and form- D'Arcy Thompson - 1917]

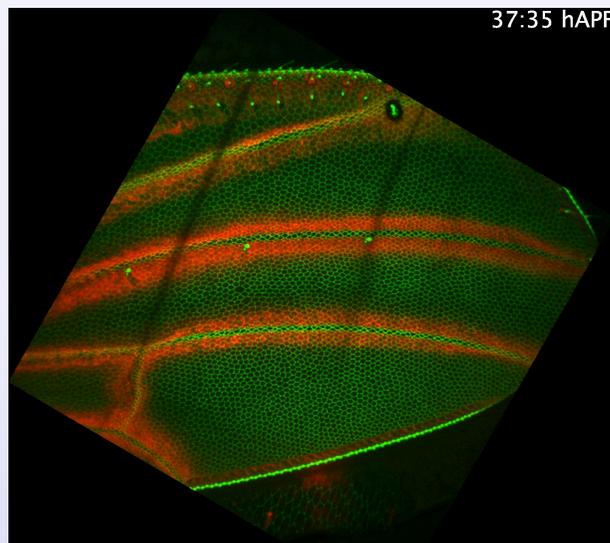
On growth, form and flows



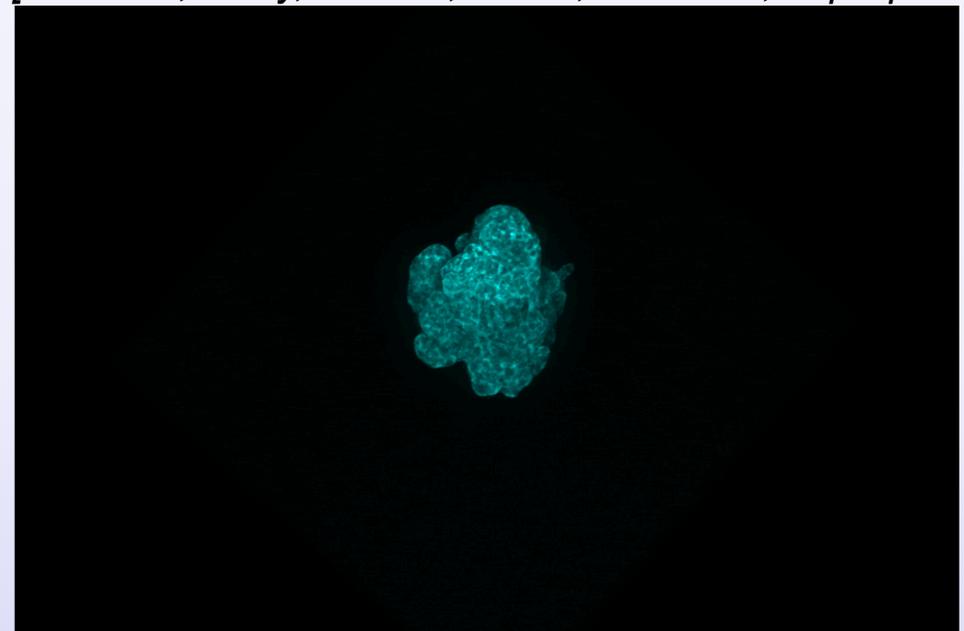
[De Simone & al, Nature, 2021]



[Delorme, Cuny, Mazzei, Rauzi, Salbreux, in preparation]



[Herszterg & al, Dev Cell, 2025]



[B. Canales, A. Elosegui-Artola, R. Rollin, G. Salbreux]

Continuum theories of active matter

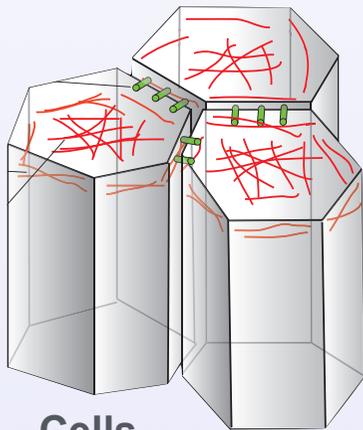
Microscopic

Mesososcopic

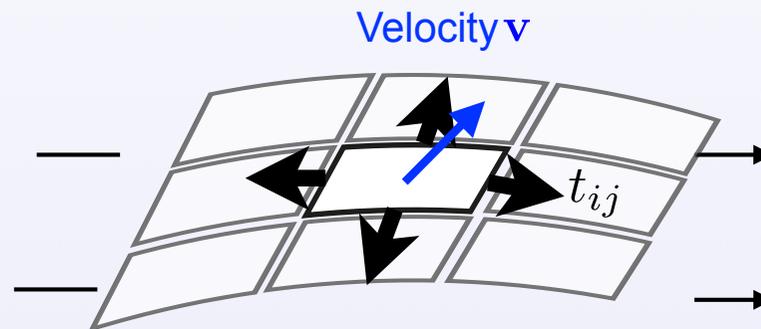
Macroscopic



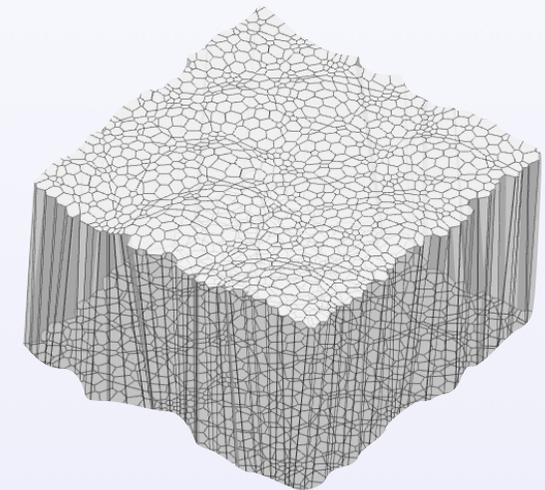
Motor,
cytoskeletal
filaments,



Cells

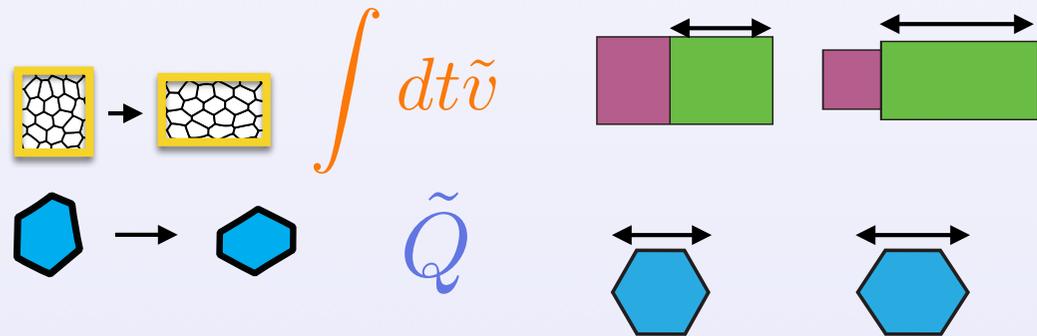
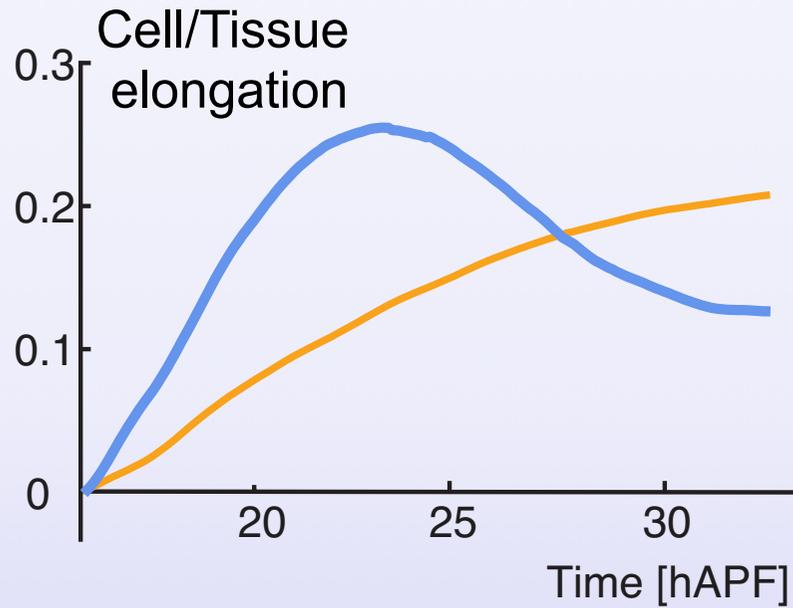
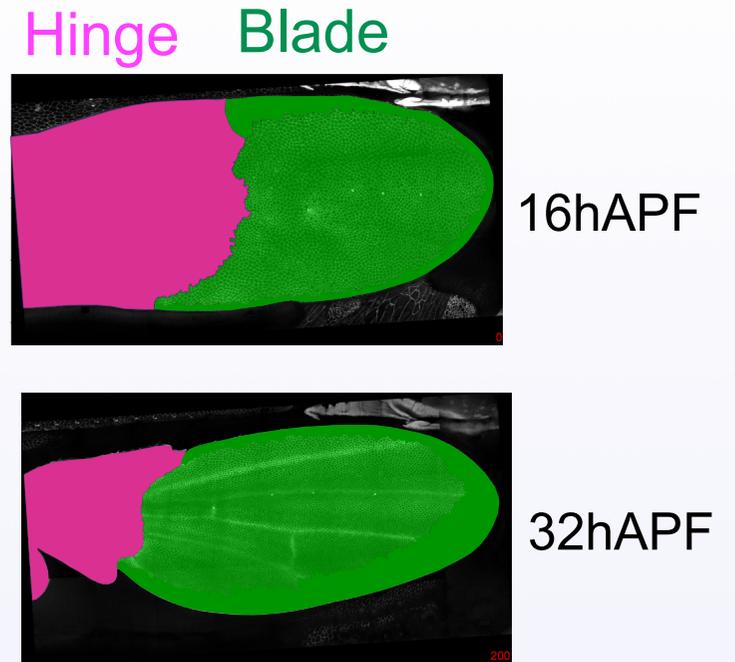


Continuum theory of
active matter

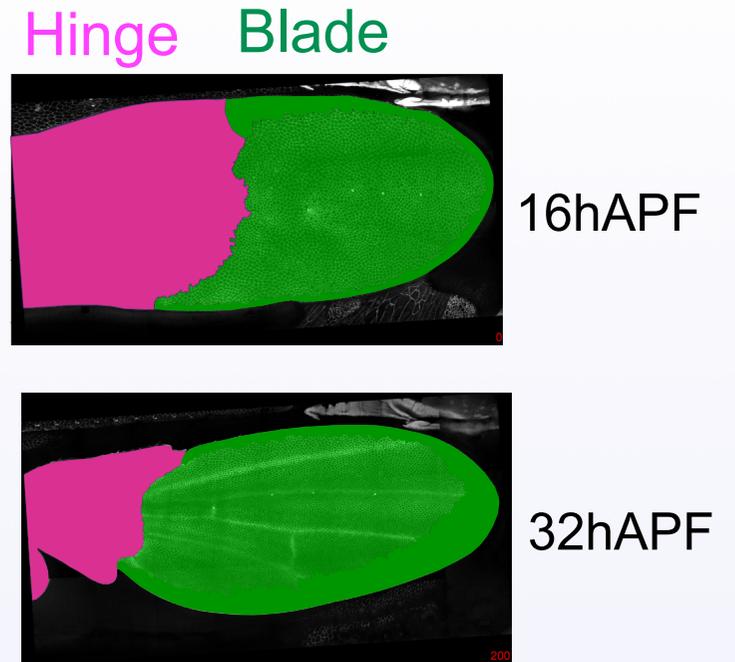


Biological
tissue

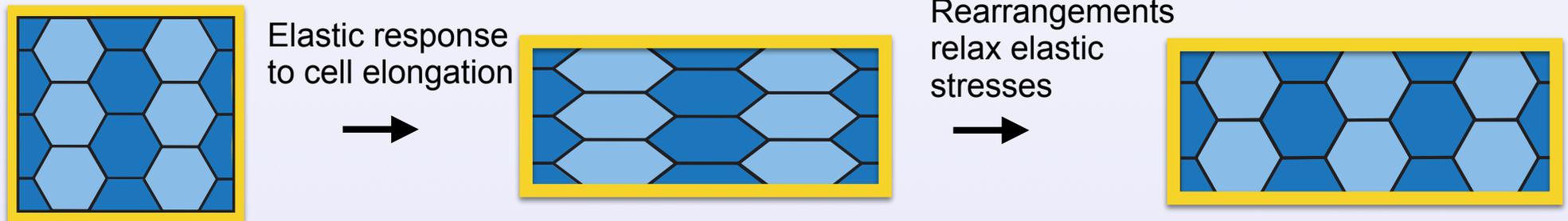
Tissue fluidity



Tissue fluidity



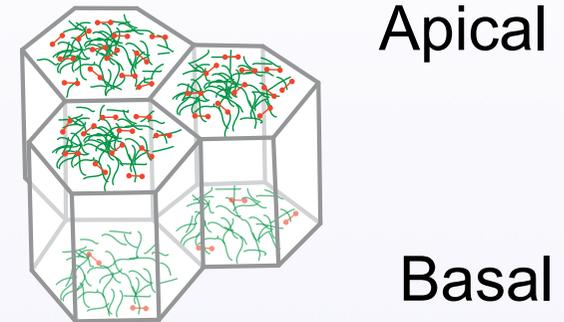
Cellular rearrangements ensure long-time scale tissue fluidity



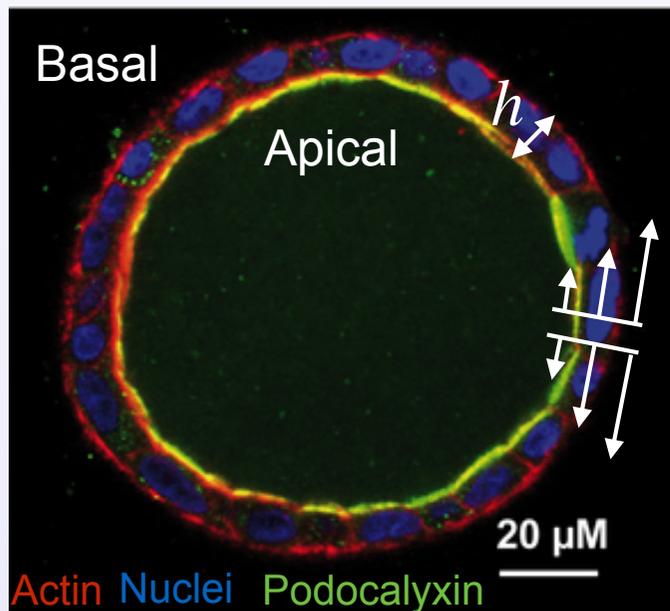
Tissue viscosity $\sim 10^4 - 10^5$ Pa.s

Epithelial tissues as thin shells

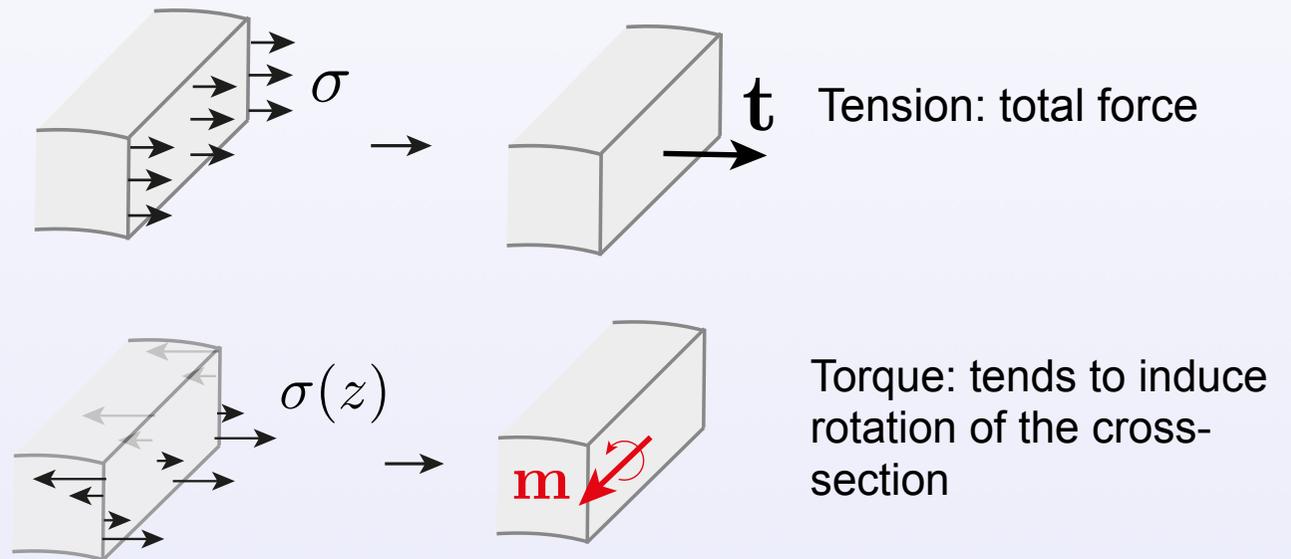
Describing epithelia as « active thin shells »:



MDCK cyst



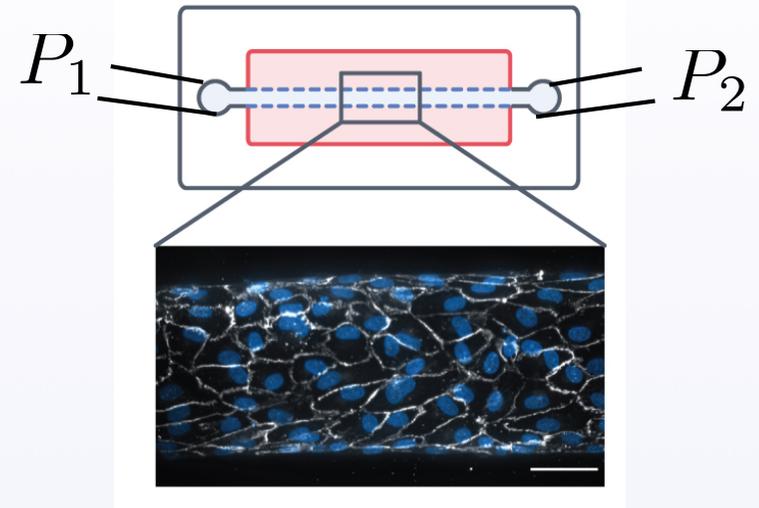
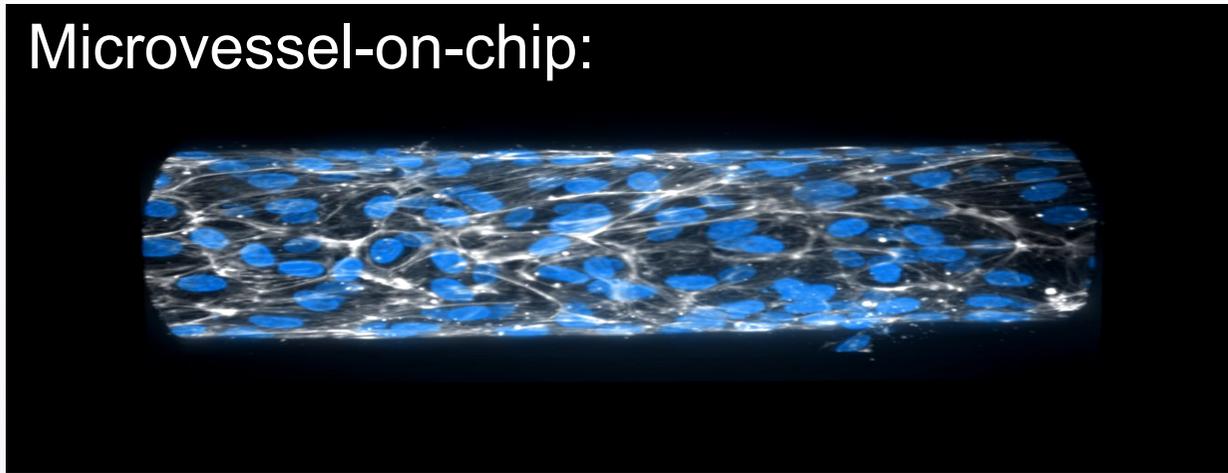
[Engelberg&al, PloS Comp Bio, 2011]



[Salbreux&al, PRE, 2017; Salbreux&al, PRR, 2022]

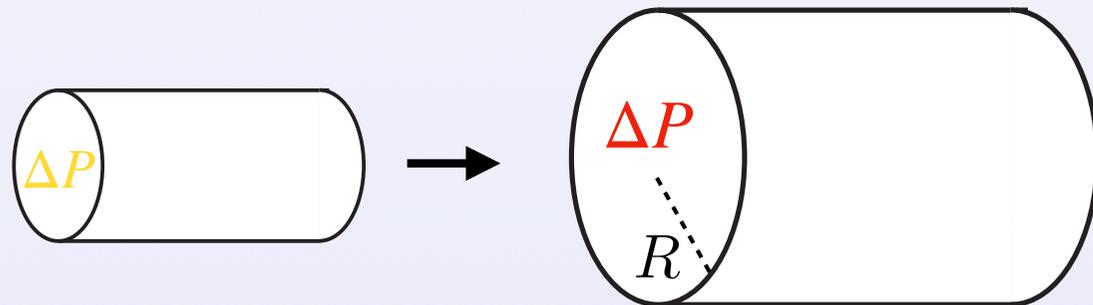
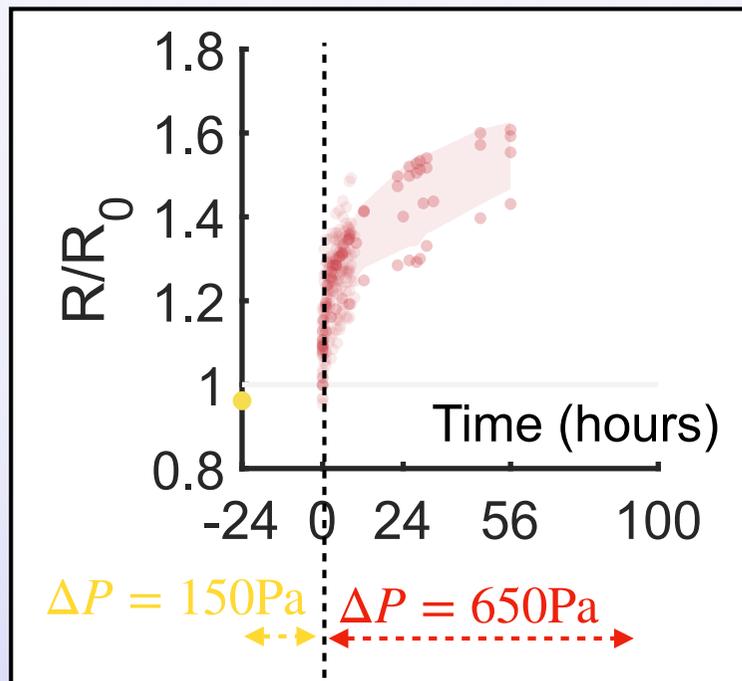
Tissues as nematic liquid crystals

Microvessel-on-chip:



[Dessalles & al, Biofabrication, 2022]

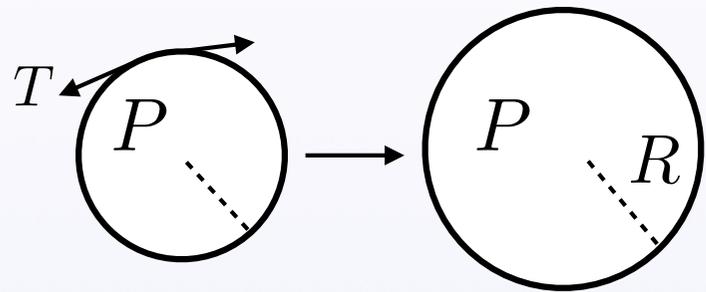
Pressure application leads to endothelial tube slow expansion:



[Dessalles, Cuny & al, Nature Physics, 2025]

How to resist the expansion of a tube?

Surface tension?

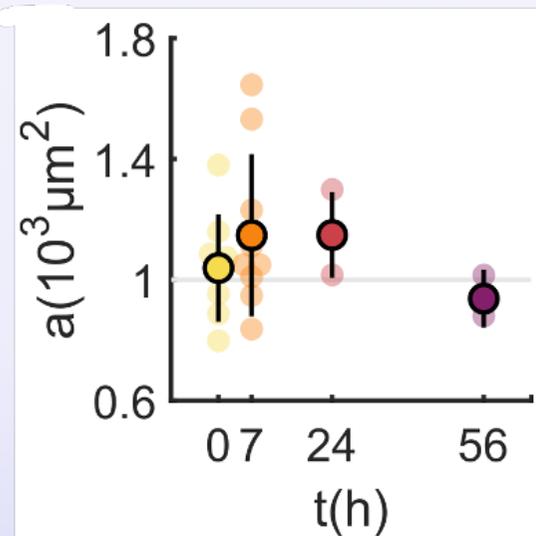
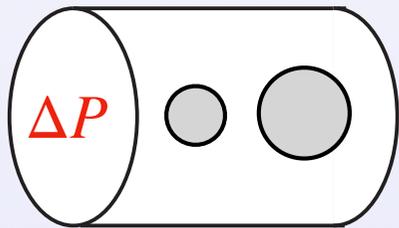


$$P = \frac{T}{R}$$

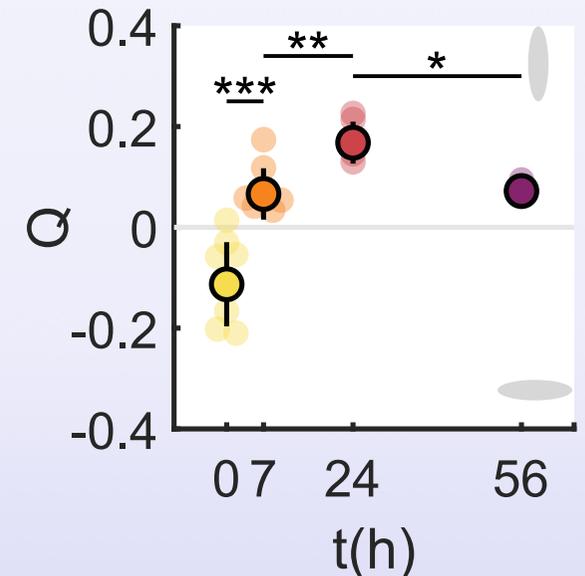
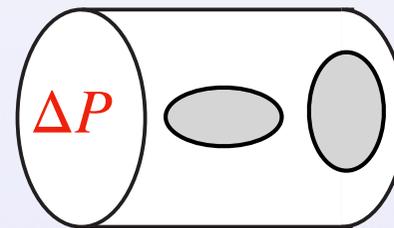
Unstable by the law of Laplace

Elastic stresses resulting from cell deformation?

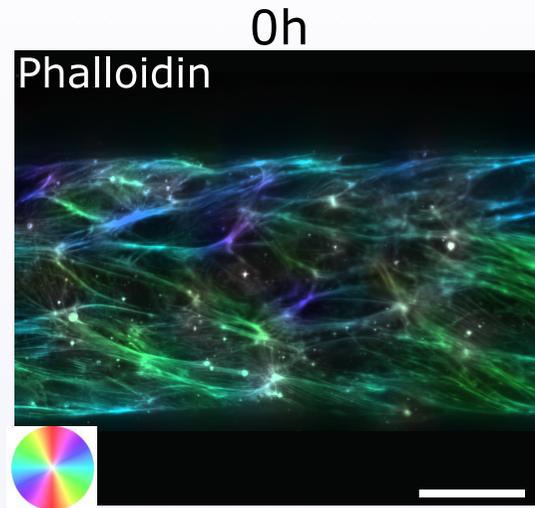
Cell area dynamics



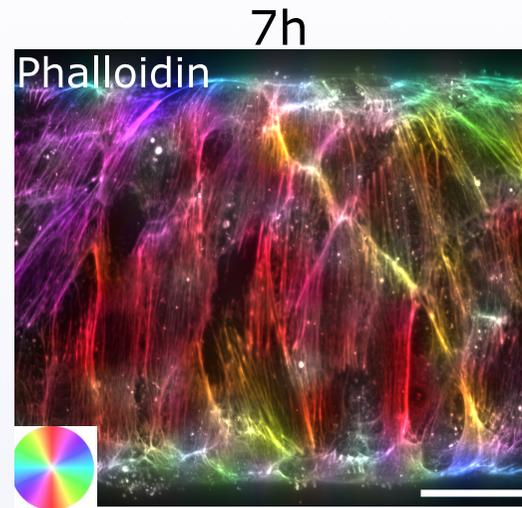
Cell elongation dynamics



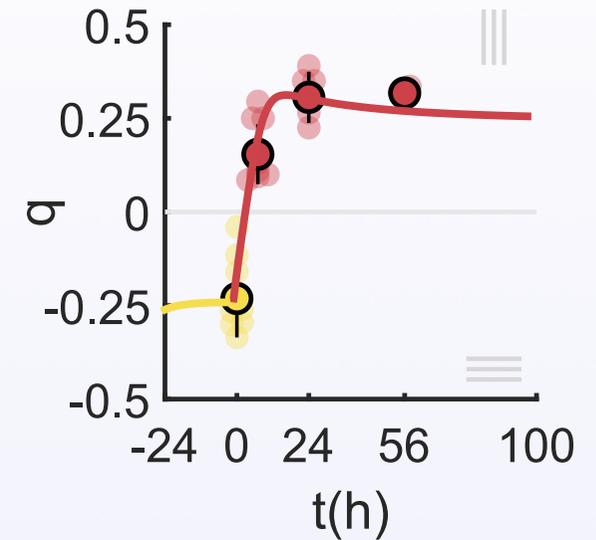
How to resist the expansion of a tube?



$\Delta P = 150Pa$



$\Delta P = 650Pa$

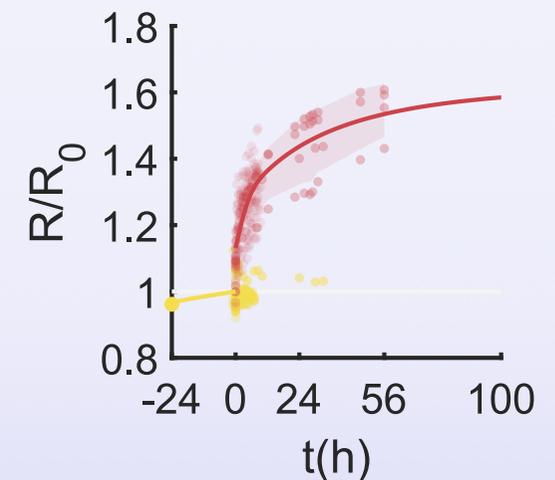
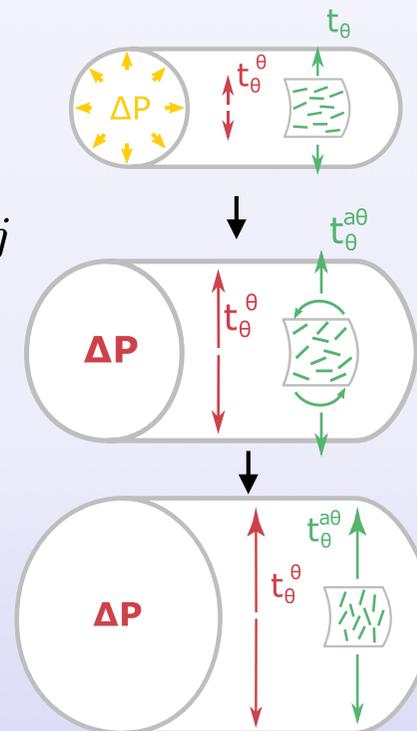


Nematodynamics:

$$D_t q_{ij} = -\frac{1}{\gamma} (q^2 - q_0^2) q_{ij} + \beta t_{ij}^r$$

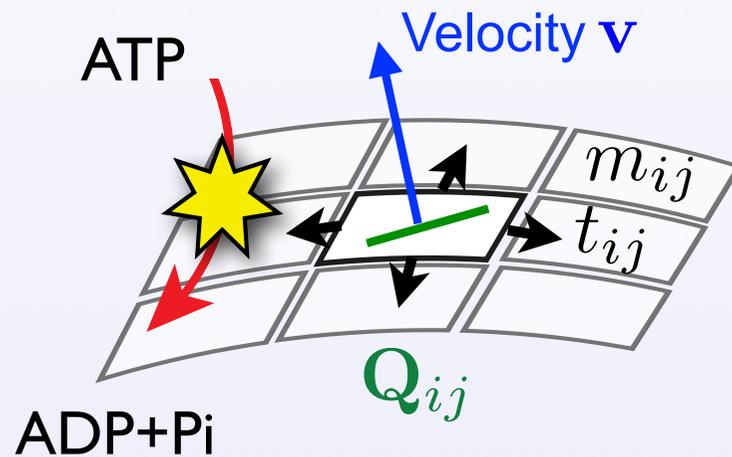
Tension oriented by nematic order:

$$t_{ij}^a \sim \zeta q^{ij}$$



Hydrodynamics of active nematic surfaces

Continuum, coarse-grained description of active surface:



Metric tensor g_{ij}

Curvature tensor C_{ij}

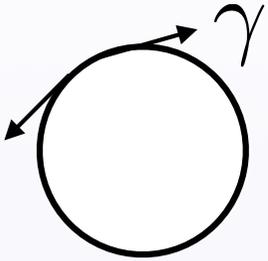
Velocity field \mathbf{v}

Nematic tensor \mathbf{Q}_{ij}

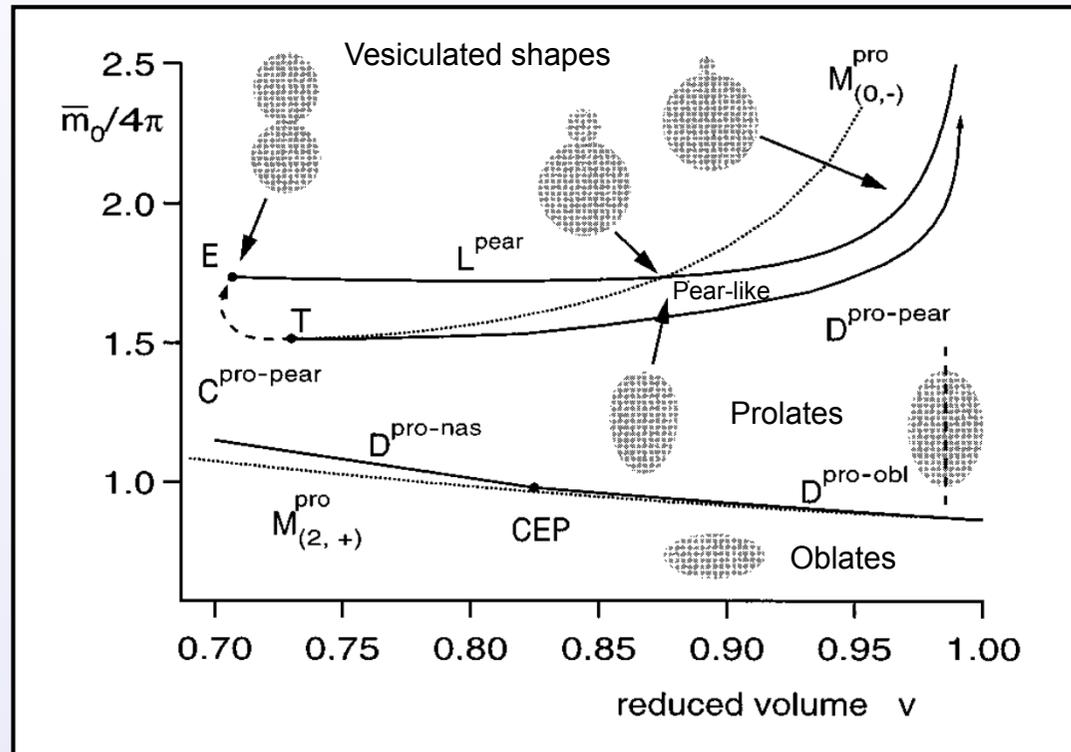
Tension tensor t_{ij}

Bending moment tensor m_{ij}

Helfrich theory for lipid membranes: a passive fluid surface



$$F = \int dS \left(\gamma + \frac{\kappa}{2} (C_k^k - C_0)^2 \right)$$



[Döbereiner & al, PRE, 1997]

Helfrich theory for lipid membranes: a passive fluid surface

$$F = \int dS \left(\gamma + \frac{\kappa}{2} (C_k^k - C_0)^2 \right)$$

Virtual work principle for a surface: $\delta W = \int dS \left[\bar{t}^{ij} \frac{\delta g_{ij}}{2} + \bar{m}^i_j \delta C_i^j \right]$

Tensions and bending moment arising in a Helfrich membrane:

$$\bar{t}_e^{ij} = 2 \frac{\delta F}{\delta g_{ij}} \sim \gamma g_{ij} \quad \bar{m}_e^{ij} = \frac{\delta F}{\delta C_{ij}} = \kappa (C_k^k - C_0) g_{ij}$$

Linear non-equilibrium thermodynamics

Rate of free energy change = -Entropy production:

$$\frac{dF}{dt} = - \sum_i f_i \frac{d\phi_i}{dt}$$

Postulate linear phenomenological relation between **fluxes** and **forces**:

$$\frac{d\phi_i}{dt} = \sum_j L_{ij} f_j$$

L_{ij}
phenomenological coefficients

Thermodynamic fields ϕ_i and forces $f_i = -\frac{\delta F}{\delta \phi_i}$

[De Groot&Mazur, Non equilibrium thermodynamics, 2013]

Rate of free energy change for an active nematic surface:

$$\frac{dF}{dt} = - \int dS \left[(t^{ij} - t_e^{ij}) v_{ij} + (\bar{m}^{ij} - \bar{m}_e^{ij}) D_t C_{ij} + D_t Q_{ij} H^{ij} + r \Delta \mu \right]$$

Conjugate pairs of **fluxes** and **forces**:

Tension tensor
(non-equilibrium part)

$$\bar{t}^{ij} - \bar{t}_e^{ij}$$

Surface shear

$$v_{ij} \sim D_t g_{ij}$$

Bending moment tensor
(non-equilibrium part)

$$\bar{m}^{ij} - \bar{m}_e^{ij}$$

Rate of change of
curvature tensor

$$D_t C_{ij}$$

Nematodynamics
(Corotational time
derivative)

$$D_t Q_{ij}$$

Molecular field

$$H^{ij} = \frac{\delta F}{\delta Q_{ij}}$$

Rate of ATP consumption

$$r$$

Chemical potential
of ATP hydrolysis

$$\Delta \mu$$

Linear non-equilibrium thermodynamics

Rate of free energy change = -Entropy production:

$$\frac{dF}{dt} = - \sum_i f_i \frac{d\phi_i}{dt}$$

Postulate linear phenomenological relation between **fluxes** and **forces**:

$$\frac{d\phi_i}{dt} = \sum_j L_{ij} f_j$$

L_{ij} phenomenological coefficients

Constitutive equations obtained from linear phenomenological relations:

$$\begin{matrix} \bar{t}^{ij} \\ \bar{m}^{ij} \end{matrix} = \begin{matrix} \bar{t}_e^{ij} \\ \bar{m}_e^{ij} \end{matrix} + \begin{matrix} \sim g_{ij}, \sim Q_{ij} \end{matrix} + \begin{matrix} \sim v_{ij}, \sim \frac{DC_{ij}}{Dt} \end{matrix}$$

Helfrich passive terms

Active terms driven by non-equilibrium chemical reactions

Viscous dissipative terms

Active nematic surface theory for tissues

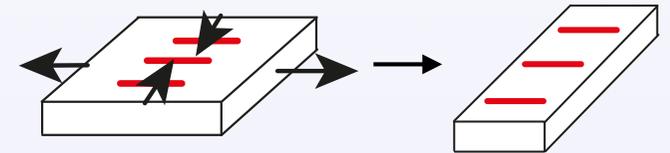
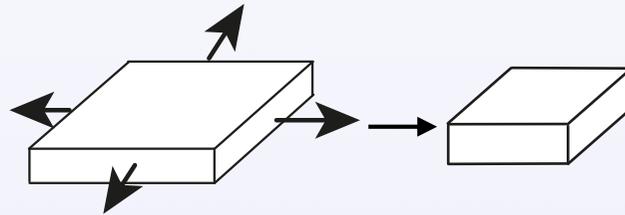
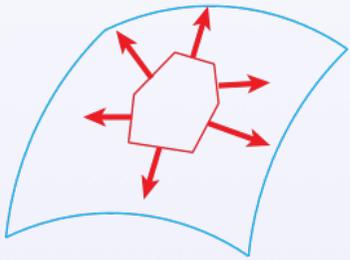
Tension $t_{ij} = \underline{2Kug_{ij}} + \underline{\zeta g_{ij}} + \underline{\zeta_n Q_{ij}} + \eta v_{ij}$

Bending moment $\bar{m}_{ij} = \underline{\kappa C_{ij}} + \underline{\zeta_c g_{ij}} + \underline{\zeta_{cn} Q_{ij}} + \eta_c D_t C_{ij}$

Area elasticity:

Isotropic tension:

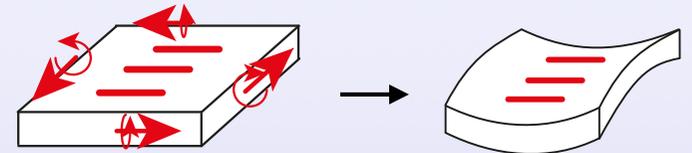
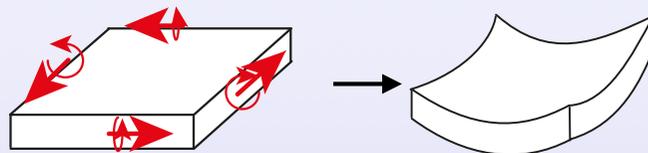
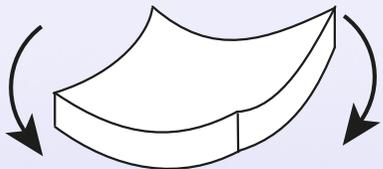
Nematic tension:



Bending rigidity:

Isotropic bending moment:

Nematic bending moment:

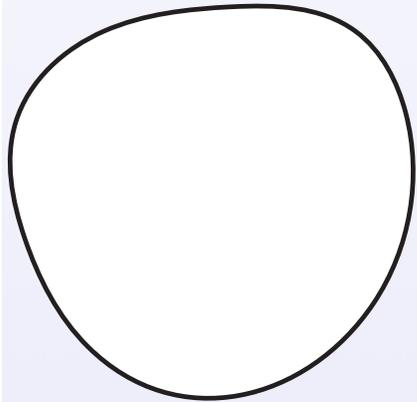


Active nematic surface theory for tissues

Tension $t_{ij} = 2Kug_{ij} + \zeta g_{ij} + \zeta_n Q_{ij} + \eta v_{ij}$

Bending moment $\bar{m}_{ij} = \kappa C_{ij} + \zeta_c g_{ij} + \zeta_{cn} Q_{ij} + \eta_c D_t C_{ij}$

Shape at time t



Force balance:

$$\nabla_i t^{ij} + C_i^j t_n^i = 0$$

$$\nabla_i t_n^i - C_{ij} t^{ij} = 0$$

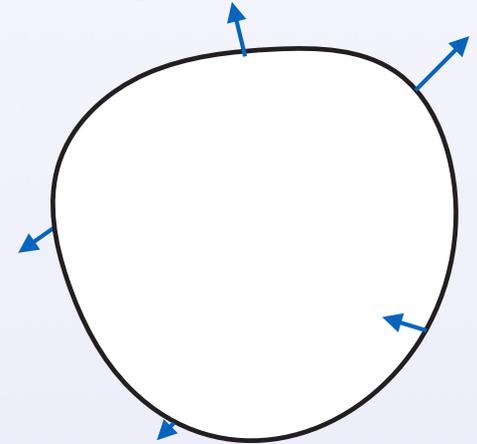
Torque balance:

$$t_n^i = \nabla_i \bar{m}^{ij}$$

Solve for flow field:

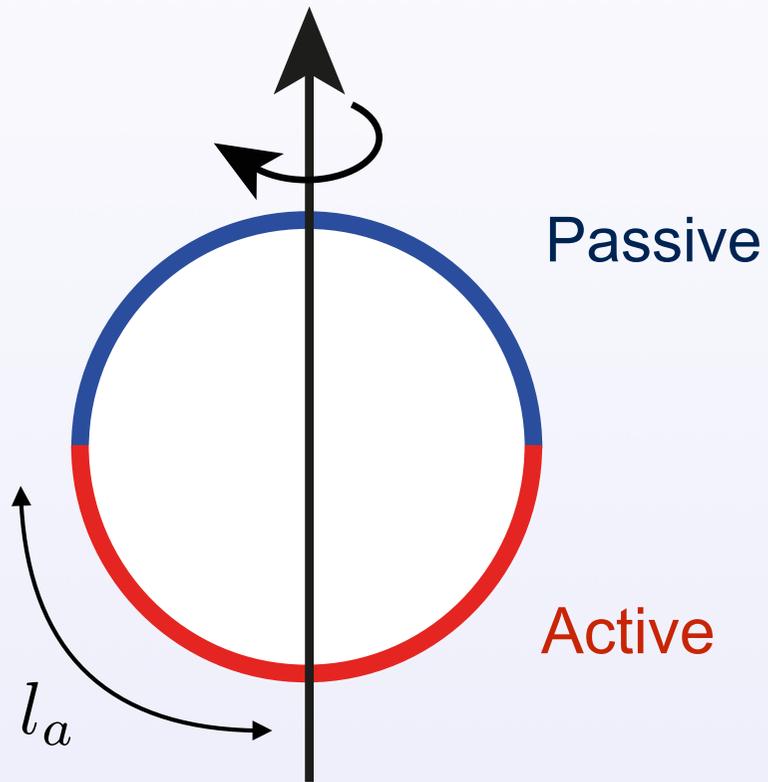


Update shape
according to velocity
field:

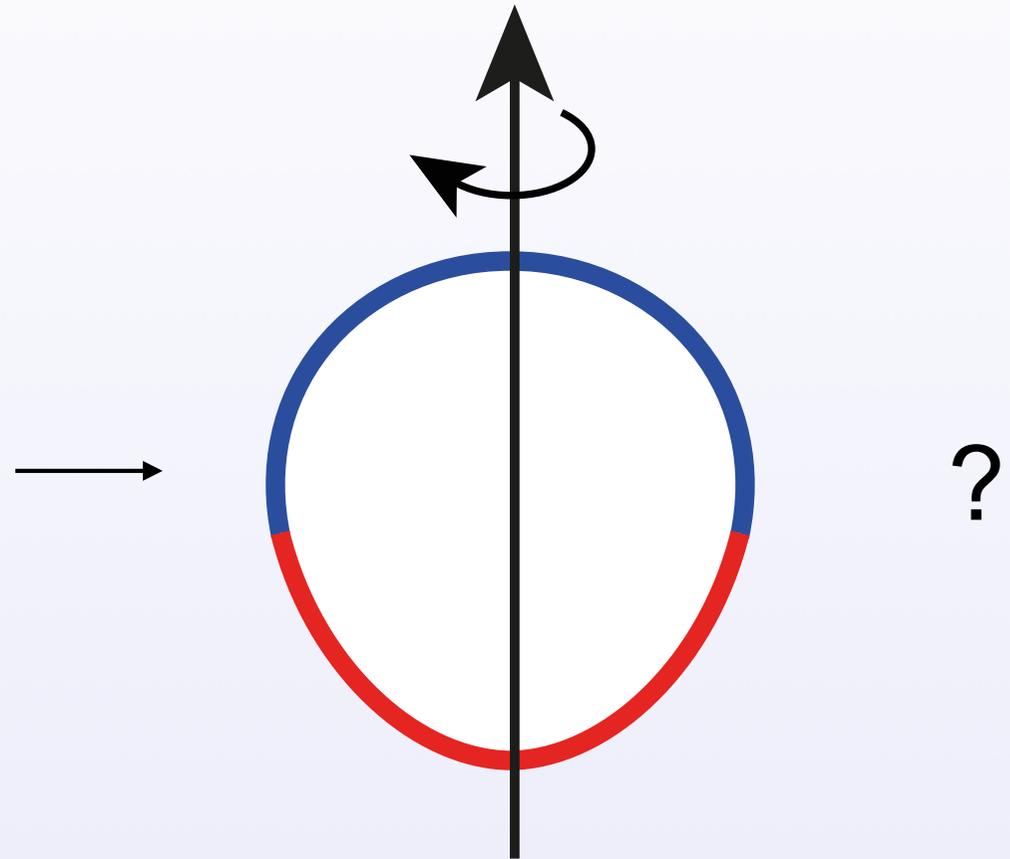


Deformations of mechanically patterned spherical surfaces

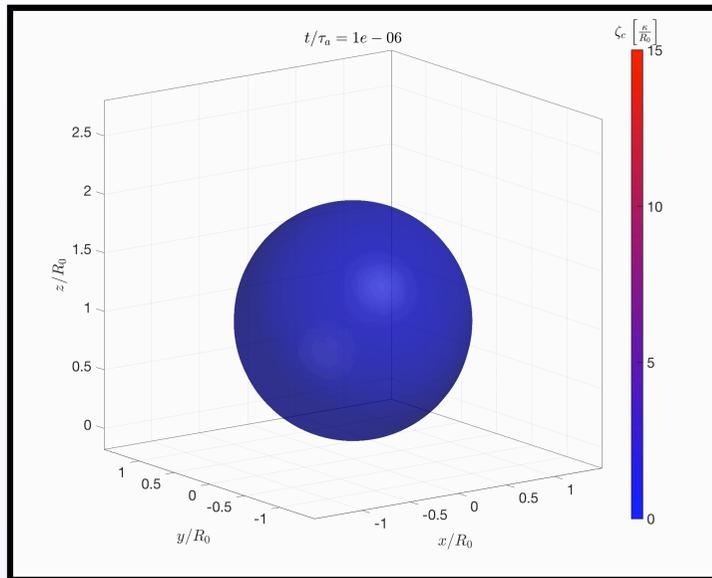
Active and passive domains:



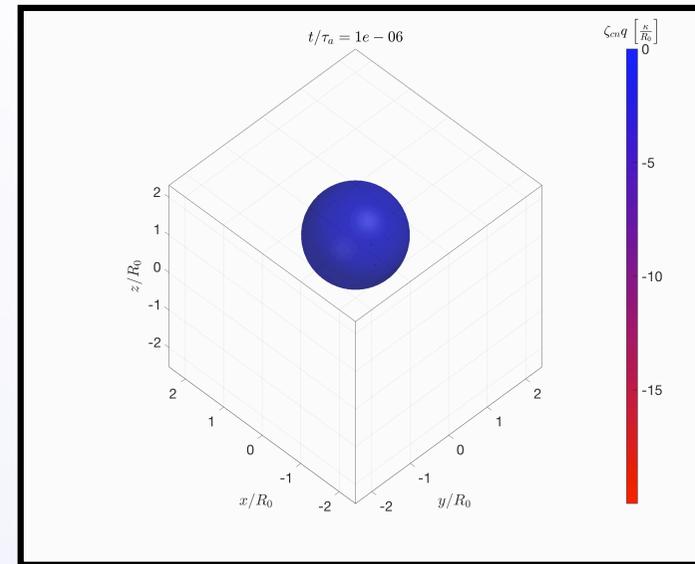
Shape changes?



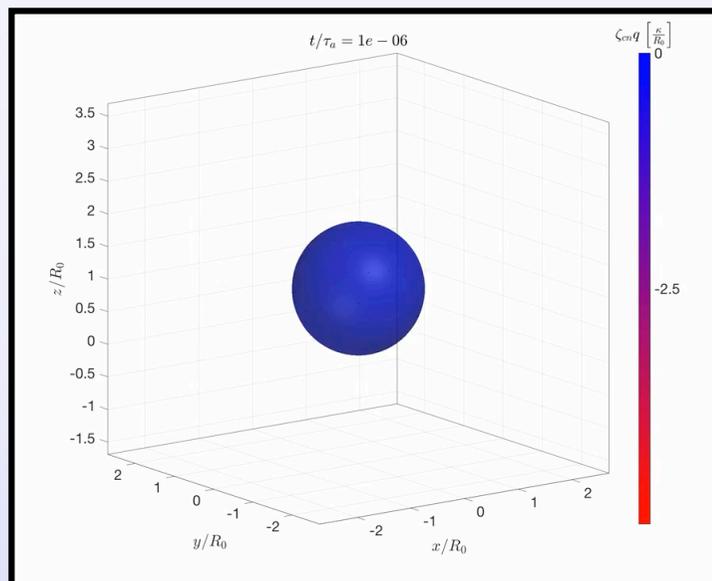
Exploring shape changes of active surfaces



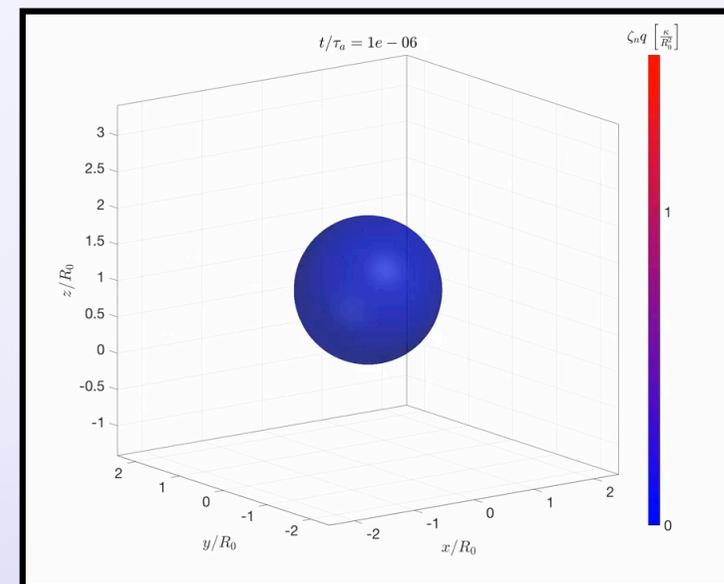
$$l_a/L_0 = 0.85 \quad \frac{\zeta_c R_0}{\kappa} = 15$$



$$l_a/L_0 = 0.3 \quad \frac{\zeta_{cn} R_0}{\kappa} = -20$$



$$l_a/L_0 = 1 \quad \zeta_{cn} R_0/\kappa = -5$$

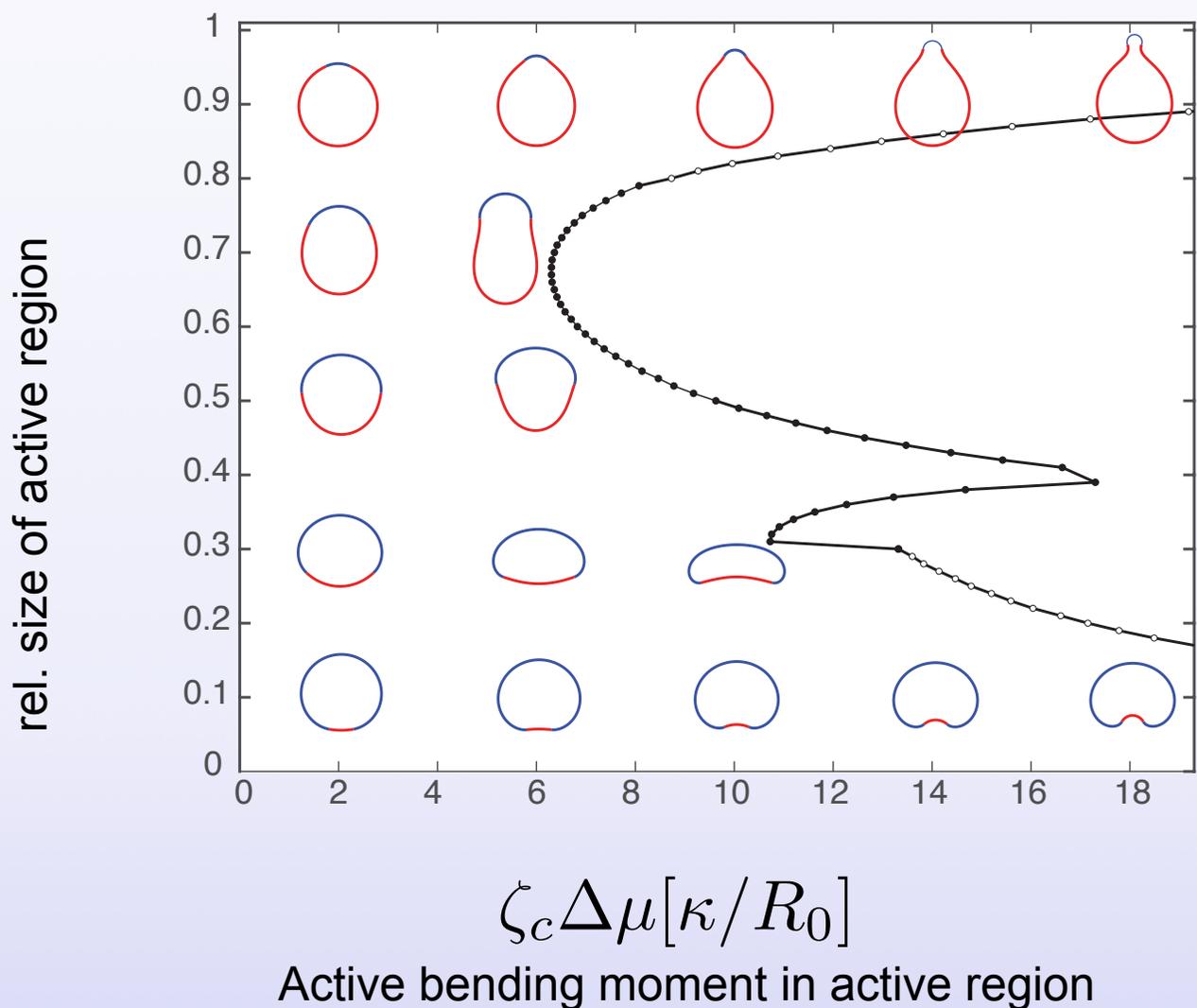


$$l_a/L_0 = 1 \quad \zeta_n R_0^2/\kappa = 1.5$$

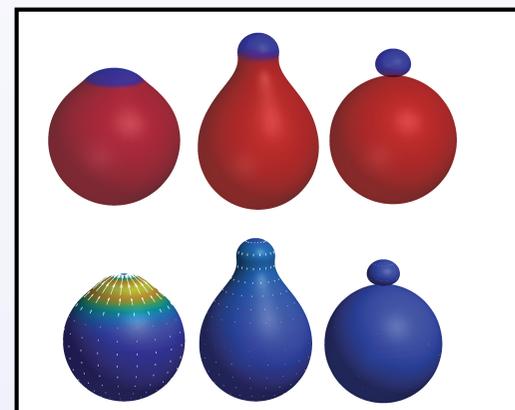
Epithelial shells with isotropic active bending moment

Tension $t_{ij} = 2Kug_{ij} + \zeta g_{ij} + \zeta_n Q_{ij}$

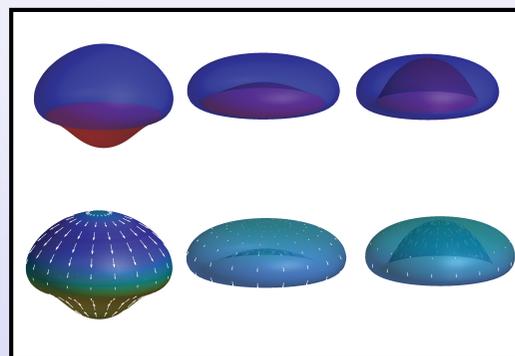
Bending moment $\bar{m}_{ij} = \kappa C_{ij} + \zeta_c g_{ij} + \zeta_{cn} Q_{ij}$



Neck constriction:



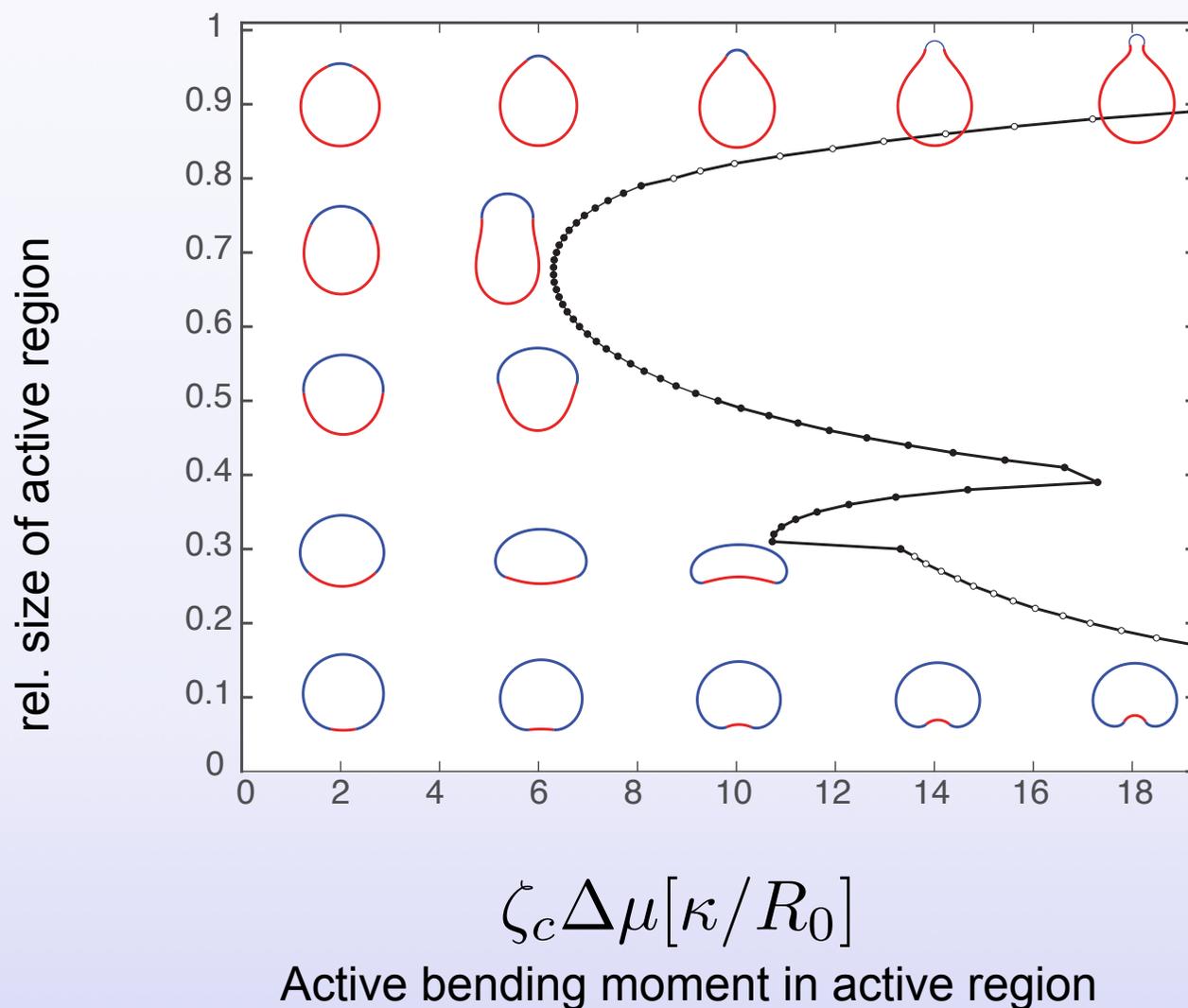
Instability followed by self-intersecting shape:



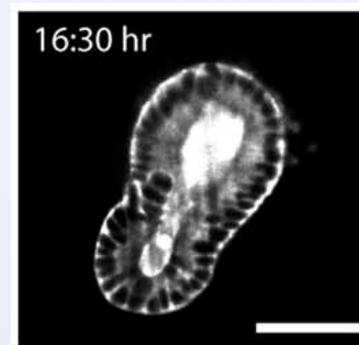
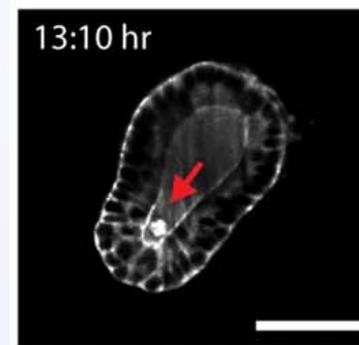
Epithelial shells with isotropic active bending moment

Tension $t_{ij} = 2Kug_{ij} + \zeta g_{ij} + \zeta_n Q_{ij}$

Bending moment $\bar{m}_{ij} = \kappa C_{ij} + \boxed{\zeta_c g_{ij}} + \zeta_{cn} Q_{ij}$



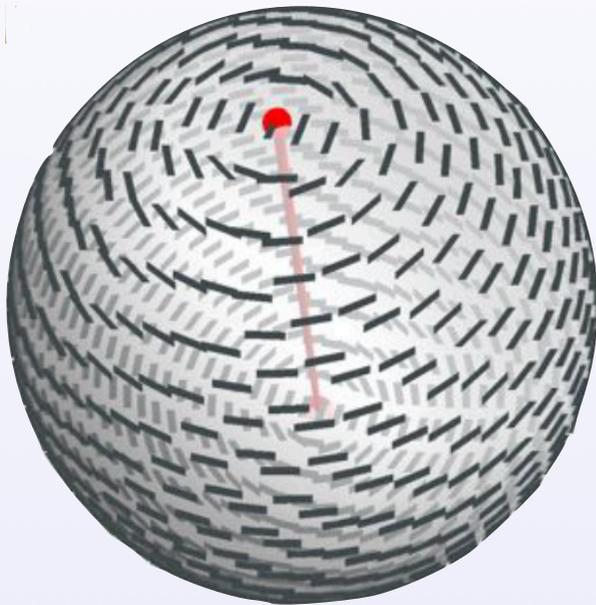
Intestinal organoids:



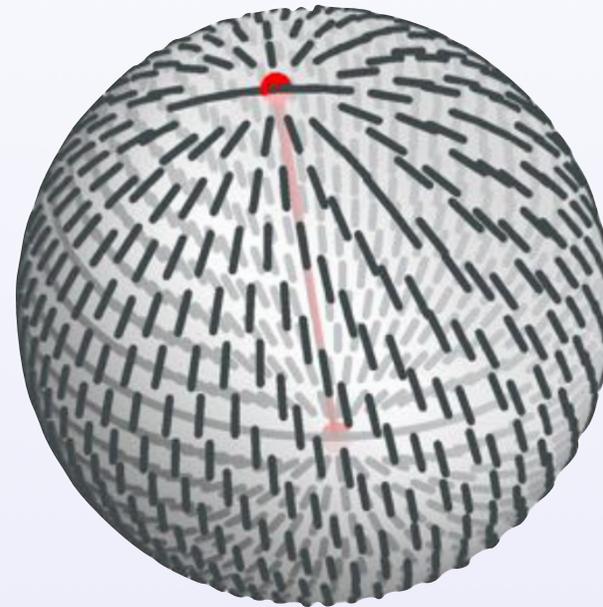
[Yang & al, NCB, 2021]

Deformations of mechanically patterned spherical surfaces

Nematic order:
$$F = \int dS \left[\nabla_i Q_{jk} \nabla^i Q^{jk} - \frac{a}{4} \mathbf{Q}^2 + \frac{a}{16} \mathbf{Q}^4 \right]$$



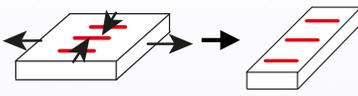
Equatorial



Meridional

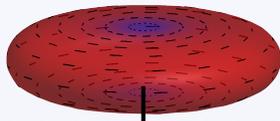
Epithelial shells with nematic active tension

Tension $t_{ij} = 2Kug_{ij} + \zeta g_{ij} + \zeta_n Q_{ij}$

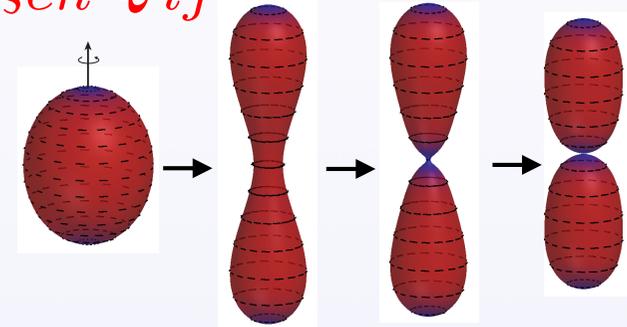


Bending moment $\bar{m}_{ij} = \kappa C_{ij} + \zeta_c g_{ij} + \zeta_{cn} Q_{ij}$

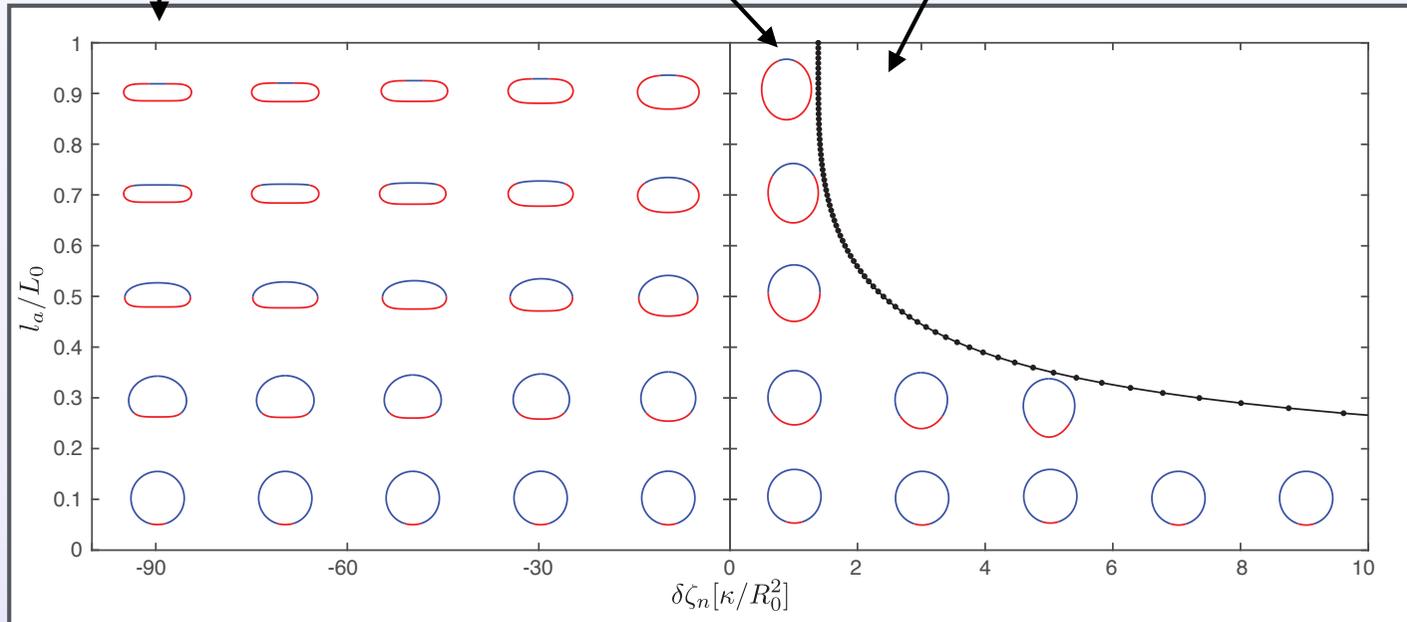
Oblate spheroid



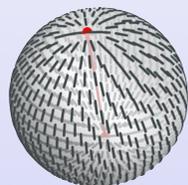
Prolate spheroid



rel. size of active region

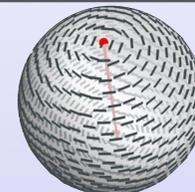


Active nematic tension in active region



Meridional

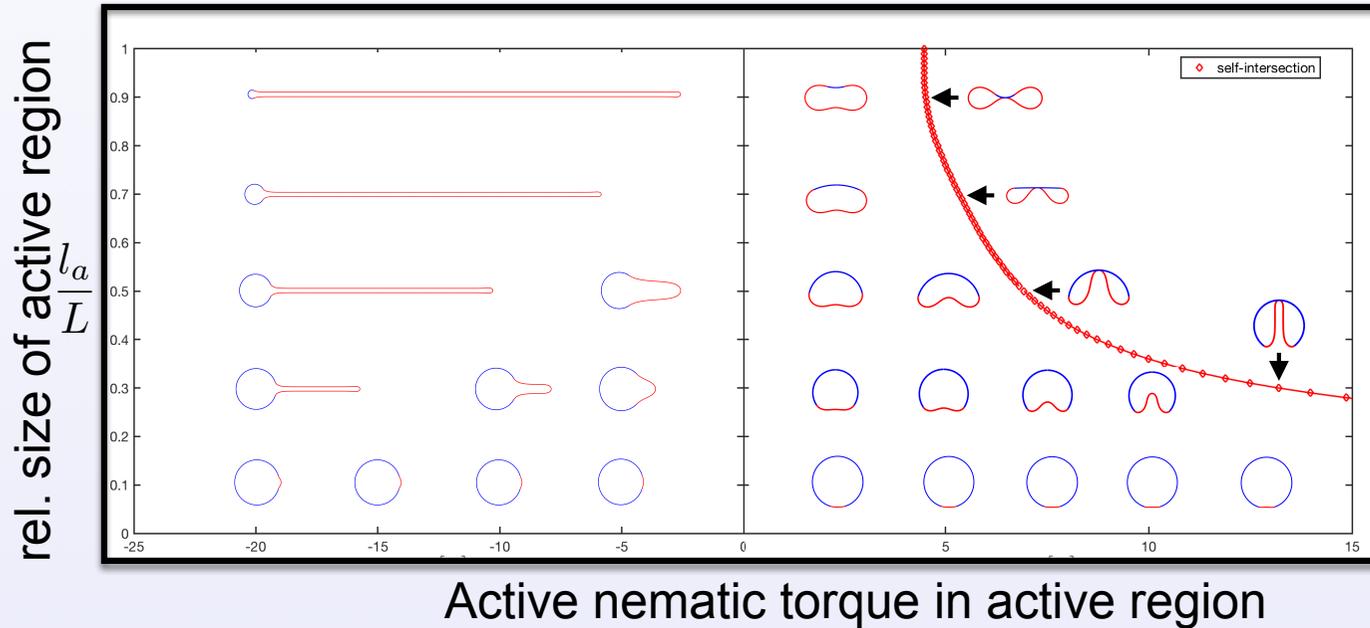
Equatorial



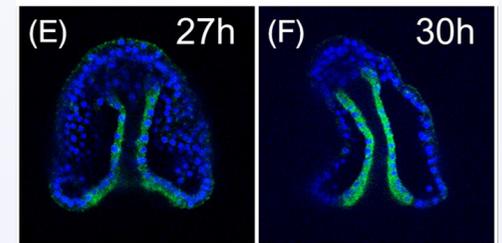
Nematic active bending moment: tubulogenesis

Tension $t_{ij} = 2Kug_{ij} + \zeta g_{ij} + \zeta_n Q_{ij}$

Bending moment $\bar{m}_{ij} = \kappa C_{ij} + \zeta_c g_{ij} + \zeta_{cn} Q_{ij}$

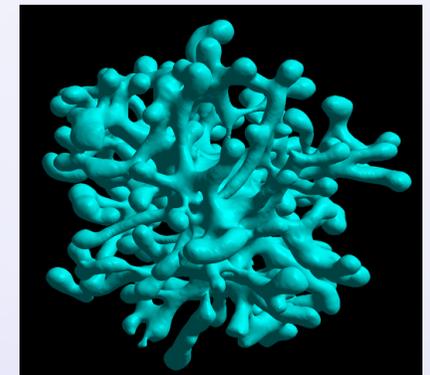


Sea urchin gastrulation:

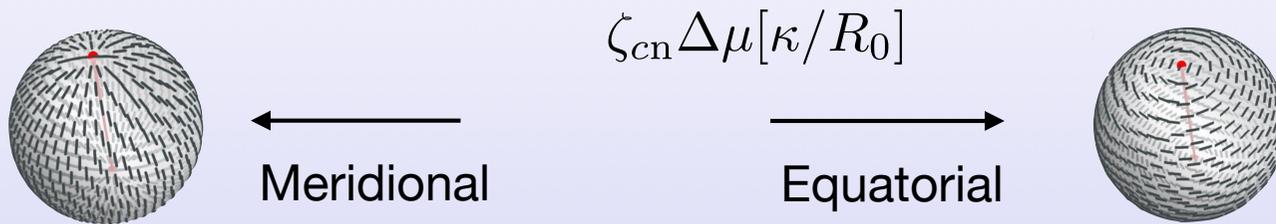


[Kamata & al. 2023]

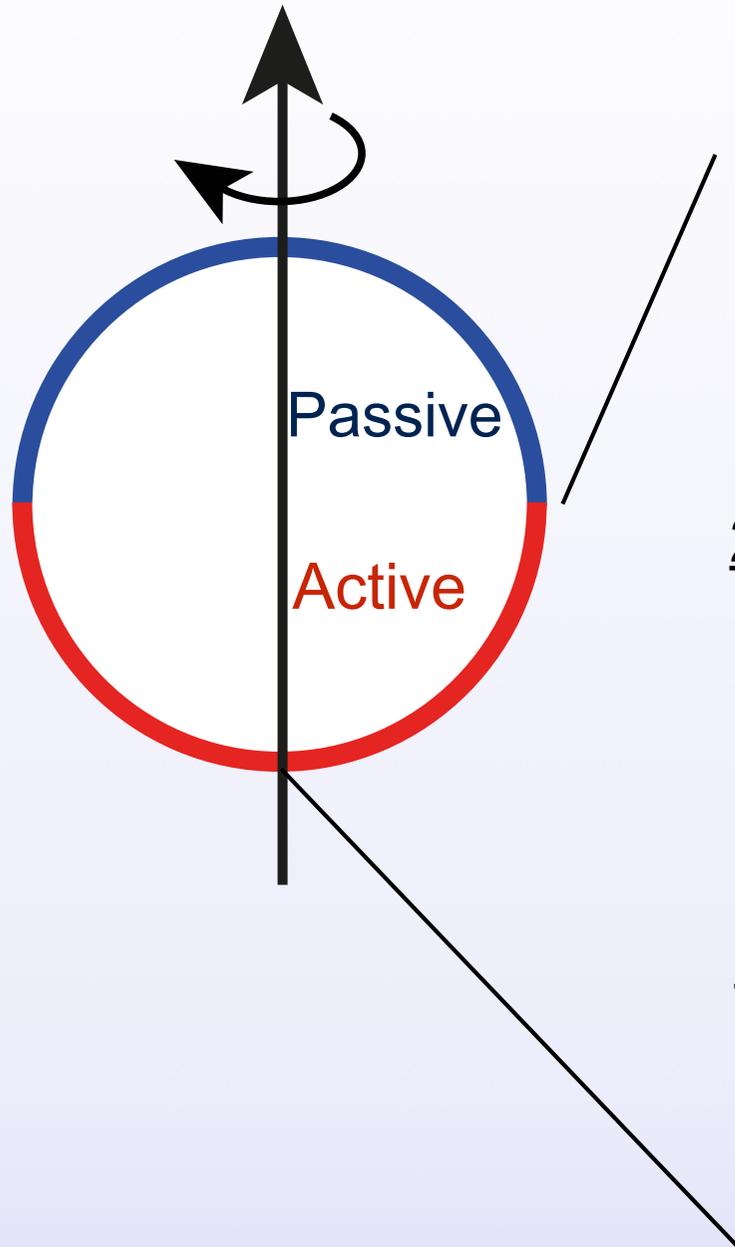
Mammary gland organoid:



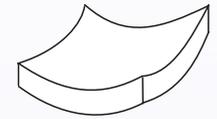
[R. Rollin, B. Canales, A. Elosegui]



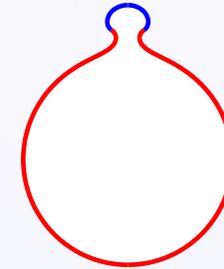
Patterned active surface shape zoology:



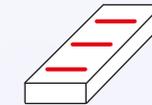
1. Isotropic active bending moment



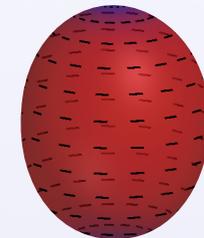
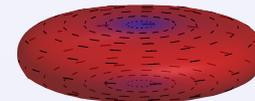
Budding



2. Nematic active tension



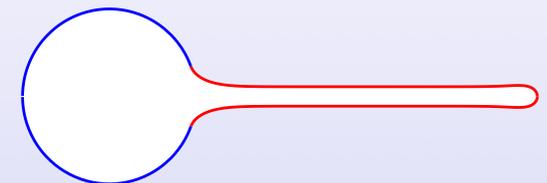
Prolate/oblate spheroids



3. Nematic active bending moment



Cylindrical tubes



Active surfaces and cnidarian larval shape diversity

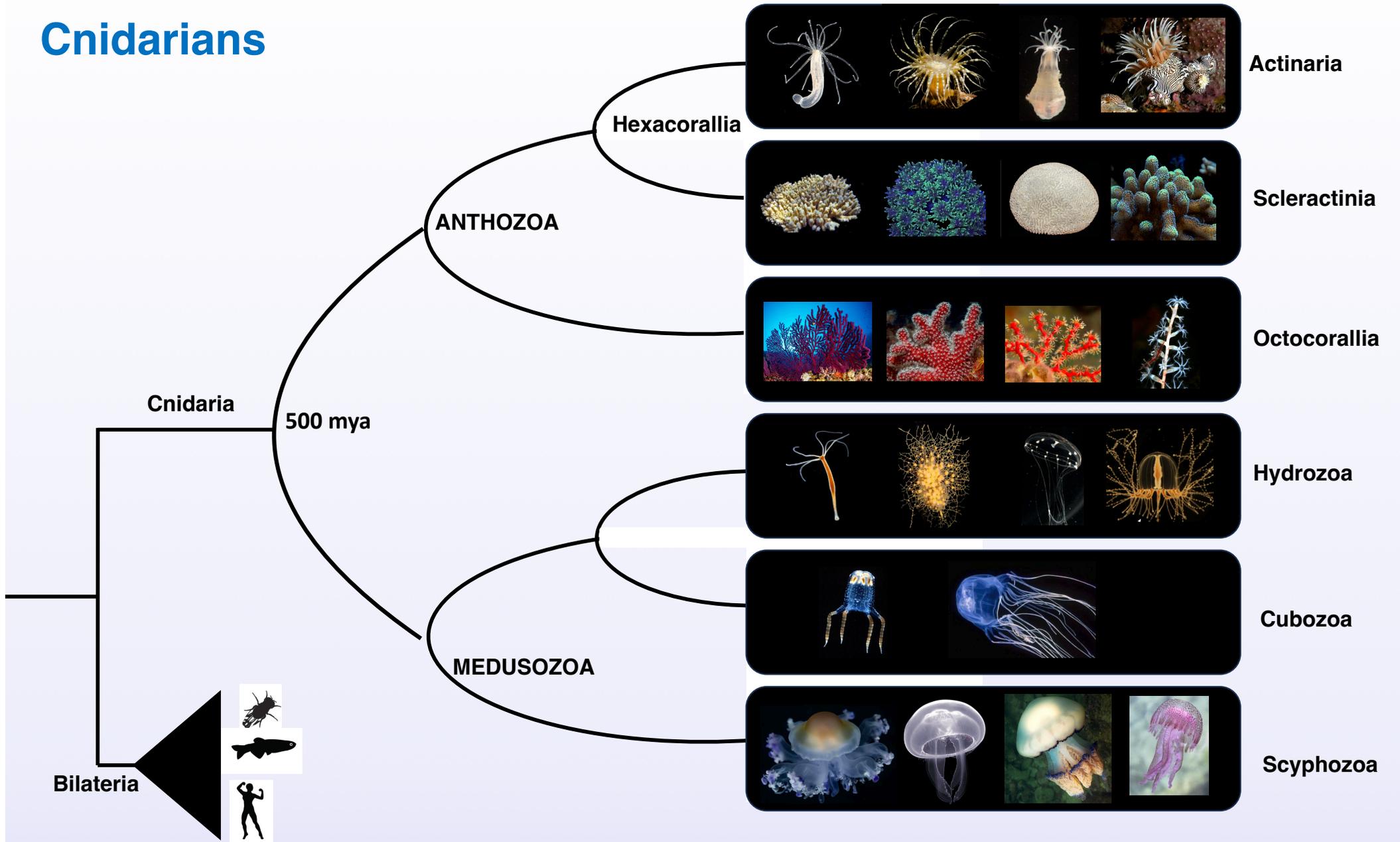
Theory: Nicolas Cuny, Diana Khoromskaia

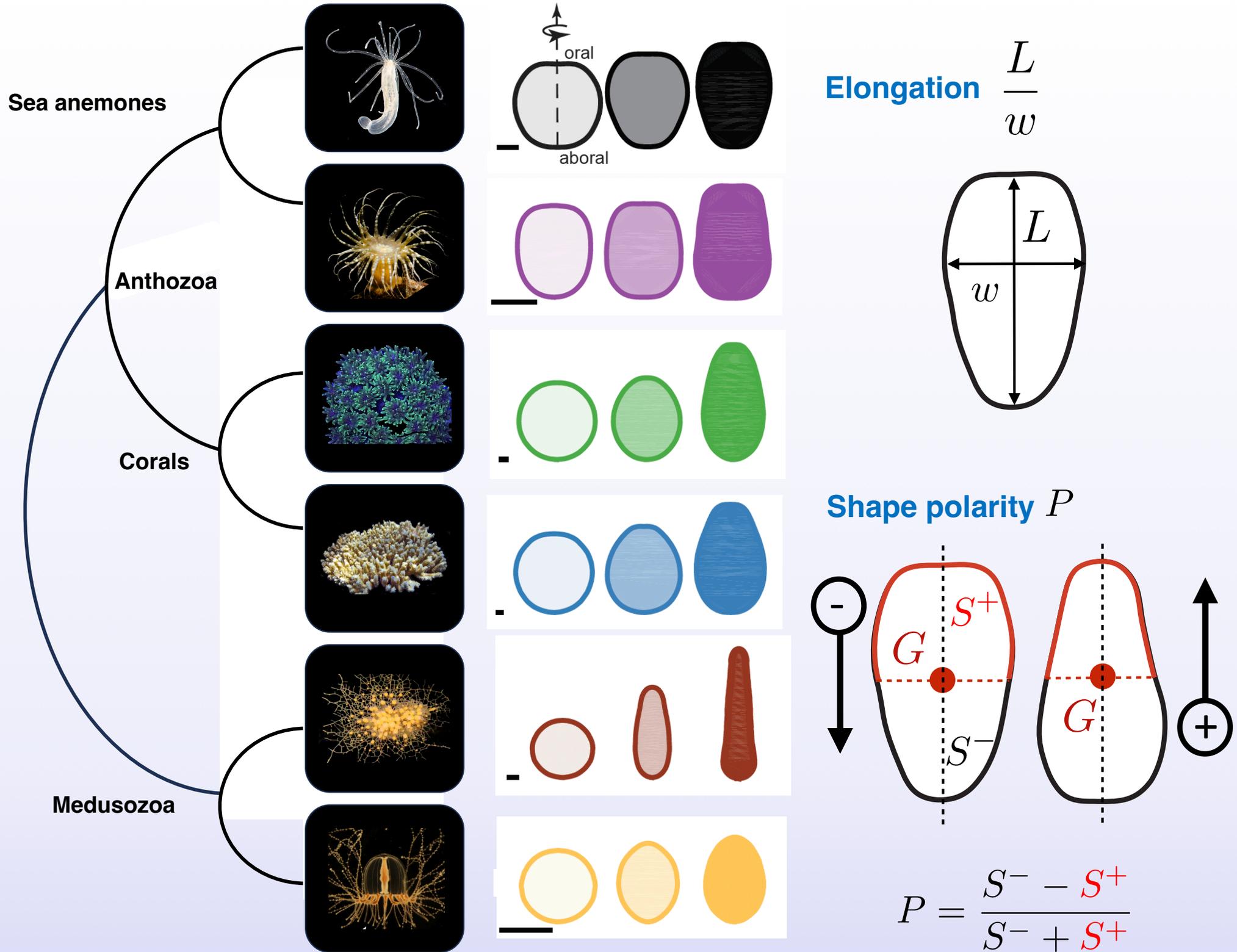


Experiments: Richard Bailleul, Aissam Ikmi

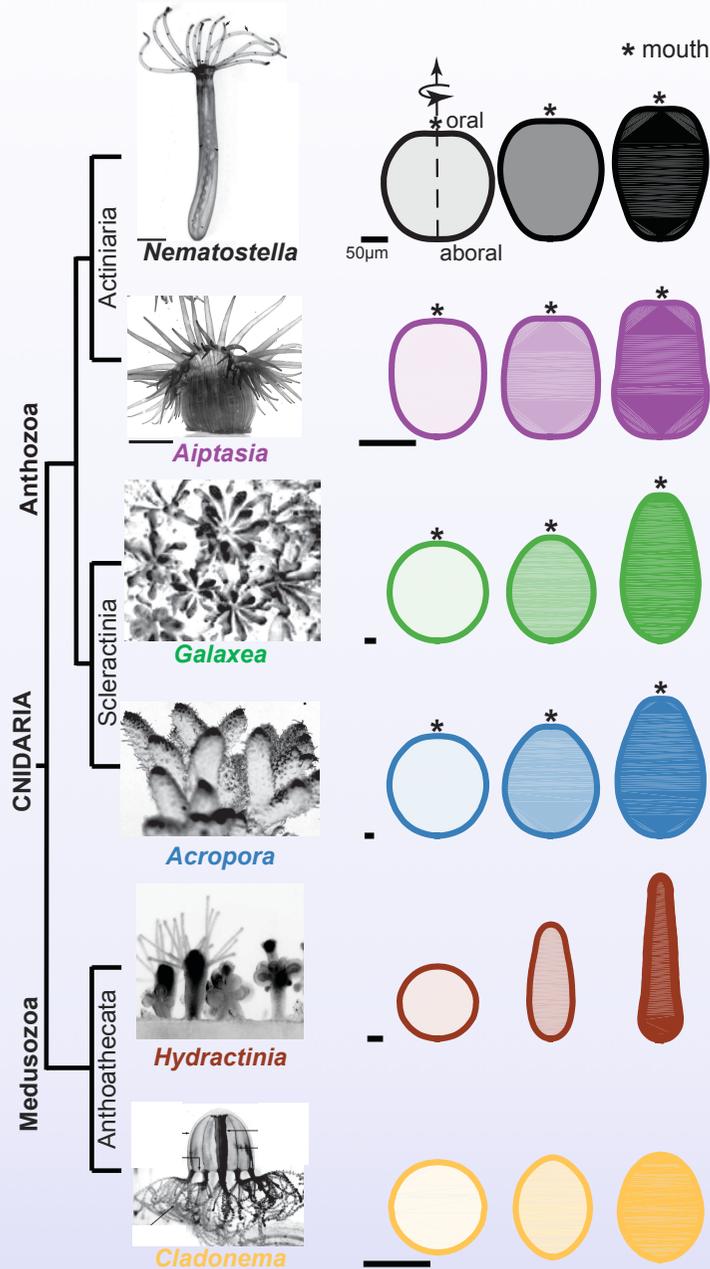


Cnidarians

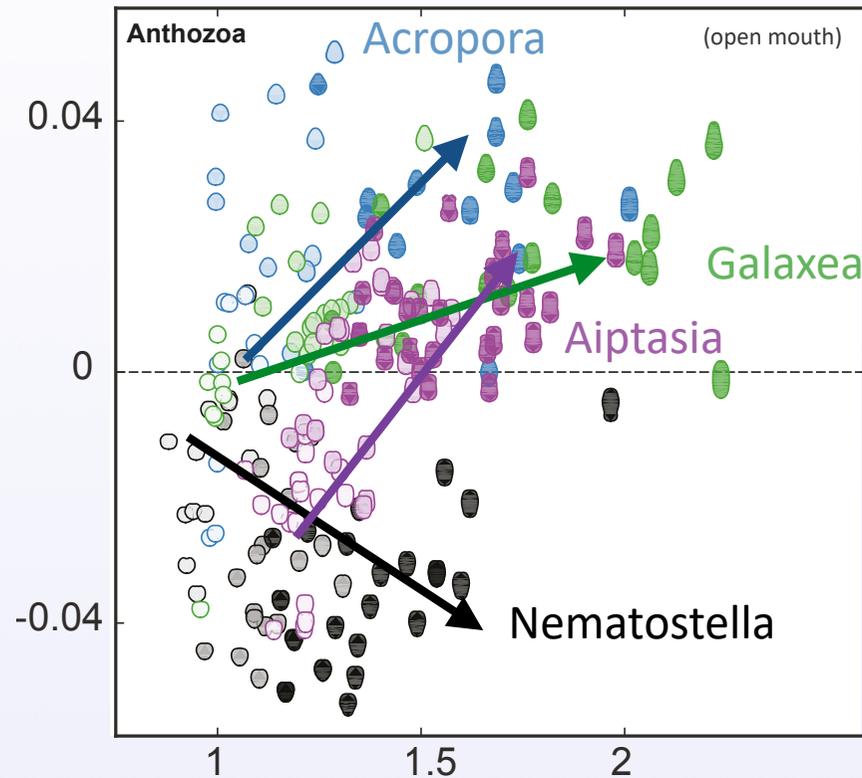




The cnidarian larvae morphospace

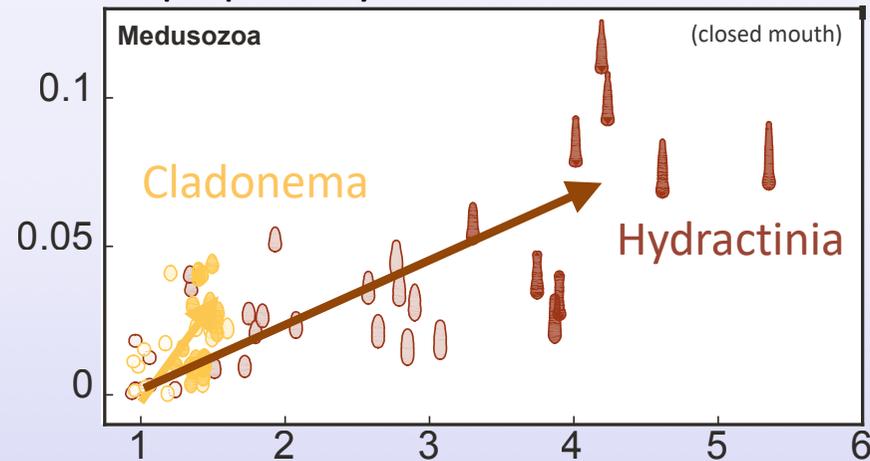


Shape polarity



Elongation

Shape polarity norm



Elongation

Nematic order in cnidarian larvae

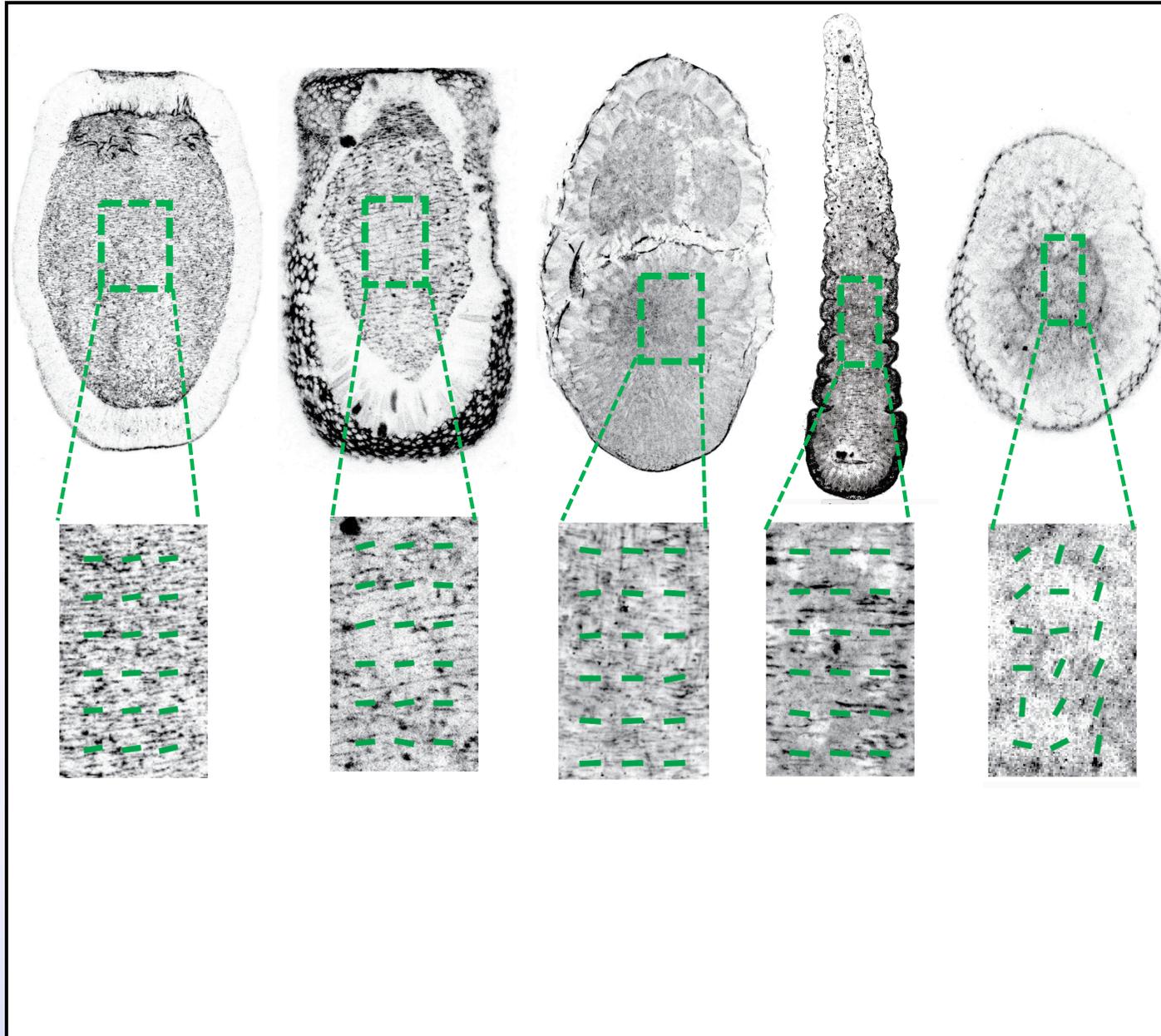
Nematostella

Aiptasia

Galaxea

Hydractinia

Cladonema



- Uniform circumferential order of stress fibres on the basal surface of the endoderm/ectoderm

Comparing cnidarian larvae

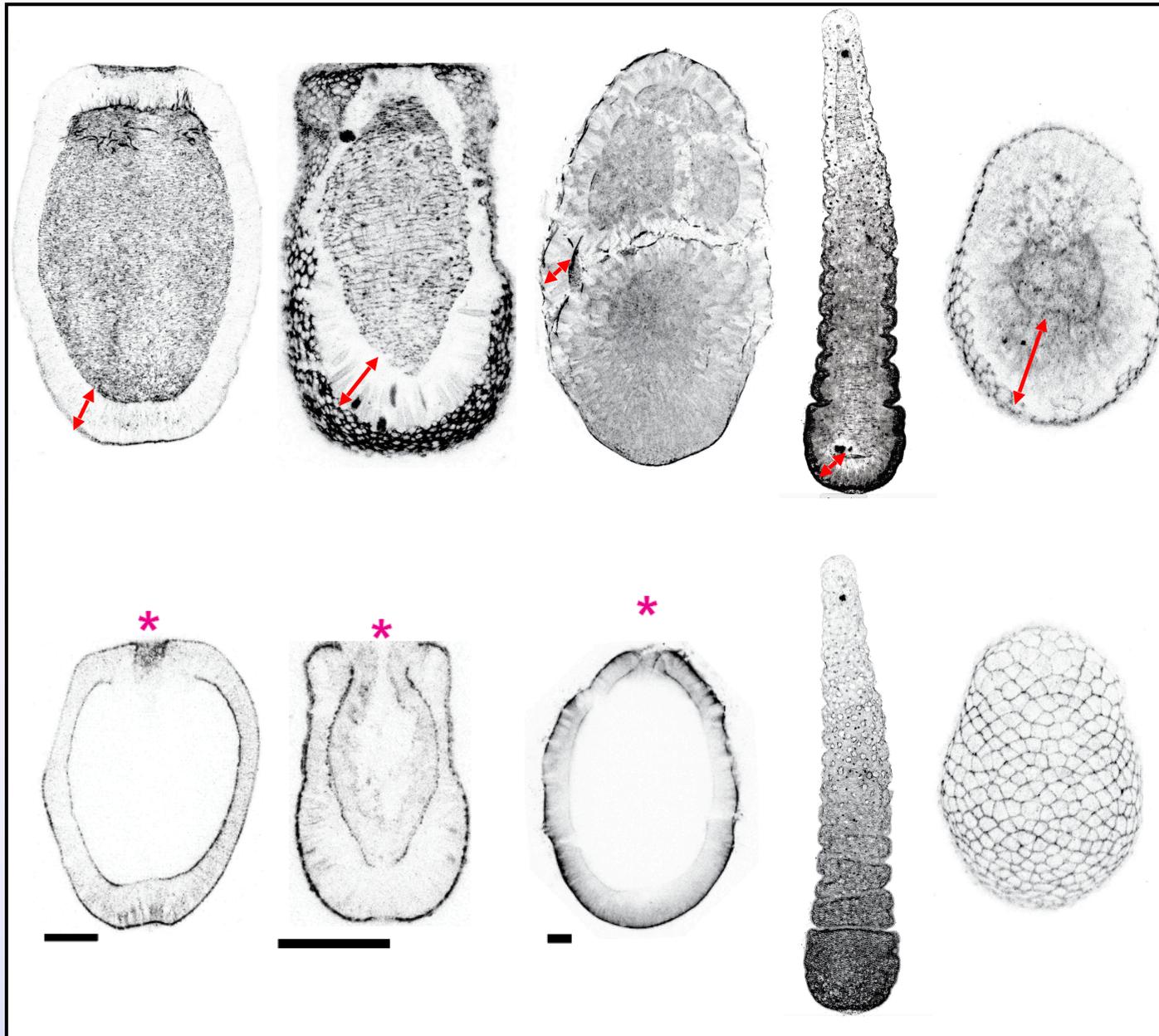
Nematostella

Aiptasia

Galaxea

Hydractinia

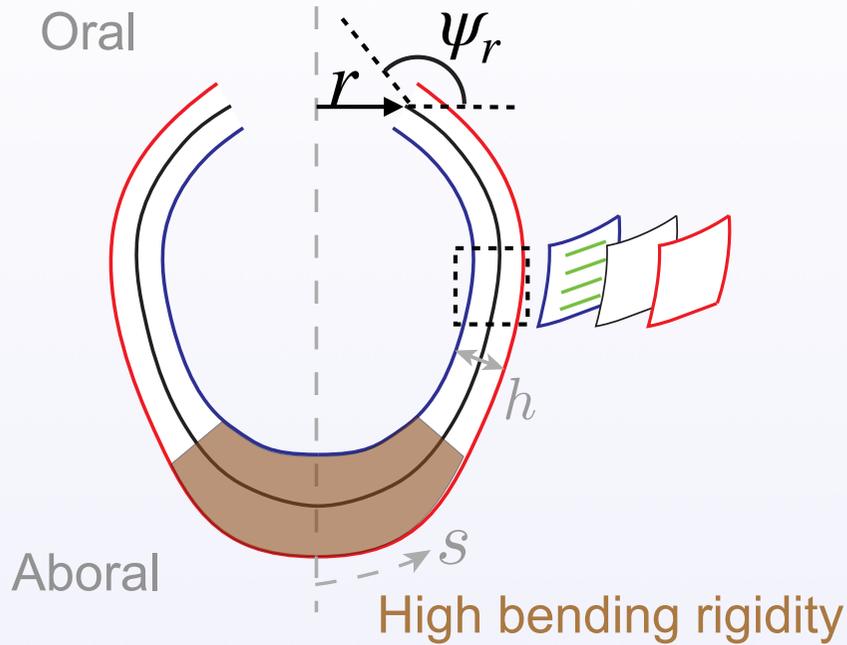
Cladonema



- Species-specific variations in thickness profiles of the ectoderm

- Variable oral opening geometry

Active surface theory for cnidarian larvae

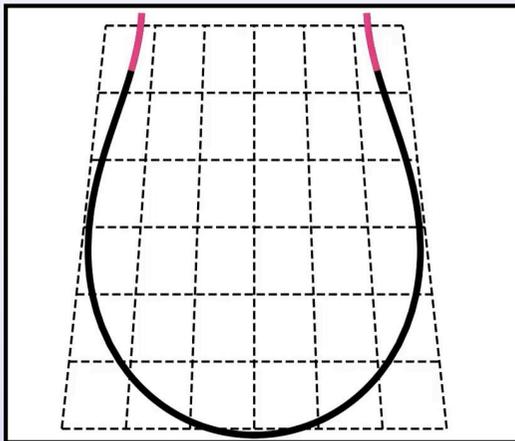


Constitutive equations for tensions and bending moments:

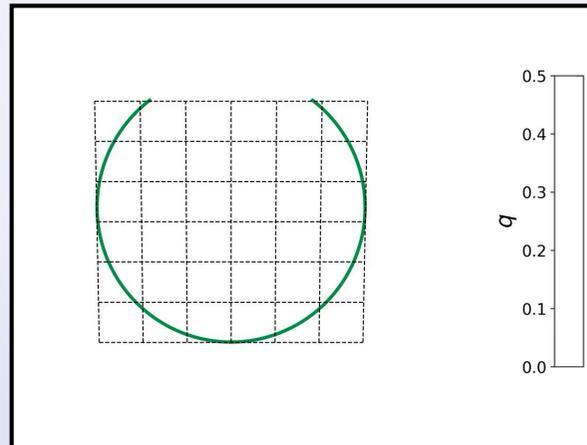
$$t_{ij} = 2K u g_{ij} + \zeta_n Q_{ij}$$

$$\bar{m}_{ij} = 2\kappa(s) C_k^k g_{ij} - \frac{h}{2} \zeta_n Q_{ij}$$

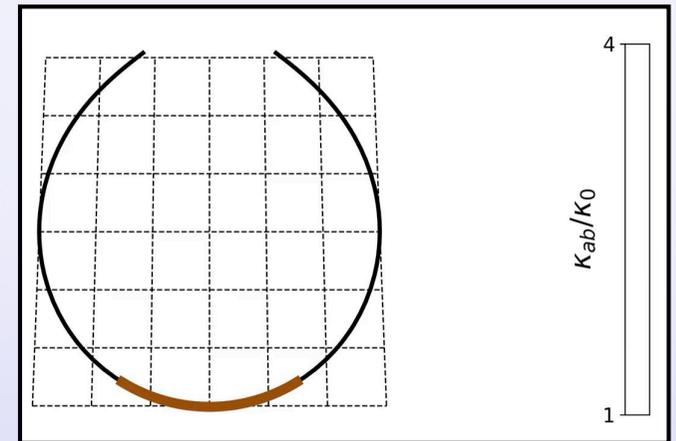
Boundary conditions r, ψ_r :



Active nematic stresses ζ_n :

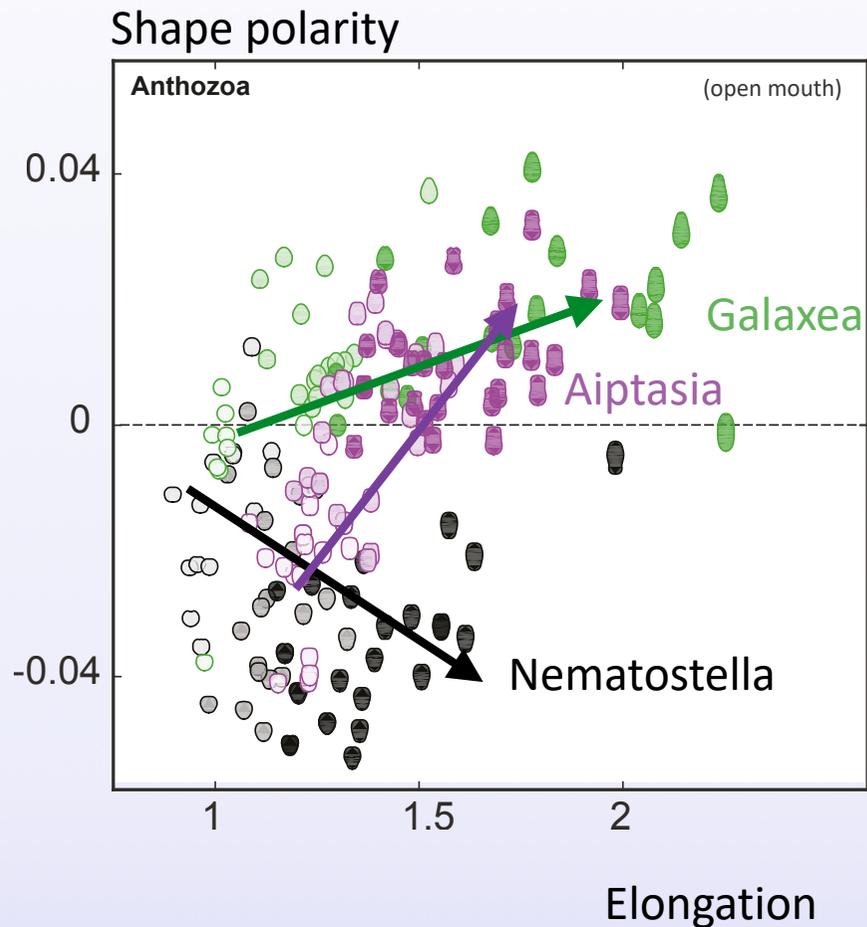


Gradient of bending rigidity $\kappa(s)$:

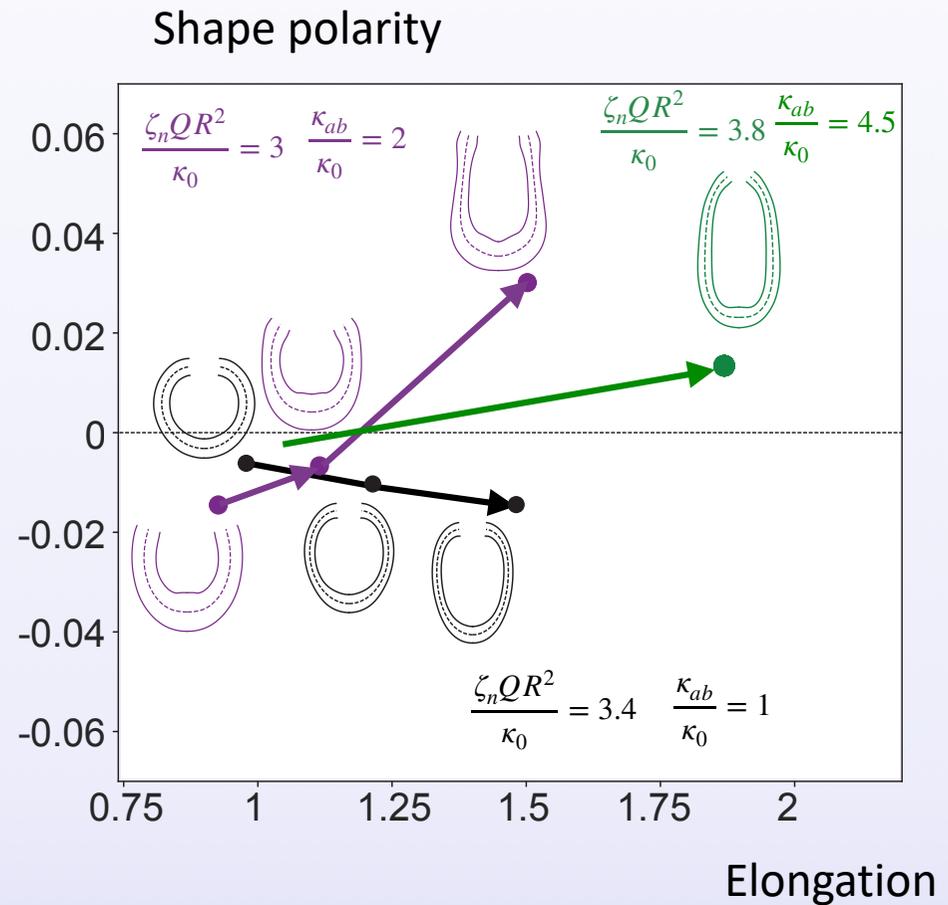


From active surface theory to morphospace

Morphospace (experiment)



Morphospace (theory, aboral increased bending rigidity)



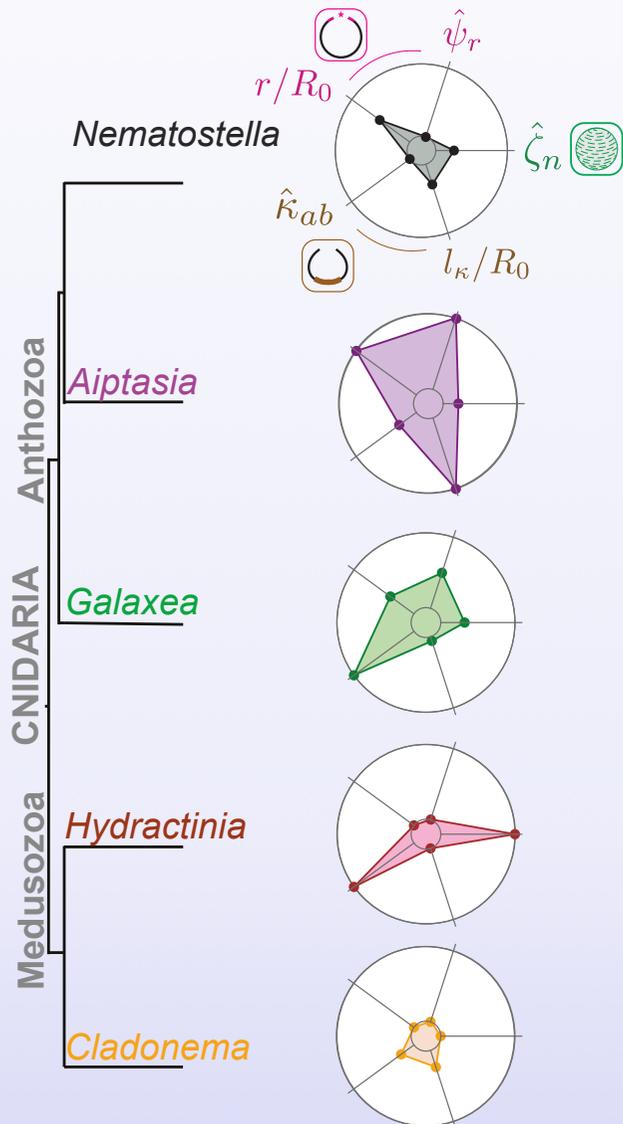
Varying two free parameters per species

From “mechanotype” to phenotype

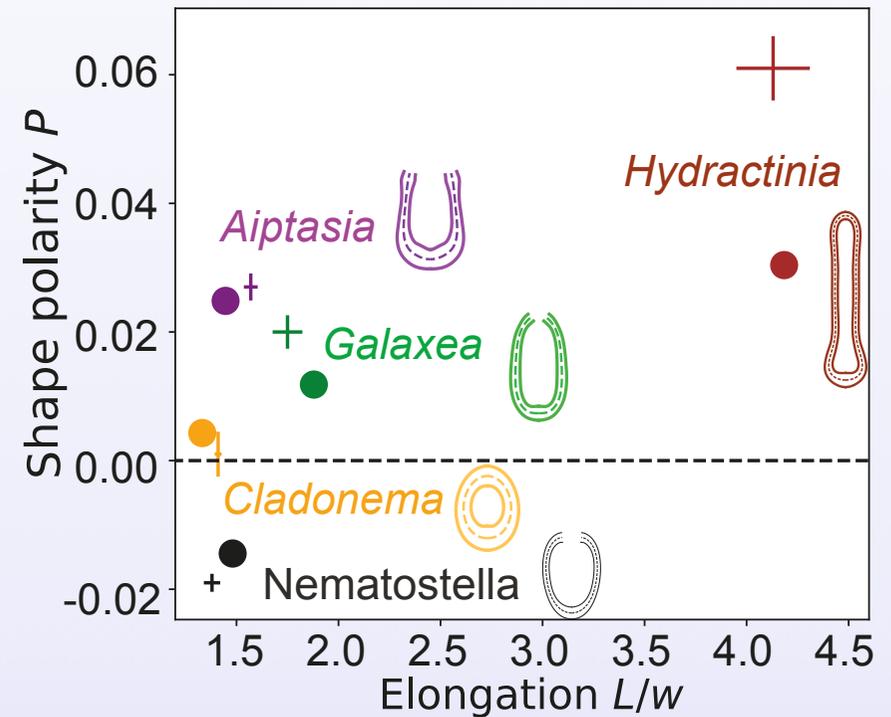
Nematic active surface theory

$$t_{ij} = 2Kug_{ij} + \zeta_n Q_{ij} \quad +\text{B.C. } r, \psi_r$$

$$\bar{m}_{ij} = 2\kappa(s)C_k^k g_{ij} - \frac{h}{2}\zeta_n Q_{ij}$$



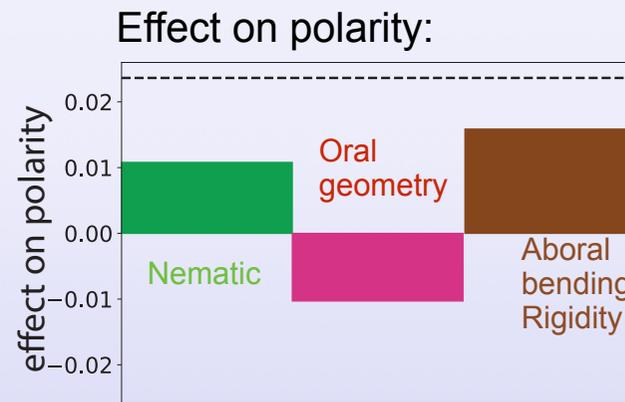
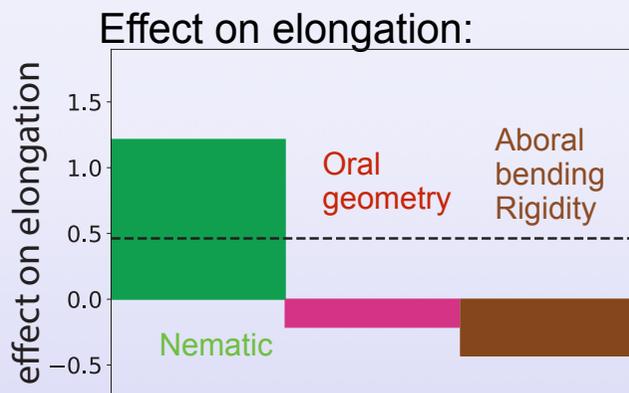
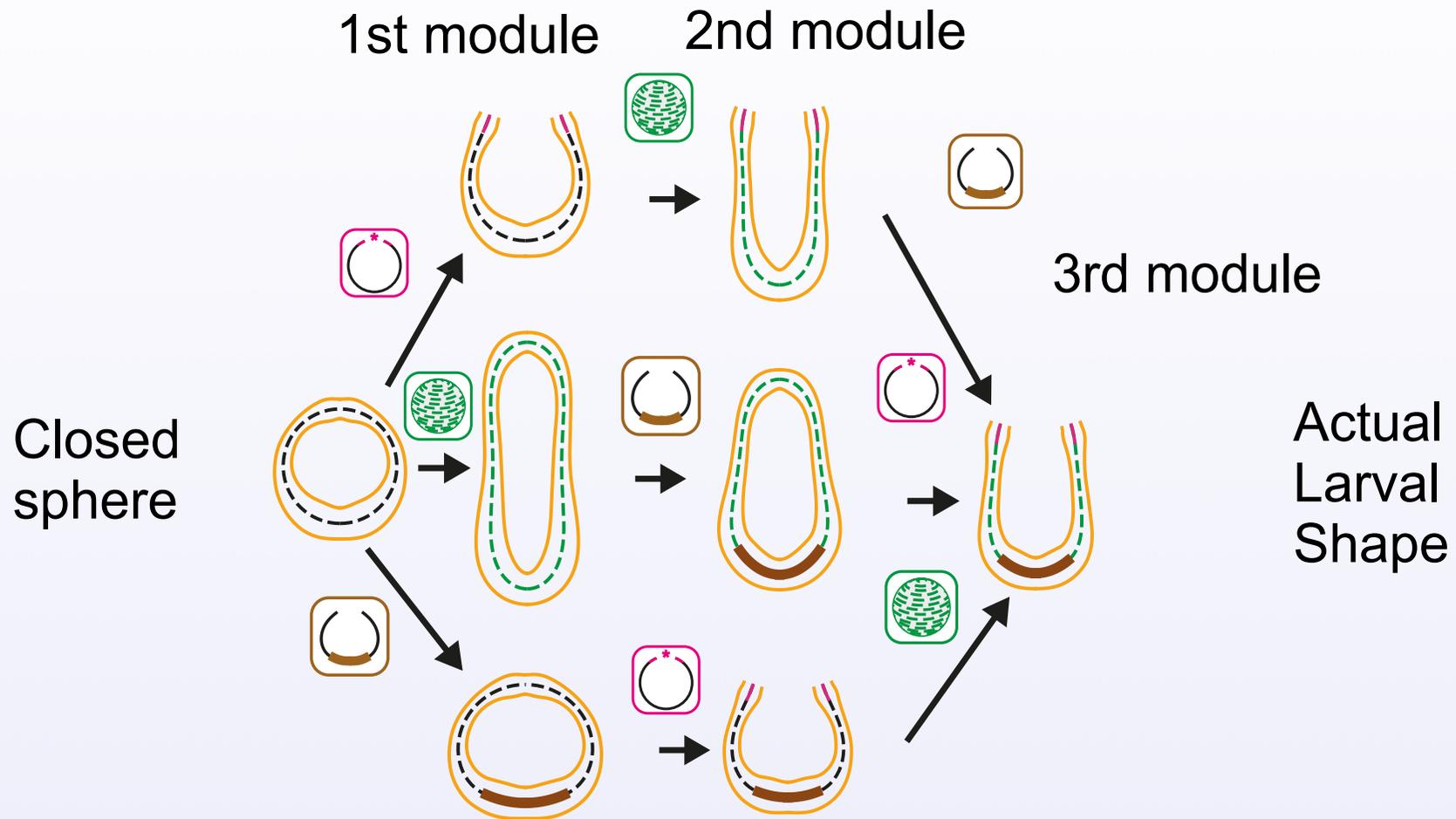
Shape (morphospace)



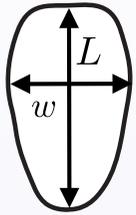
- + Experiment
- Simulation

Dissociating modules

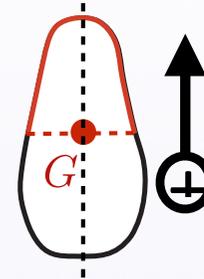
Aiptasia



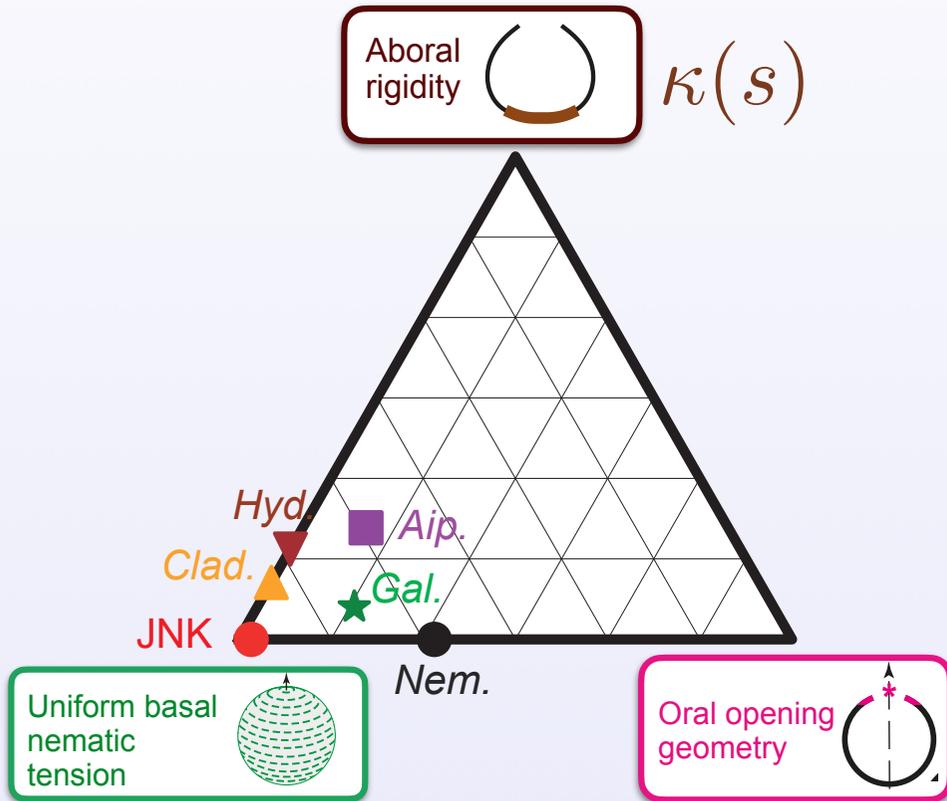
Relative role of mechanical modules in setting elongation and shape polarity



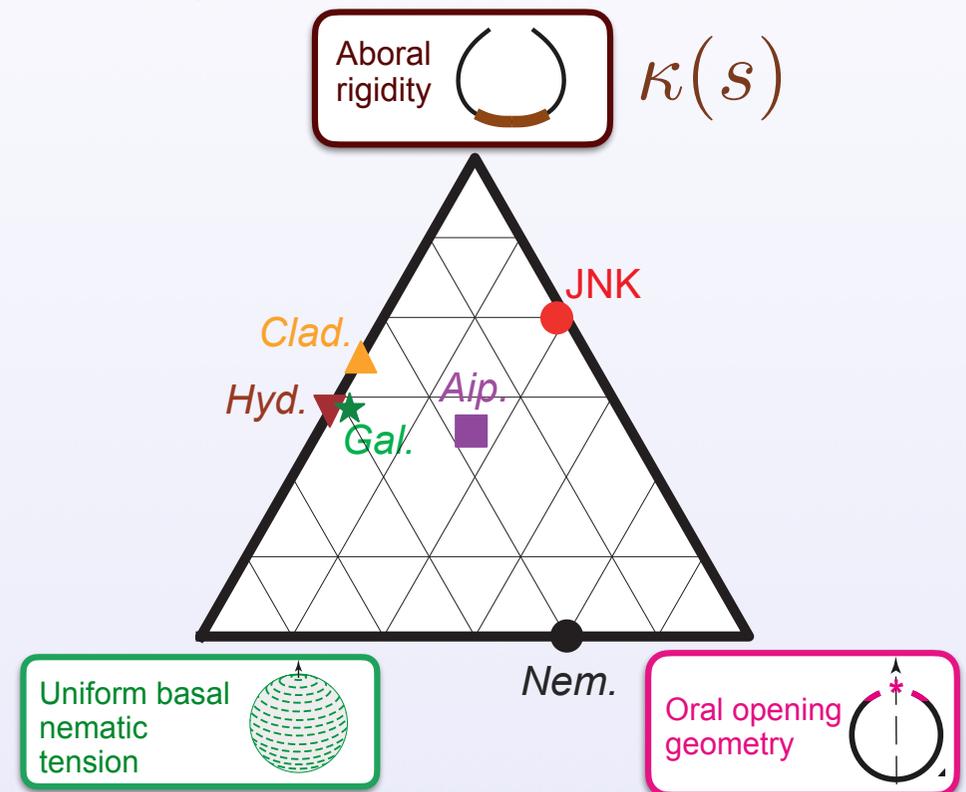
Elongation



Shape polarity



“Simple” trait



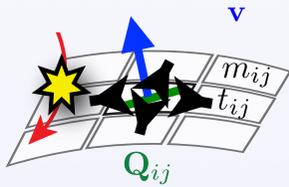
“Complex” trait

The rich physics of active nematic surfaces

- Nematic order dynamics is key to biological tissues



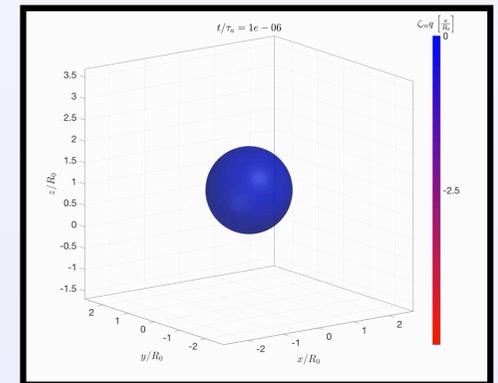
- Hydrodynamic theory of active surfaces with tensions and bending moments



$$t_{ij} = 2Kug_{ij} + \zeta g_{ij} + \zeta_n Q_{ij} + \eta v_{ij}$$

$$\bar{m}_{ij} = \kappa C_{ij} + \zeta_c g_{ij} + \zeta_{cn} Q_{ij} + \eta_c D_t C_{ij}$$

- Conditions for spontaneous tubulogenesis in active nematic surfaces



- Mechanical origin of shape diversity in evolution



Acknowledgements

Looking for PhD student and postdocs!



Salbreux group:

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