



Stein-optimal transport for the Signal-to-Noise problem

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Introduction:

Signal-to-noise degradation
Source reweighting
Improved reweighting

Reformulation:

Map in generative modelling
Expanding the KL divergence

Solution:

Neural-network KL minimisation
Stein-Poisson equation and FK formula
Some preliminary results...

Introduction

Parisi-Lepage: Signal and noise decays as states with different mass gaps

Signal-to-noise

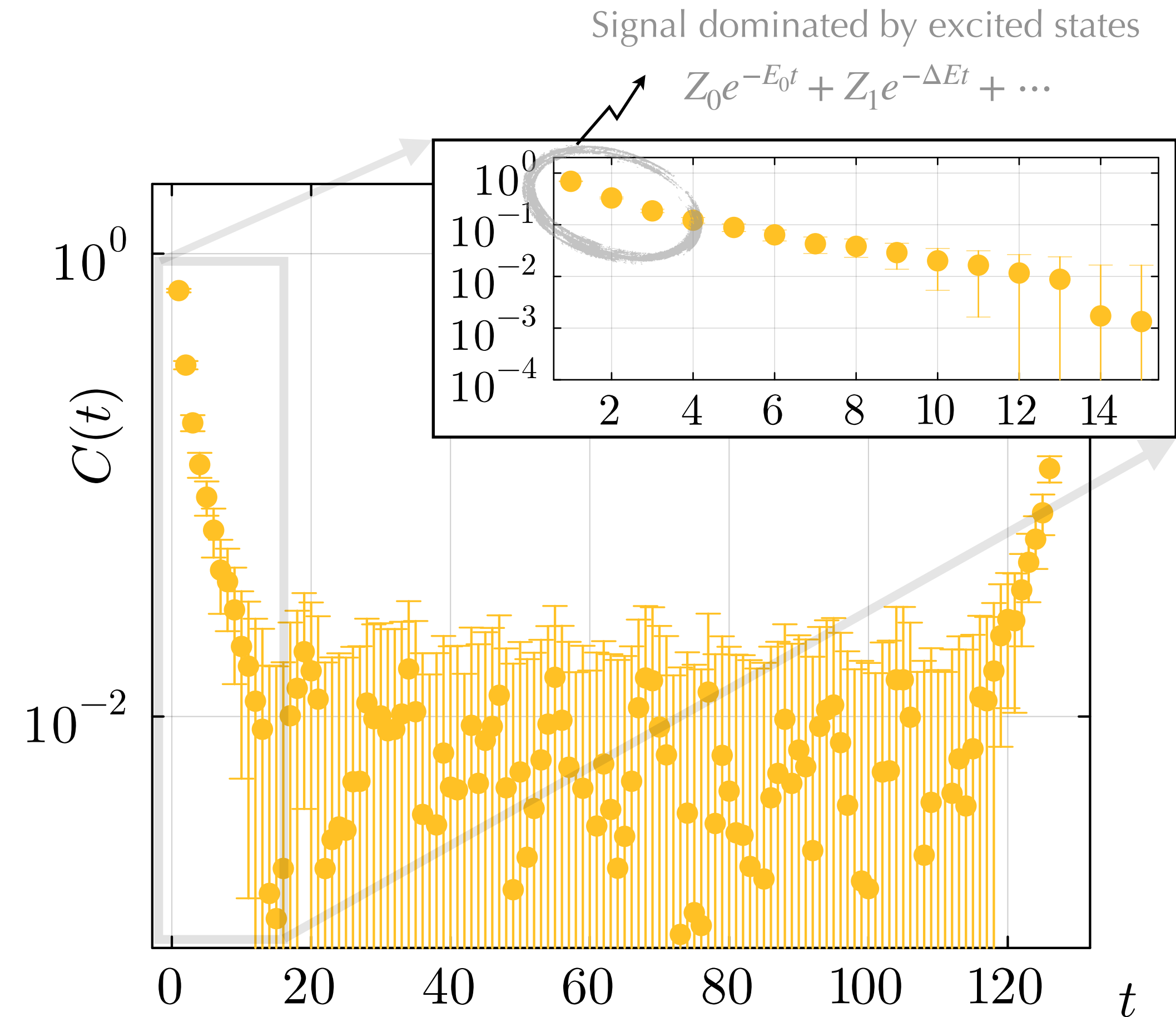
$$C(t) = \langle \mathcal{O}(t) \mathcal{O}^\dagger(0) \rangle \xrightarrow{t \gg (\Delta E)^{-1}} Z e^{-M_{\text{signal}} t}$$

Mass of the lightest states of \mathcal{O}

$$\text{noise} \sim \langle |\mathcal{O}(t) \mathcal{O}^\dagger(0)|^2 \rangle - |C(t)|^2 \xrightarrow{t \gg (\Delta E)^{-1}} Z e^{-M_{\text{noise}} t}$$

Mass of the lightest state of $\mathcal{O} \mathcal{O}^\dagger$

$$\frac{\text{error}[C(t)]}{C(t)} \xrightarrow{t \gg (\Delta E)^{-1}} \frac{e^{t\Delta}}{\sqrt{N_{\text{conf}}}}$$



Add a source to the action
then **take derivatives wrt J**

$$S_J = S - J\mathcal{O}_0$$

A new approach

[Catumba, Ramos] - Eur.Phys.J.C 85 (2025)

$$\langle \mathcal{O}_t \rangle_{S_J} = \frac{\langle e^{J\mathcal{O}_0} \mathcal{O}_t \rangle_S}{\langle e^{J\mathcal{O}_0} \rangle_S}$$

$$\langle \mathcal{O}_t \mathcal{O}_0 \rangle_S = \left. \frac{\partial}{\partial J} \right|_{J=0} \langle \mathcal{O}_t \rangle_{S_J}$$

2-point function $C(t)$

$$\mathcal{O}_t[\phi] = \sum_{\vec{x}} \phi(\vec{x})|_{x_0=t}$$

Write $J = \varepsilon$, then expand
the reweighting formula to $\mathcal{O}(\varepsilon)$
...or use Automatic Differentiation!

Correlators via reweighting

$\phi \sim e^{-S}$
Configurations

$e^{-(S-J\mathcal{O}_0)}$
Target distribution

Importance weights (normalized):

$$w[\phi] = e^{S[\phi] - (S[\phi] - J\mathcal{O}_0) + \log \frac{Z}{Z_J}}$$

Reweight to compute $\langle \cdot \rangle_{S_J}$

$$\langle \mathcal{O}_t \rangle_{S_J} = \langle w \mathcal{O}_t \rangle_S$$

Big fluctuation in
reweighting factors

Expand in $J = \varepsilon$ to compute d/dJ

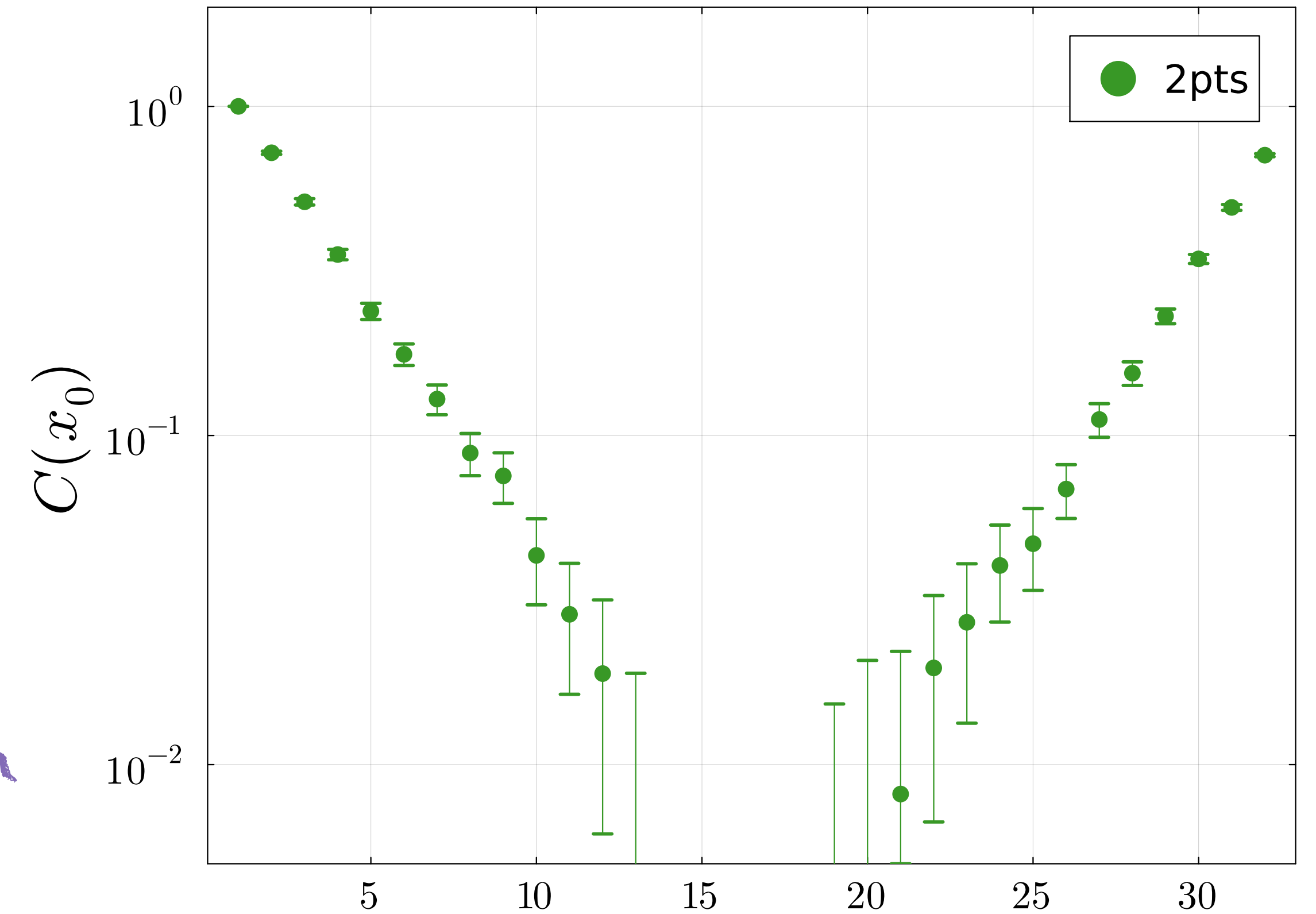
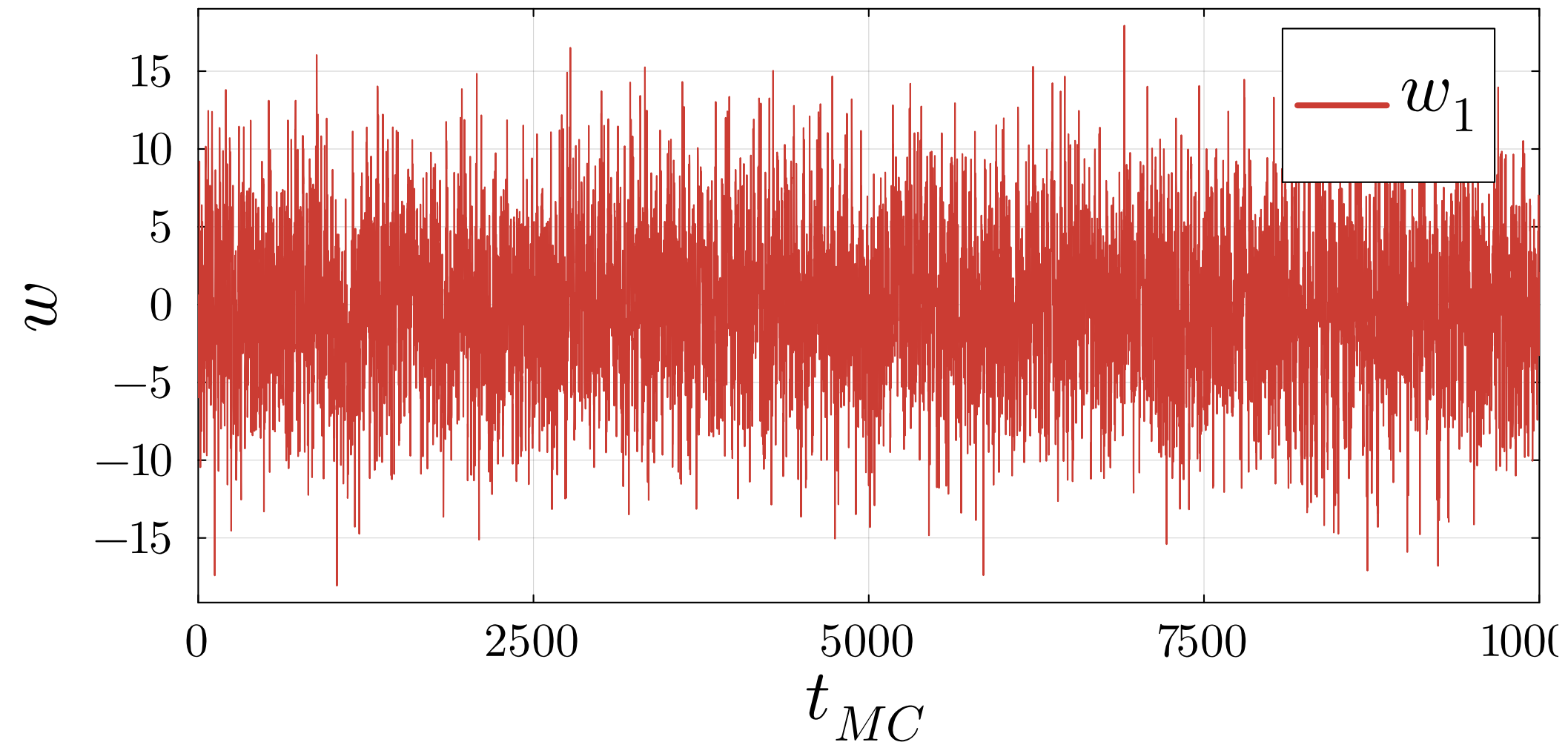
$$= 1 + \varepsilon (\mathcal{O}_0 - \langle \mathcal{O}_0 \rangle) + \dots$$

$$= \langle \mathcal{O}_t \rangle_S + \varepsilon C(t) + \dots$$

signal-to-noise
degradation

$$\langle w \mathcal{O}_t \rangle_S = \langle \mathcal{O}_t \rangle_S + \varepsilon C(t) + \dots$$

Correlators via reweighting



Solution: find sample transformation that renders the w constant!

$$\phi \longrightarrow \tilde{\phi} = \phi + \varepsilon f$$

$\phi \sim e^{-S}$
Configurations

$e^{-(S-J\mathcal{O}_0)}$
Target distribution

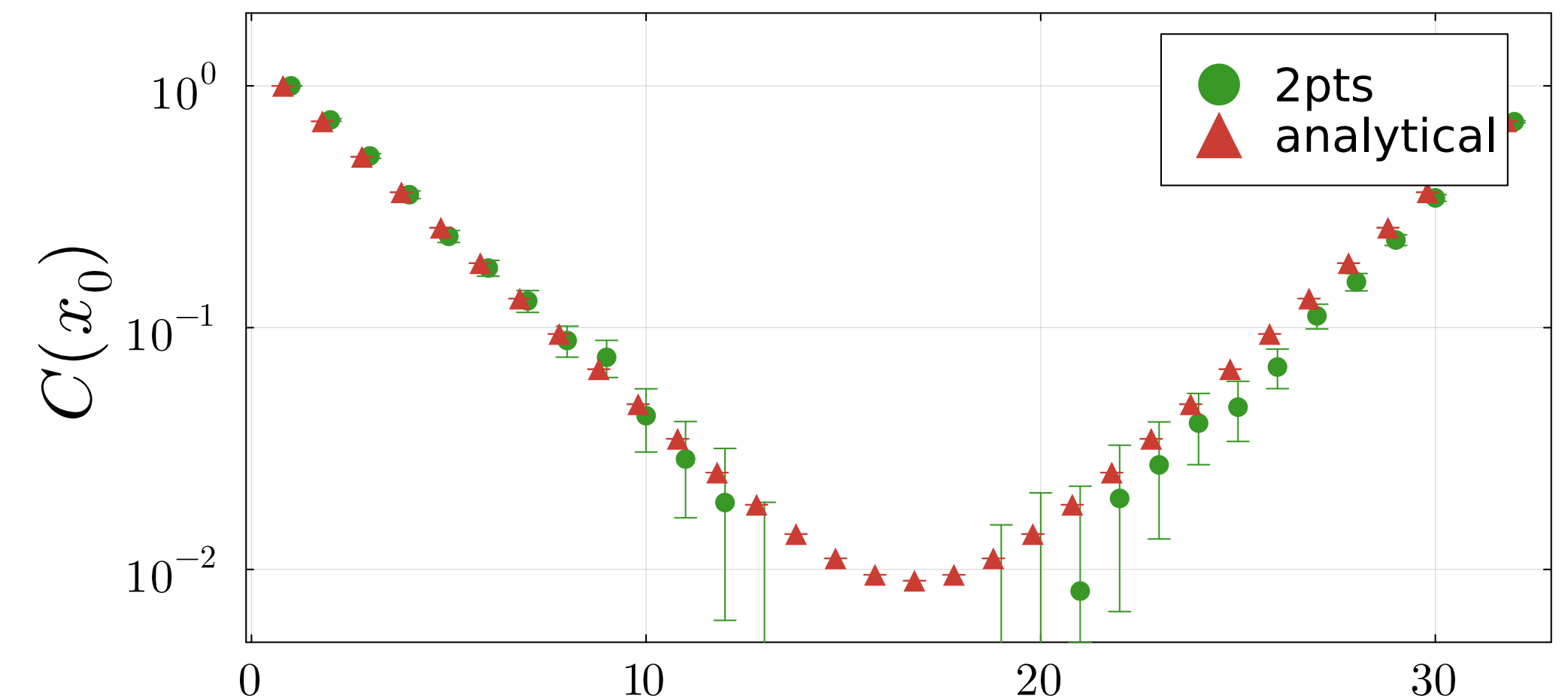
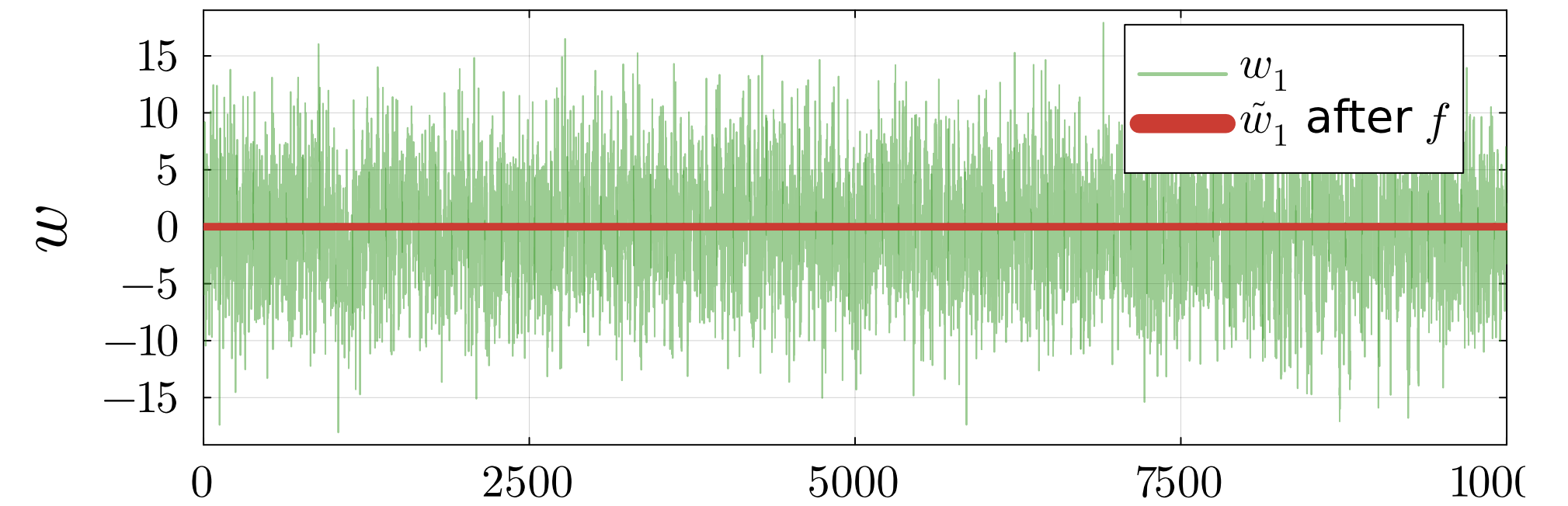
Improved reweighting

Transform samples before reweighting

$$\phi \longrightarrow \tilde{\phi} = \phi + \varepsilon f$$

Scalar free theory:

$$\phi_p \longrightarrow \tilde{\phi}_p = \phi_p + \frac{1}{2} \frac{\delta(\vec{p})}{\hat{p}^2 + \hat{m}^2} \varepsilon$$



Improved reweighting

$$\phi \sim e^{-S}$$

Configurations

$$e^{-(S - J\mathcal{O}_0)}$$

Target distribution

Transform samples before reweighting

$$\phi \longrightarrow \tilde{\phi} = \phi + \varepsilon f$$

reweight with...

$$w = \exp \left[-S_J[\tilde{\phi}] + S[\phi] + \log |1 + \varepsilon J_f| \right]$$

Scalar ~~free~~ interacting theory:

$$\phi_p \longrightarrow \tilde{\phi}_p = \phi_p + \frac{1}{2} \frac{\delta(\vec{p})}{\hat{p}^2 + \hat{m}_R^2(\phi)} \varepsilon$$

Renormalised mass

Reformulating as generative modelling

Reformulating

Lattice / physics

transport / flow

Action

$$S$$

Action w/ a source

$$S - J\mathcal{O}_0$$

Base distribution

$$r = e^{-S} / Z_0$$

Target distribution

$$p = e^{-S_J} / Z_J$$

Transf. of configs induces effective action

$$\phi \longrightarrow \tilde{\phi} = \phi + \varepsilon f(\phi)$$

Transport/flow map

$$\phi \rightarrow T(\phi) \sim q = r | \det J_T |^{-1}$$

Reweighting factors

$$\log w = -\Delta S + \log |1 + \varepsilon J_f|$$

Overlap factor / likelihood ratio

$$\log w = \log p(T(\phi)) - \log r(\phi) + \log \det J_T$$

$$= -\text{KL}(q || p_\varepsilon)$$

$$\text{KL}(q || p_\varepsilon) = \frac{1}{2} \text{Var}[\log w] + \mathcal{O}(\log w)^3$$

Linearised flow maps

Target distribution

p

$q_\theta(\phi)$

$$\text{KL}(q||p) =$$

$$\left\langle \log \frac{r}{p} \right\rangle$$

base-target KL divergence
(constant)

$$+ \varepsilon \left\langle f \cdot \nabla \log \frac{r}{p} \right\rangle$$

Score-mismatch or
Stein's discrepancy

$$+ \frac{\varepsilon^2}{2} \left(\left\langle (\mathcal{T}_r f)^2 \right\rangle + \left\langle f H_{\log \frac{r}{p}} f \right\rangle \right)$$

Riemannian "length" of f
in Stein's geometry

Curvature instabilities
(Hessian mismatch)

$$\mathcal{T}_r f = \nabla \cdot f + f \cdot \log r$$

\hbar QTC

Infinitesimal transport
 $\phi \rightarrow \phi + \varepsilon f_\theta(\phi)$

$r(\phi)$

Base distribution

Linearised flow maps

Target distribution
 $S - \epsilon \mathcal{O}_0$

$q_\theta(\phi)$

$$\text{KL}(q||p) =$$

$$\left\langle \log \frac{r}{p} \right\rangle$$

base-target KL divergence
 (constant)

$$+ \epsilon \left\langle f \cdot \nabla \log \frac{r}{p} \right\rangle$$

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Riemannian "length" of f
 in Stein's geometry

Curvature instabilities
 (Hessian mismatch)

$$\mathcal{T}_r f = \nabla \cdot f - f \cdot \nabla S$$

\hbar QTC

Infinitesimal transport
 $\phi \rightarrow \phi + \epsilon f_\theta(\phi)$

S

Base distribution

Linearised flow maps

Target distribution
 $S - \epsilon \mathcal{O}_0$

$q_\theta(\phi)$

$$\text{KL}(q||p) = \frac{\epsilon^2}{2} \left\langle (\mathcal{T}_r f)^2 - 2f \cdot \nabla \mathcal{O}_0 \right\rangle + \dots$$

Infinitesimal transport
 $\phi \rightarrow \phi + \epsilon f_\theta(\phi)$

S

Base distribution

Parameterise f with a neural network

$$f_\theta(\phi) = \text{iFFT} \left[\frac{\Lambda_\theta(\tilde{\phi}_p) \delta(\mathbf{p})}{\hat{p}^2 + \mathbb{M}_\theta(\tilde{\phi}_p)} \right]$$

Use KL as a loss function

$$\left\langle (\text{tr} J_{f_\theta} - f_\theta \cdot \nabla S)^2 - 2f_\theta \cdot \nabla \mathcal{O}_0 \right\rangle$$

Minimise KL w/ variation calculus

$$\mathcal{T}_r f + \Delta \mathcal{O}_0 = 0$$

Solve the Stein-Poisson equation directly
 sample per sample via Feynmann-Kac

How source reweighting could solve the StN degradation?

StN is due to big fluctuations in the reweighting factors

$$\langle w \mathcal{O}_t \rangle = \langle \mathcal{O}_t \rangle + \varepsilon \langle \mathcal{O}_t \mathcal{O}_0 \rangle + \dots$$

Overlap can be systematically improved via a transport map that minimises the KL divergence

$$\phi \rightarrow \phi + \varepsilon f(\phi)$$

$$\min_f \text{Var}[\log w] \approx \min_T \text{KL}(q||p_\varepsilon)$$

Minimising KL is equivalent to solve the Stein-Poisson eq.

$$\text{KL}(q||p) = \frac{\varepsilon^2}{2} \left((\mathcal{T}_r f)^2 - 2f \cdot \nabla \mathcal{O}_0 \right) + \dots \quad \mathcal{T}_r f + \Delta \mathcal{O}_0 = 0$$

Numerical approach

Parameterise f with a NN network

$$f_{\theta}(\phi) = \text{iFFT} \left[\frac{A_{\theta}(\phi)\delta(\mathbf{p})}{\hat{p}^2 + M_{\theta}(\phi)} + \mathbb{R}_{\theta}(\phi) \right]$$

Training: minimise KL to $\mathcal{O}(\varepsilon^2)$

1. Take a batch of samples $\phi \sim e^{-S}$

2. Feedforward through $f_{\theta}(\phi)$

3. Compute KL loss

3.1 Compute HMC force ∇S

3.2 Estimate $\text{tr}J_f$

3.3 Average over batch

$$\left\langle (\text{tr}J_{f_{\theta}} - f_{\theta} \cdot \nabla S)^2 - 2f_{\theta} \cdot \nabla \mathcal{O}_0 \right\rangle$$

4. Backprop to update θ

Direct minimisation via NN

Variance reduction:

1. Improve confs $\tilde{\phi} = \phi + \varepsilon f_{\theta}(\phi)$

2. Compute importance weights

2.1 Compute action diff. $\Delta S[\tilde{\phi}]$

2.2 Estimate $\text{tr}J_f$

2.3 Combine for each sample

$$w[\phi] = \exp \left[\Delta S[\tilde{\phi}] - \varepsilon \text{tr}J_{f_{\theta}} \right]$$

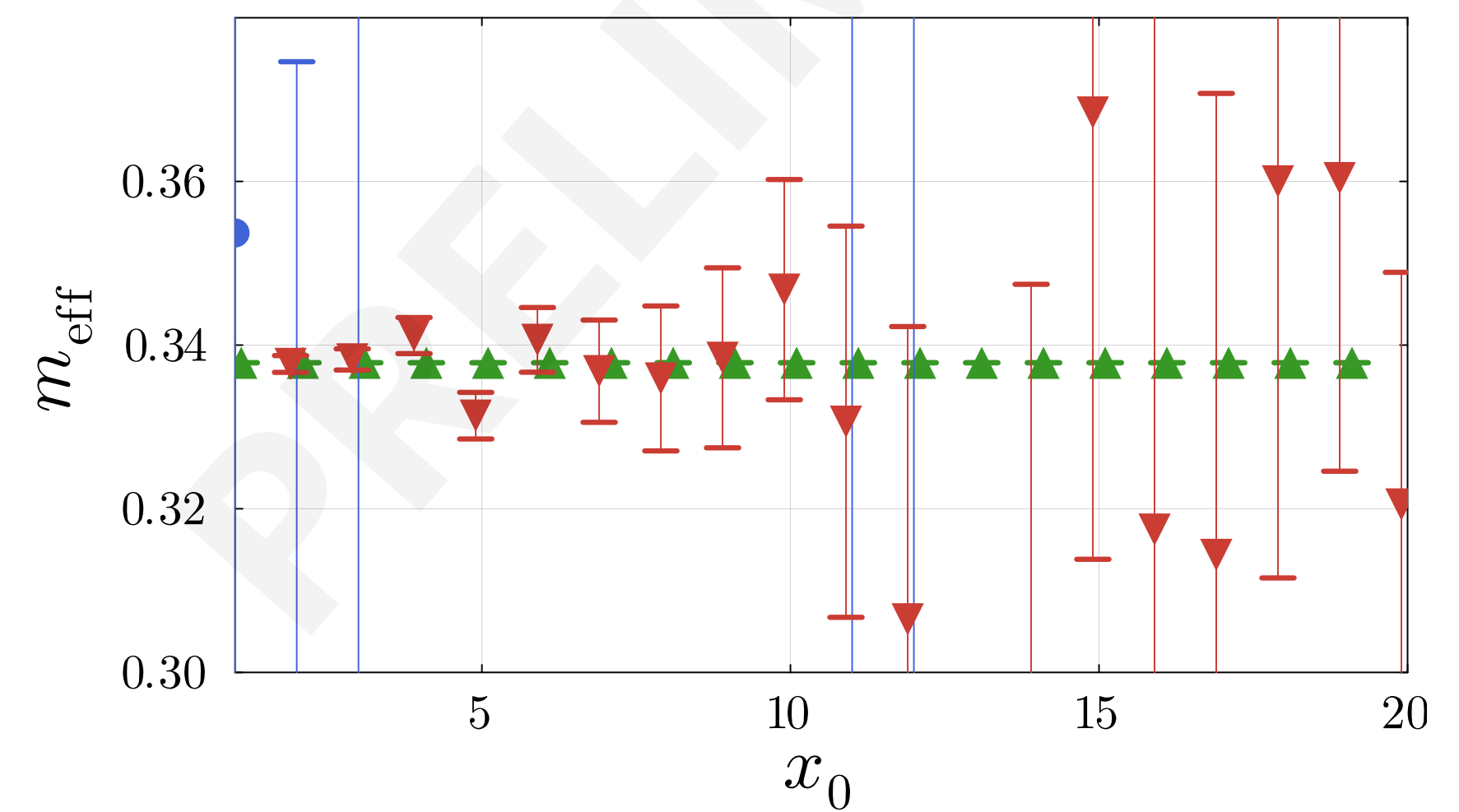
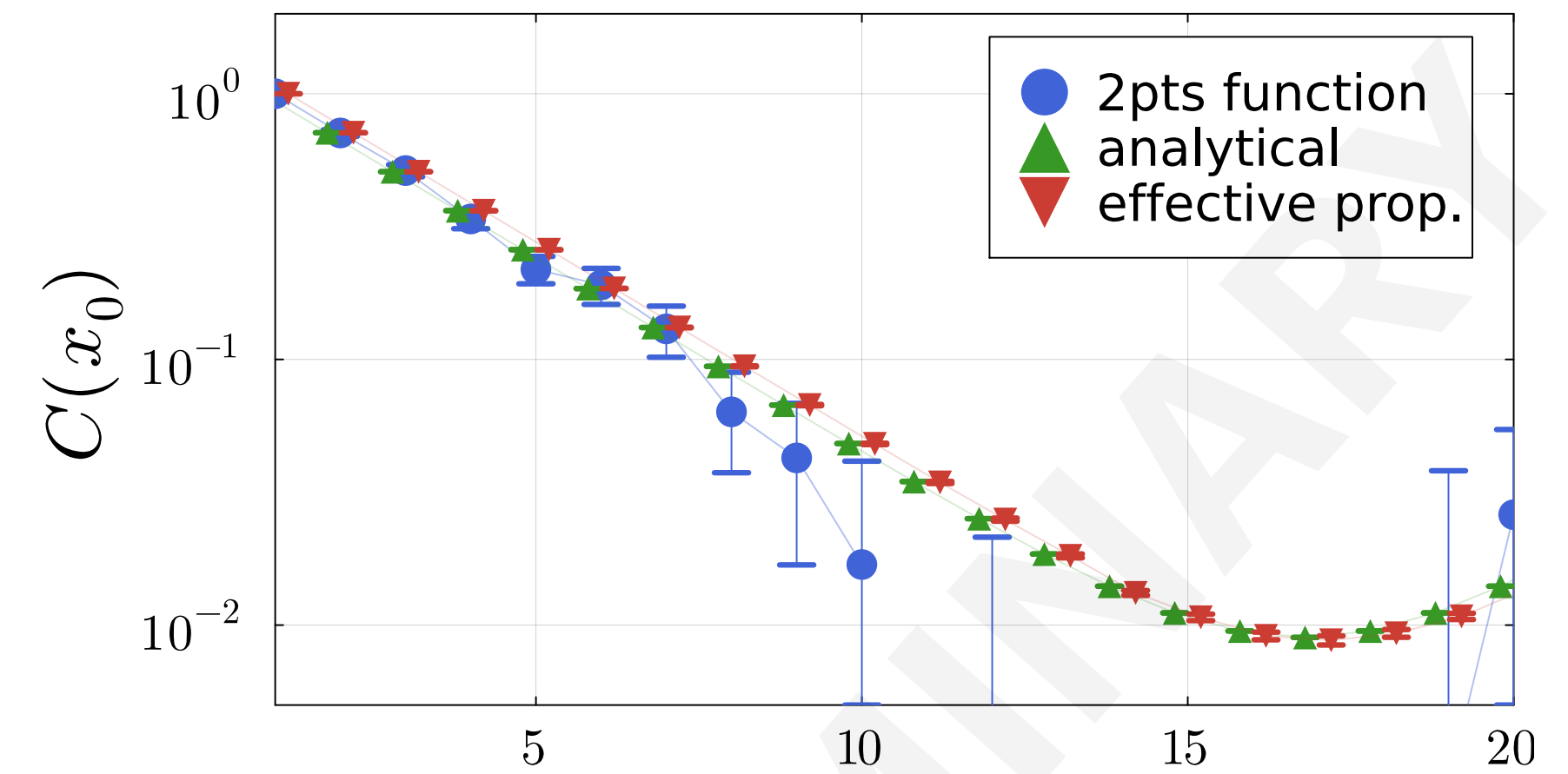
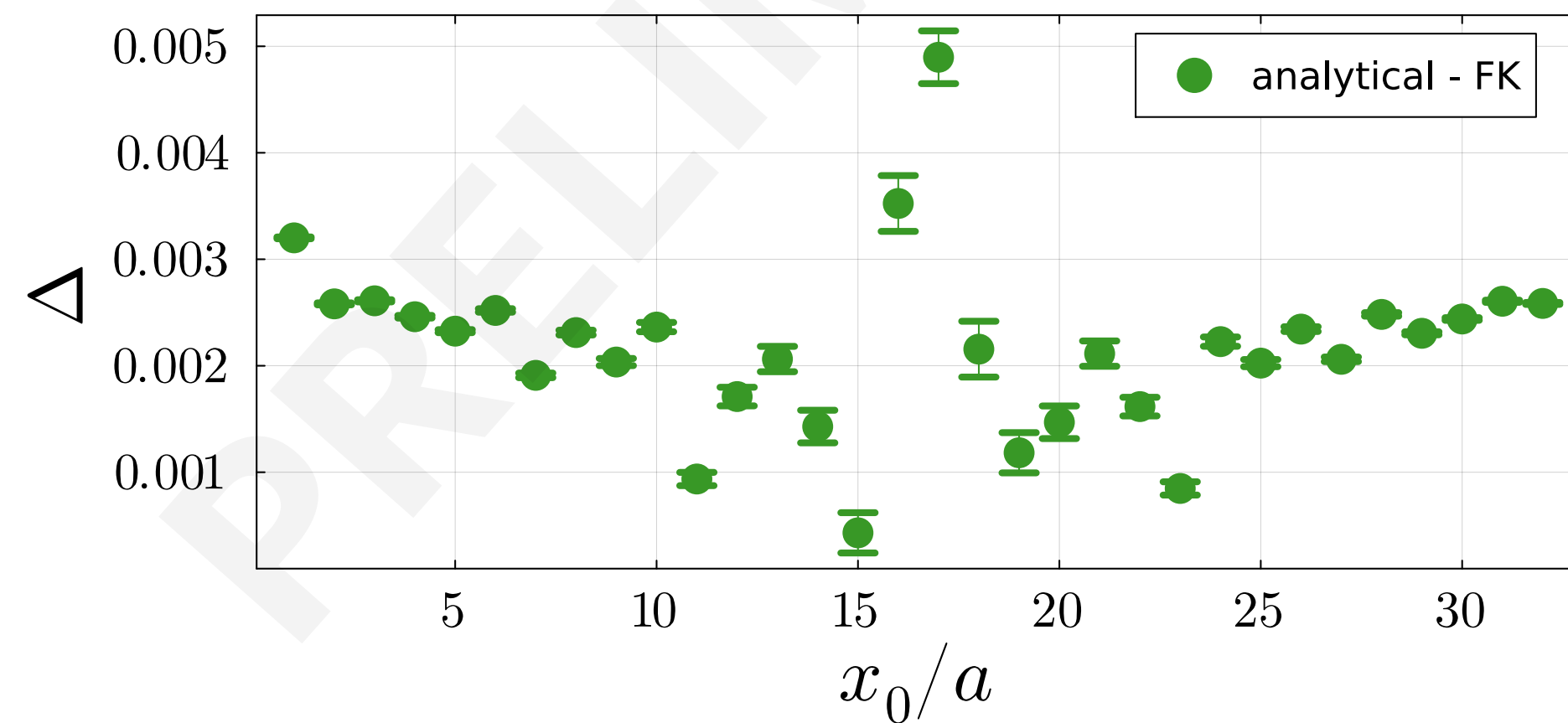
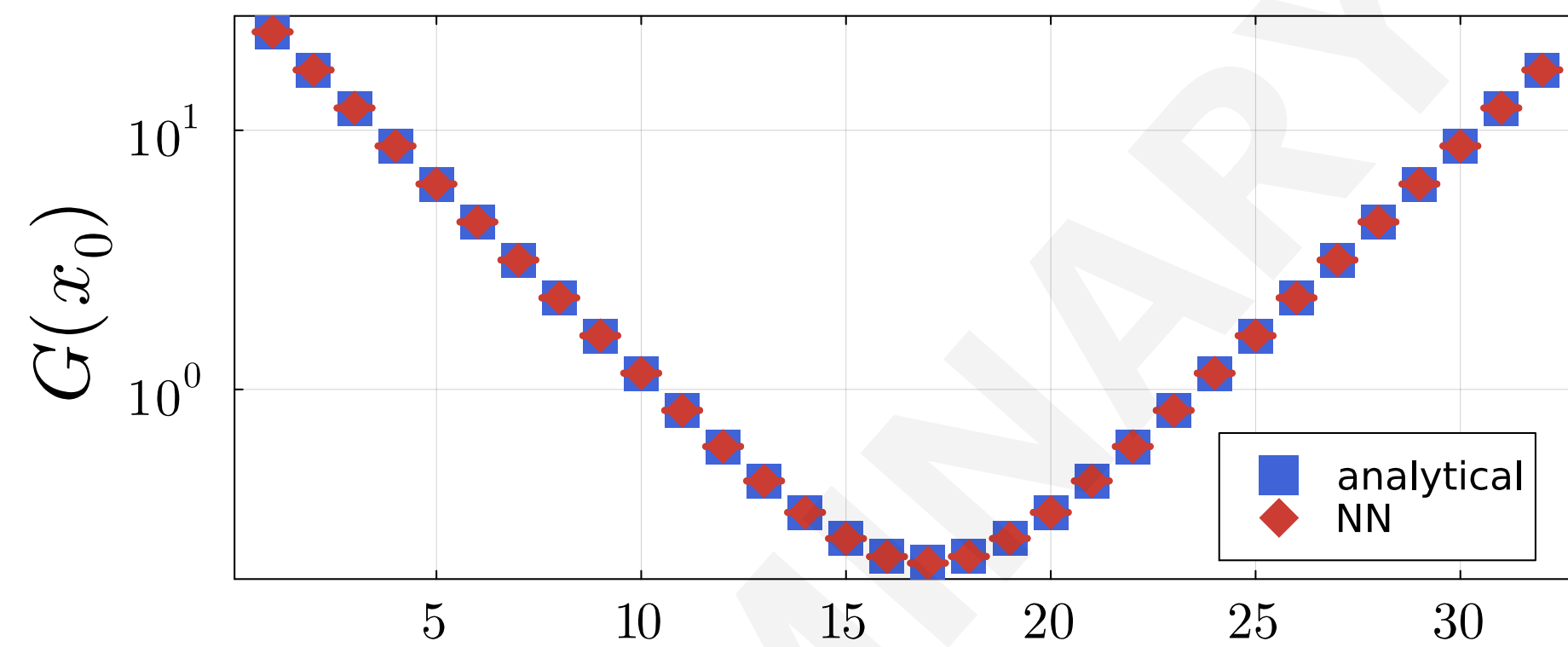
3. Reweight correlator

$$\langle w \mathcal{O}_t \rangle \longrightarrow \text{extract } \mathcal{O}(\varepsilon)$$

4. Propagate error

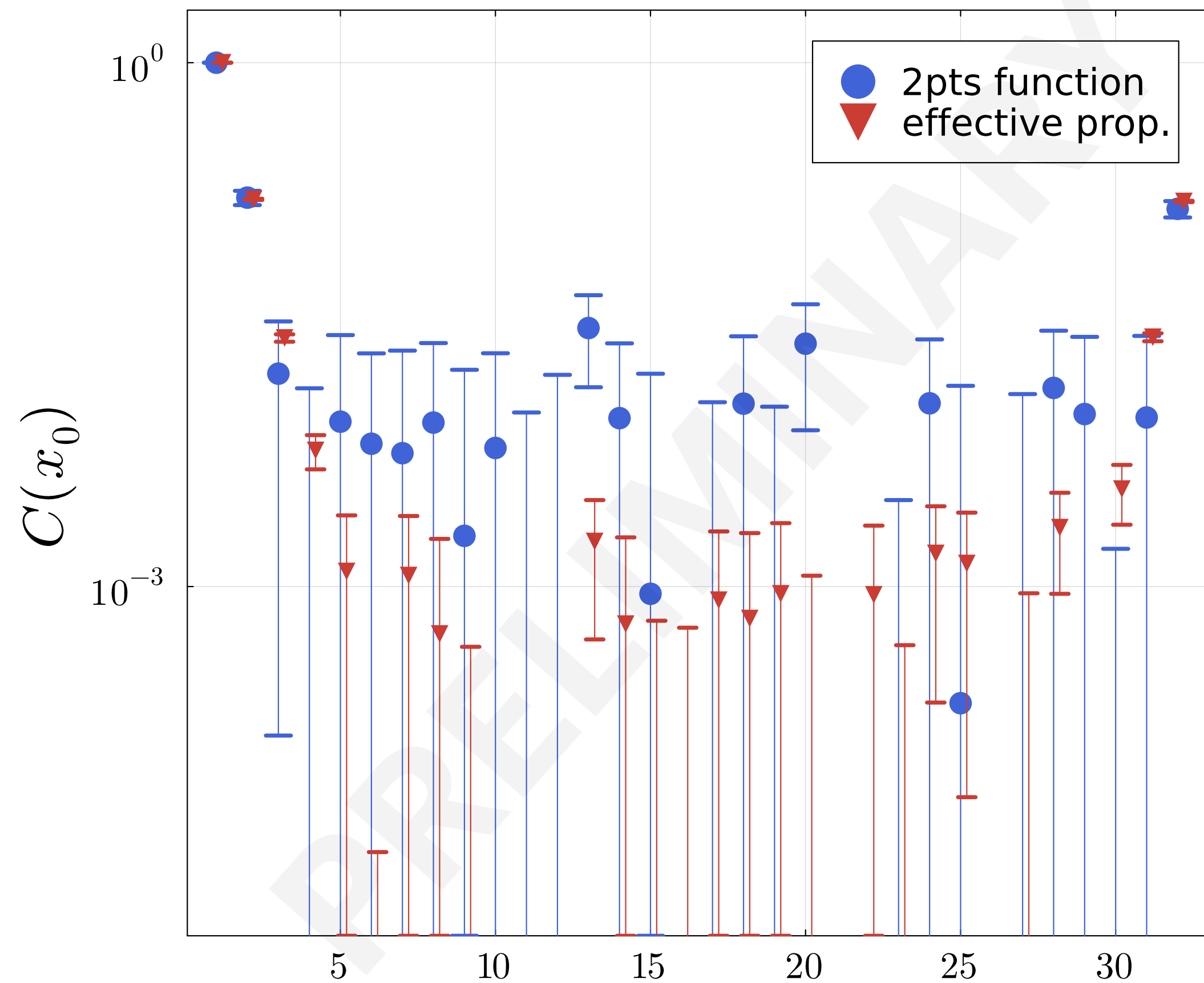
Direct minimisation via NN

$$L = 32 \times 8, \hat{\lambda} = 0.0, \hat{m}^2 = 0.1152$$

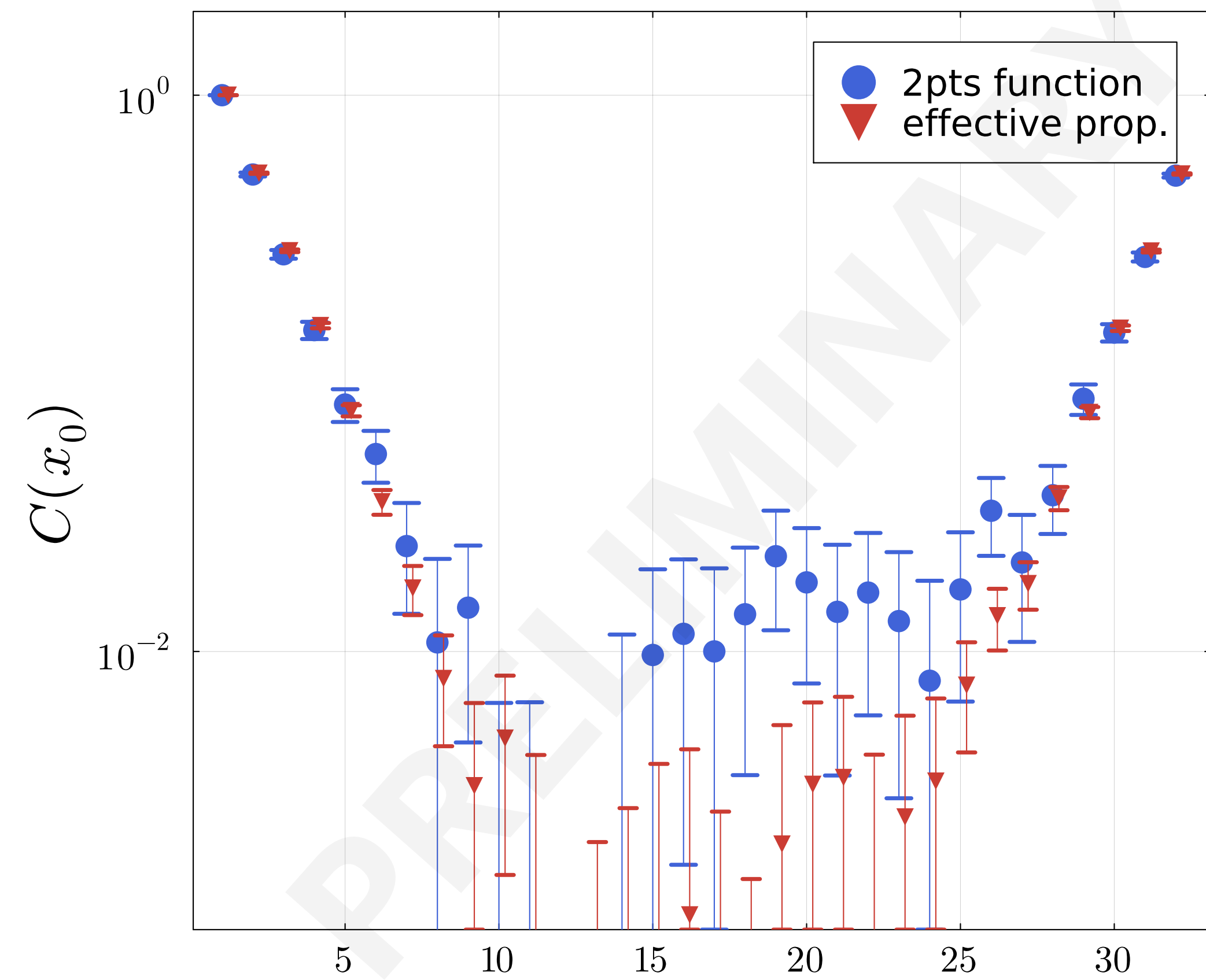


Direct minimisation via NN

$L = 32 \times 8, \lambda = 0.05, \kappa = 0.125$



$L = 32 \times 8, \lambda = 0.05, \kappa = 0.243$



Stein-Poisson equation

Extremal KL divergence ($\delta\text{KL}/\delta f = 0$) implies

$$\mathcal{T}_r f + \Delta\mathcal{O}_0 = 0$$

fluctuation at $t=0$
 $\Delta\mathcal{O}_0 \equiv \mathcal{O}_0 - \langle \mathcal{O}_0 \rangle$

Stein operator

$$\mathcal{T}_r f = \nabla \cdot f - f \cdot \nabla S$$

How to "invert" the Stein operator?

Restrict to gradient fields $f = \nabla\varphi$

$$\mathcal{T}_r f \equiv (\Delta_2 - \nabla S \cdot \nabla)\varphi = -\Delta\mathcal{O}_0$$

Generator of (overdamped)
Langevin dynamics \mathcal{L}

i.e. how a smooth function evolves infinitesimally
in (stochastic) time under Langevin dynamics

$$dZ_\tau = -\nabla S d\tau + \sqrt{2} dW_\tau$$

"inverse" is given by Markov semigroup theory

$$\varphi = -\mathcal{L}^{-1} \Delta\mathcal{O}_0$$

$$f(\phi) = \nabla_{\phi} \varphi$$

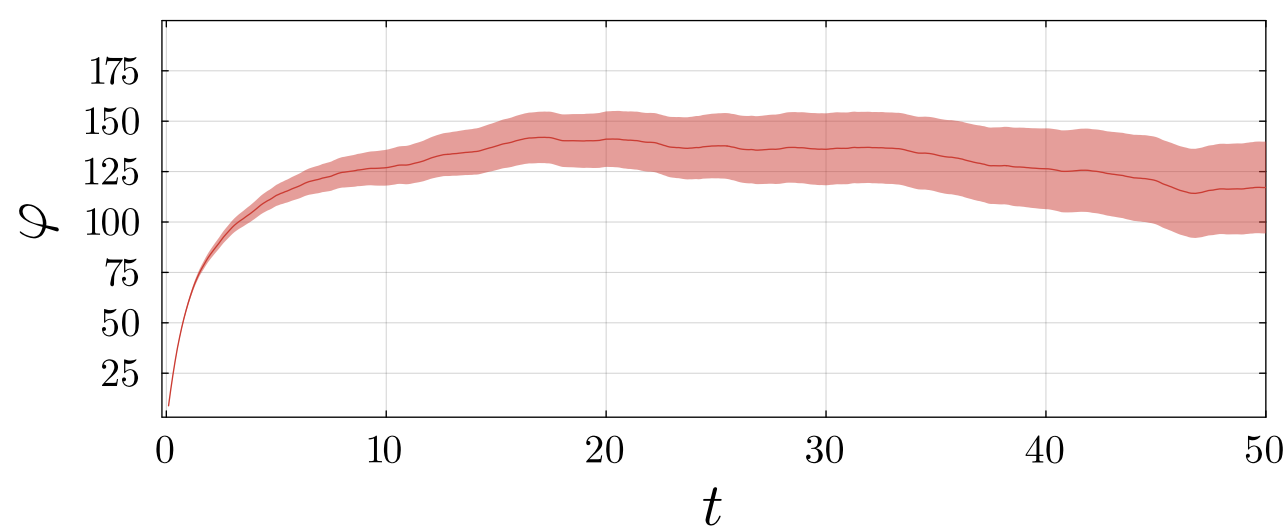
[Kanwar-Albergo] - hep-lat/2603.00252
 [Albergo, Eijnden] - 2410.02711

Feynman-Kac formula

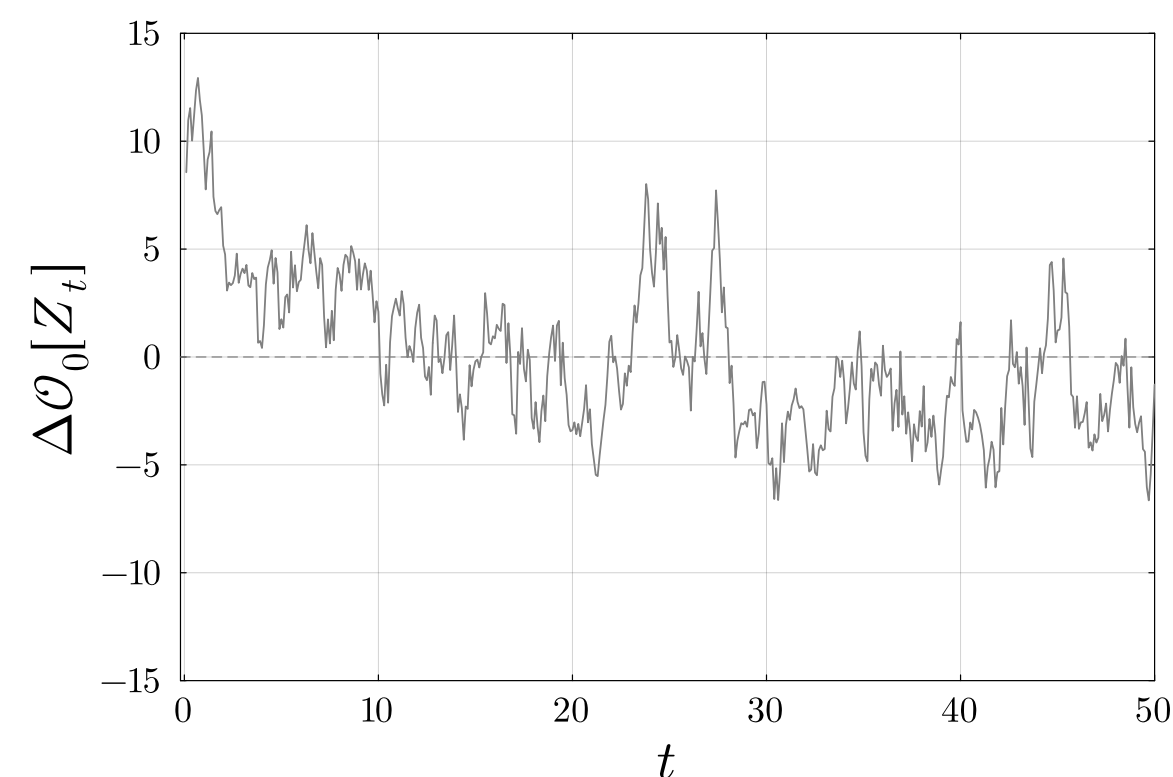
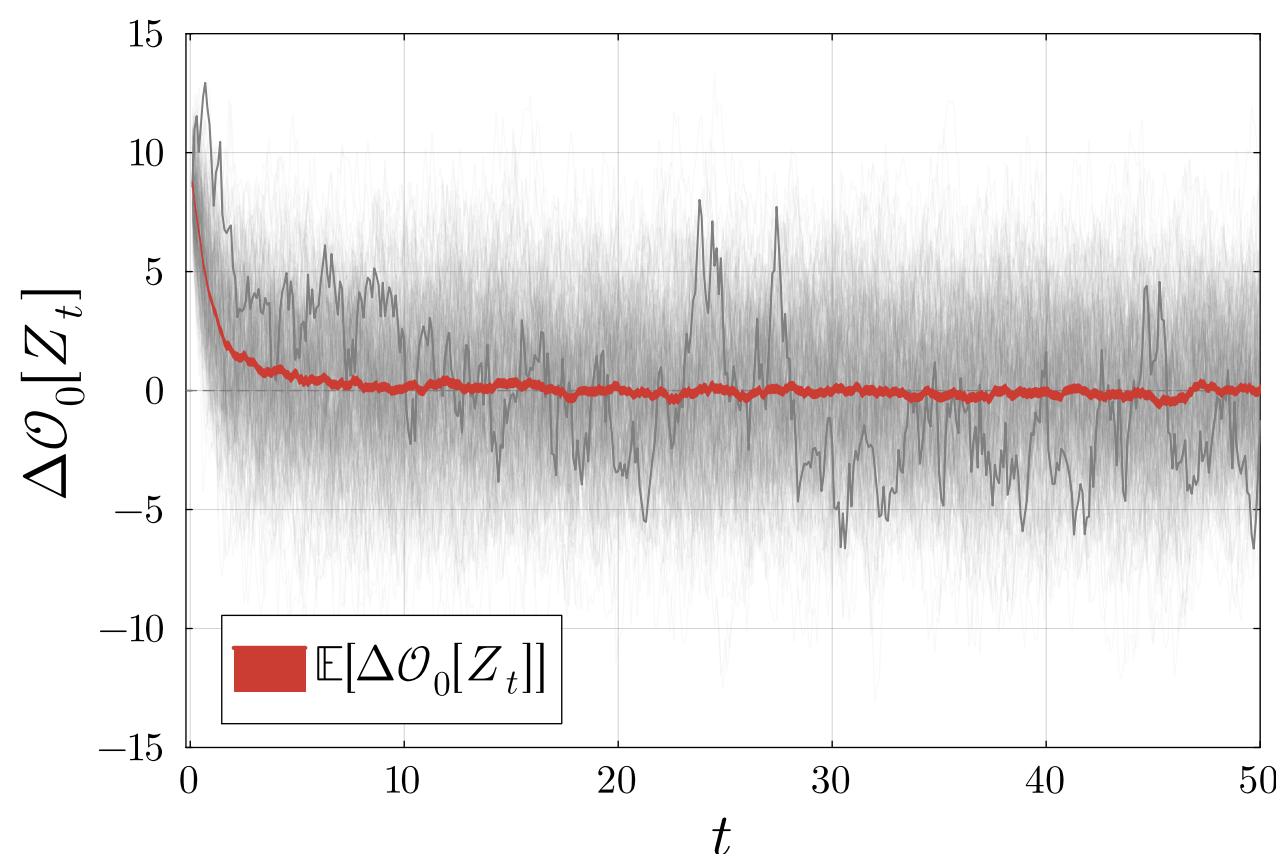
$$\varphi(\phi) = \int_0^{\infty} d\tau \mathbb{E} \left[\mathcal{O}_0[Z_{\tau}] - \langle \mathcal{O}_0 \rangle \mid Z_0 = \phi \right]$$

Integrate Langevin dynamics starting from $Z_0 = \phi$

Integrate in stochastic time



Expectation value over walkers (average over Brownian noise)



$$f(\phi) = \nabla_{\phi} \varphi$$

[Kanwar-Albergo] - hep-lat/2603.00252
[Albergo, Eijnden] - 2410.02711

Feynman-Kac formula

$$f(\phi) = \nabla_{\phi} \int_0^{\infty} d\tau \mathbb{E} \left[\mathcal{O}_0[Z_{\tau}] - \langle \mathcal{O}_0 \rangle \middle| Z_0 = \phi \right]$$



Swap gradient and noise average

$$\nabla_{\phi} = \mathbb{E} \left[\nabla \int_0^{\infty} d\tau \mathcal{O}_0[Z_{\tau} | Z_0 = \phi] \right]$$

$$f = \lim_{T \rightarrow \infty} \mathbb{E}[A_T(\phi)]$$

SDEsolve(...) forward to obtain

$$\hat{\varphi}^{[0,T]} = \int_0^T d\tau \mathcal{O}_0[Z_t]$$

Backprop to get $\nabla_{Z_0} \hat{\varphi}^{[0,T]}$ or save "every" intermediate Z_t and solve adj. backward

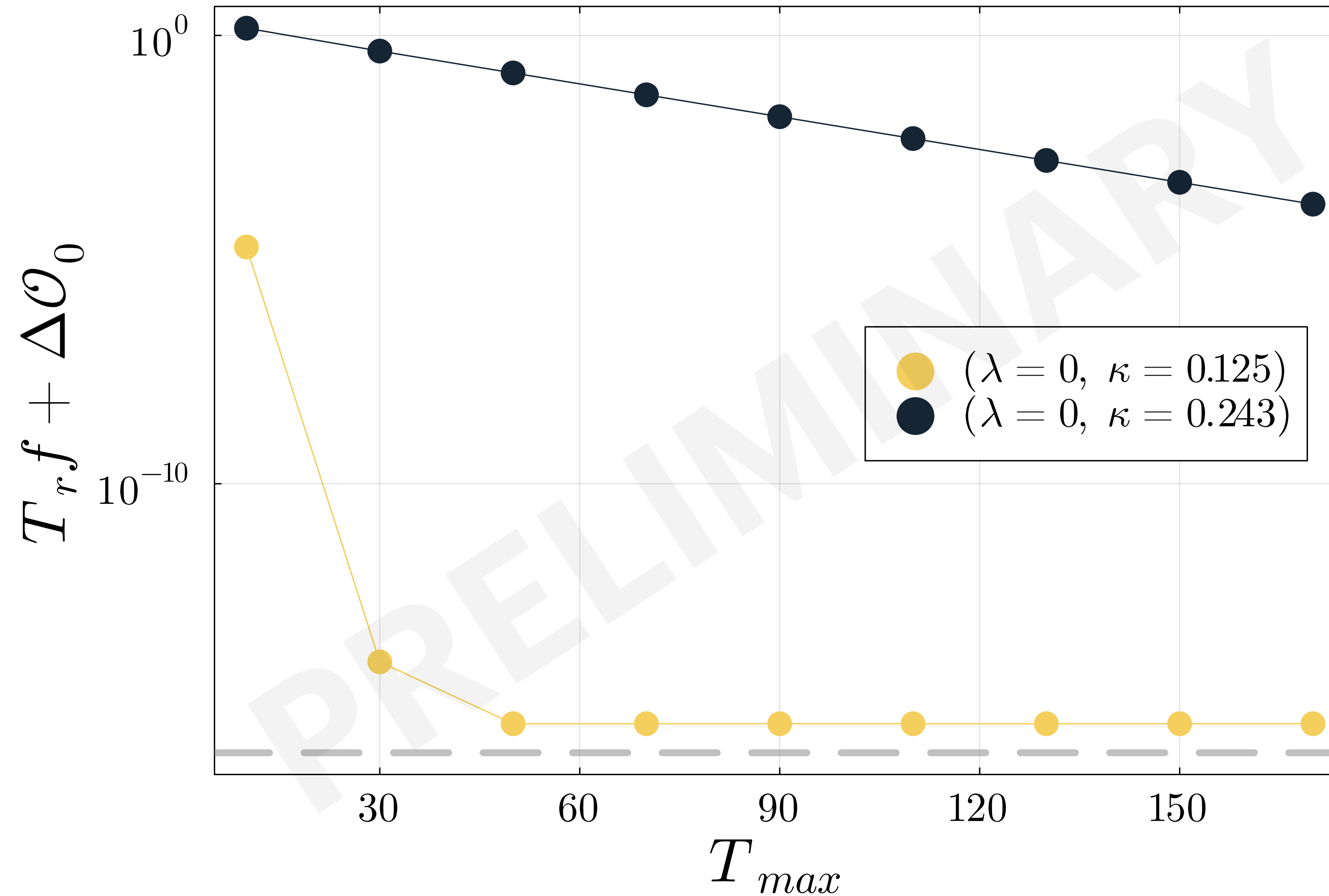
$$\frac{dA_{\tau}}{d\tau} = -H_S[Z_{t-\tau}]A_{\tau} + \delta_{x_0,0} \quad A_0 = 0$$

Works, but reproduce same hessian instabilities of HAD!

Convergence is increasingly harder towards critical points

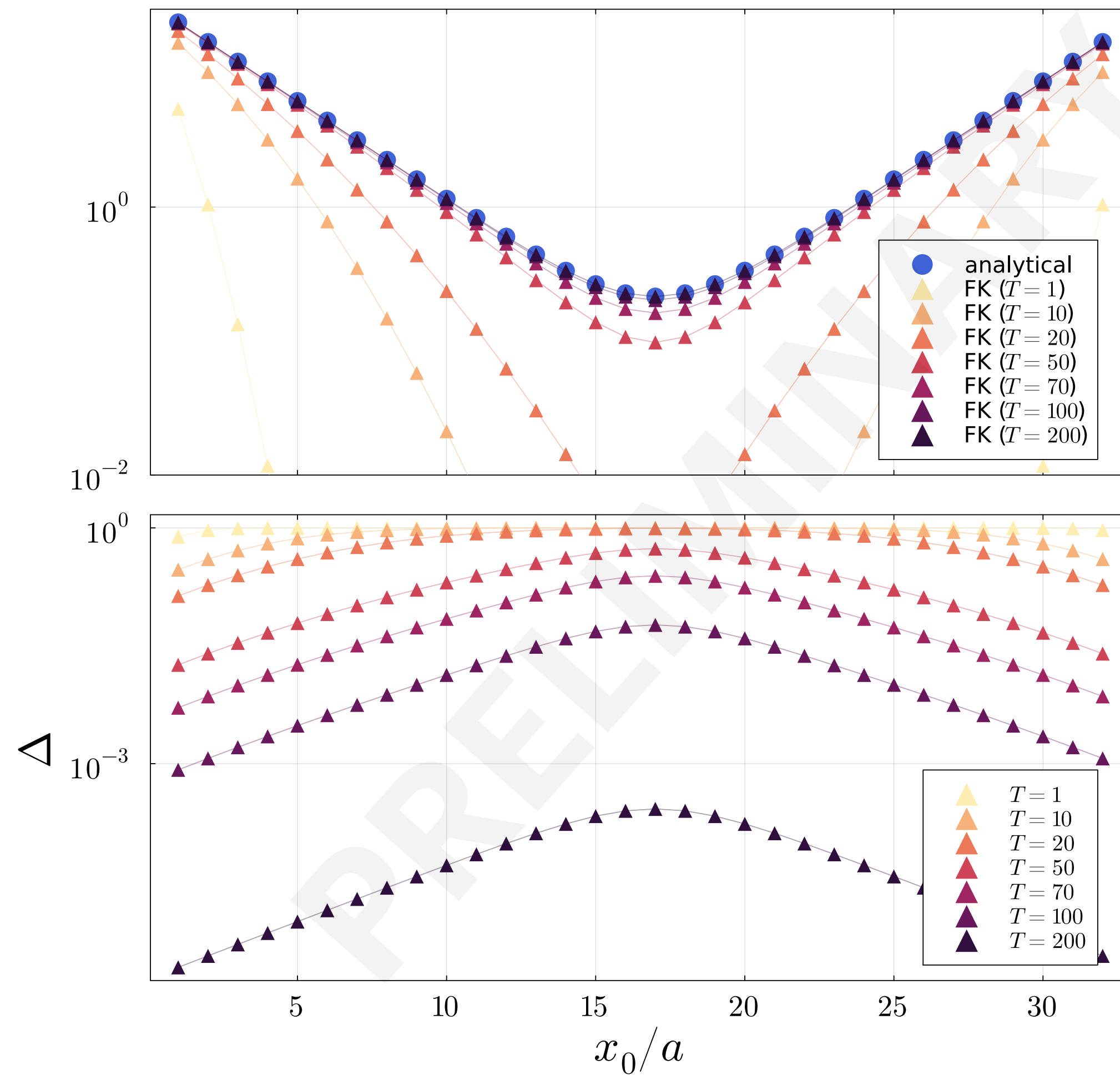
Free theory

$$f = \lim_{T \rightarrow \infty} \mathbb{E}[A_T(\phi)]$$

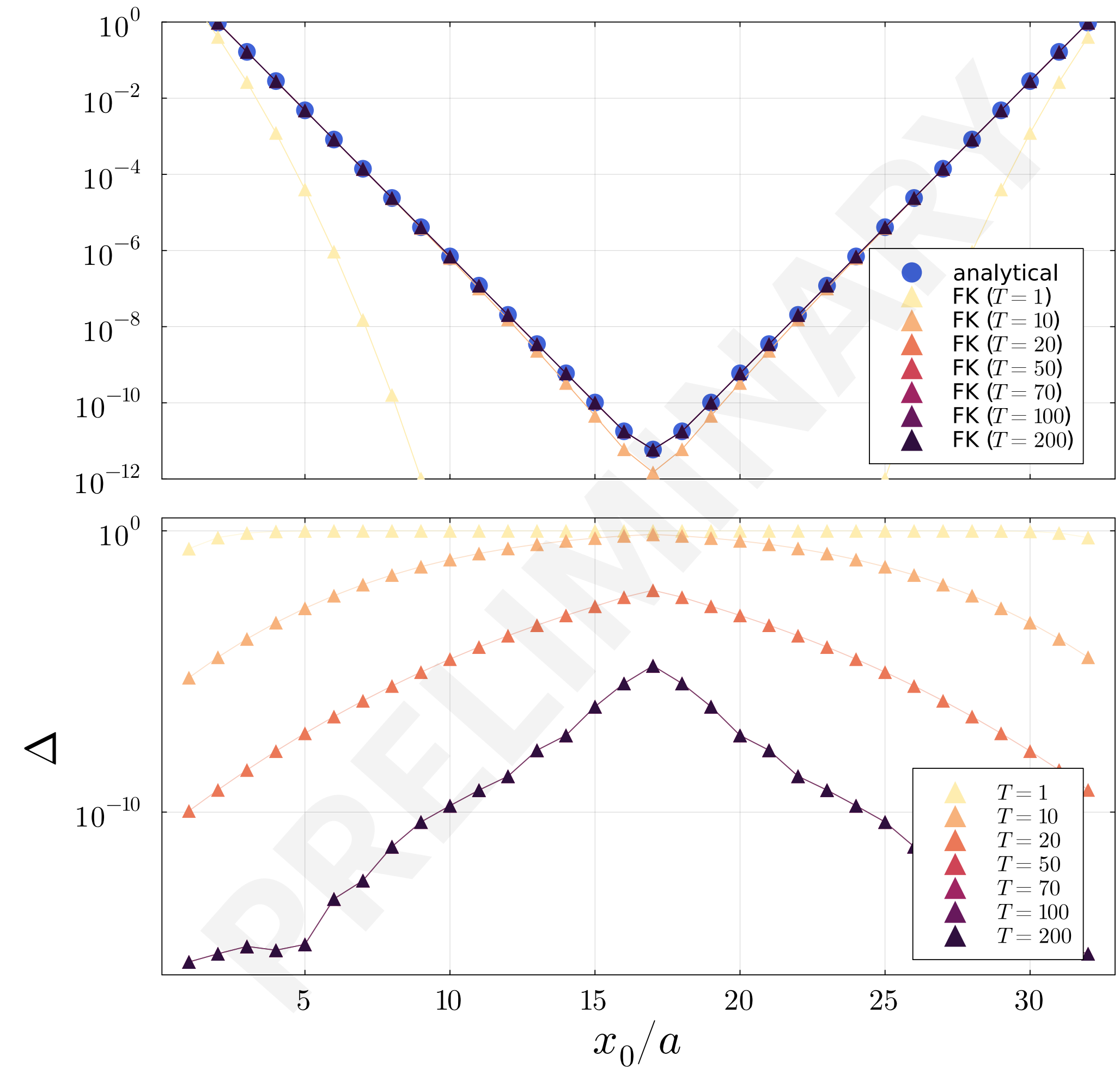


Free propagator

$L = 32 \times 8, \hat{\lambda} = 0.0, \hat{m}^2 = 0.1152$

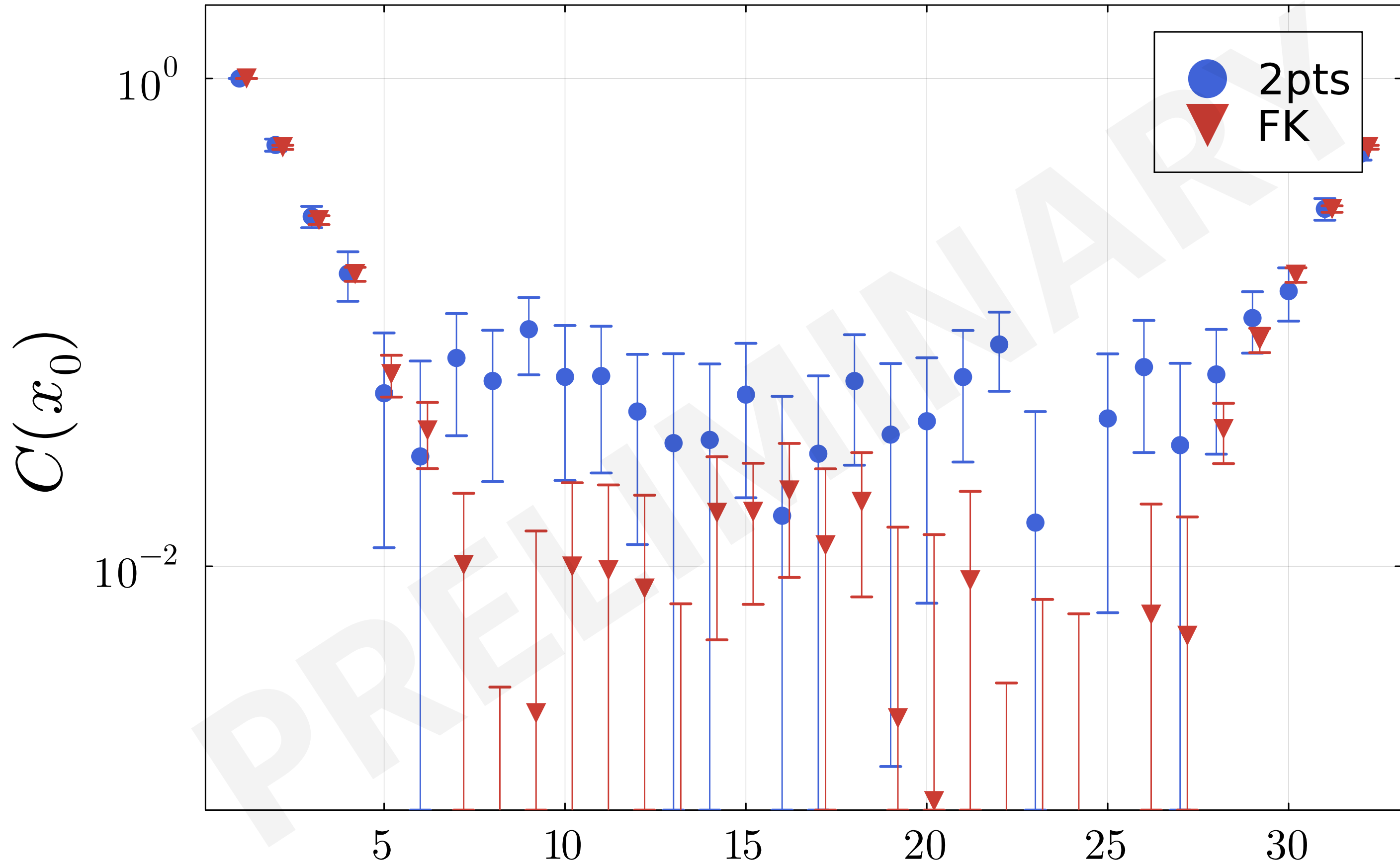


$L = 32 \times 8, \hat{\lambda} = 0.0, \hat{m}^2 = 4.025$



Correlator (close to criticality)

$$L = 32 \times 8, \lambda = 0.05, \kappa = 0.243$$



Thanks for the attention!



[Catumba, Ramos] - *"Stochastic automatic differentiation and the signal to noise problem"*, Eur.Phys.J.C 85 (2025)



[Liu, Wang] - *"Stein variational gradient descent: A general purpose bayesian inference algorithm"*, NeurIPS 29 (2016)



[Albergo, Kanwar] - *"A Monte Carlo estimator of flow fields for sampling and noise problems"*, PoS Lattice 2025



[Albergo, Eijnden] - *"NETS: A Non-Equilibrium Transport Sampler"*, e-Print: [2410.02711](https://arxiv.org/abs/2410.02711)



[Butti, Catumba, Nada, Spatscheck] - *in preparation*

BACKUP

Linearised flow maps

Target distribution
 $S - \varepsilon \mathcal{O}_0$

$q_\theta(\phi)$

$$\text{KL}(q||p) = \frac{\varepsilon^2}{2} \left\langle (\mathcal{T}_r f)^2 - 2f \cdot \nabla \mathcal{O}_0 \right\rangle + \dots$$

Minimise w/ variation calculus
 (write $f \rightarrow f + \delta f$ then set $\delta \text{KL} = 0$)

Infinitesimal transport
 $\phi \rightarrow \phi + \varepsilon f_\theta(\phi)$

S

Base distribution

$$\mathcal{T}_r f + \Delta \mathcal{O}_0 = 0 \quad \text{Stein-Poisson equation}$$

$$\Leftrightarrow \min_T \text{KL}(q||p_\varepsilon)$$

$$\mathcal{T}_r f = \nabla \cdot f - f \cdot \nabla S$$

Stein operator $\langle \mathcal{T}_r f \rangle \equiv 0$

$$\Delta \mathcal{O}_0 \equiv \mathcal{O}_0 - \langle \mathcal{O}_0 \rangle$$

field fluctuation at $t=0$

$$\phi \sim e^{-S}$$

Configurations

$$e^{-(S - J\mathcal{O}_0)}$$

Target distribution

Improved reweighting

What if I don't know the exact f ?

Transform samples before reweighting

$$\phi \longrightarrow \tilde{\phi} = \phi + \varepsilon f(\phi)$$

Importance weights becomes

$$w = \exp \left[-S_J[\tilde{\phi}] + S[\phi] + \log |1 + \varepsilon J_f| \right]$$

Find f that renders the (log-)weights constant!

$$\langle w \mathcal{O}_t \rangle_S$$

Some results (interacting theory)

$$\tilde{\phi}_p = \phi_p + \frac{1}{2} \frac{\delta(\vec{p})}{\hat{p}^2 + \hat{\Sigma}_\theta[\phi]} \varepsilon$$

Can we learn an *effective propagator* minimising the variance of the (log) weights?

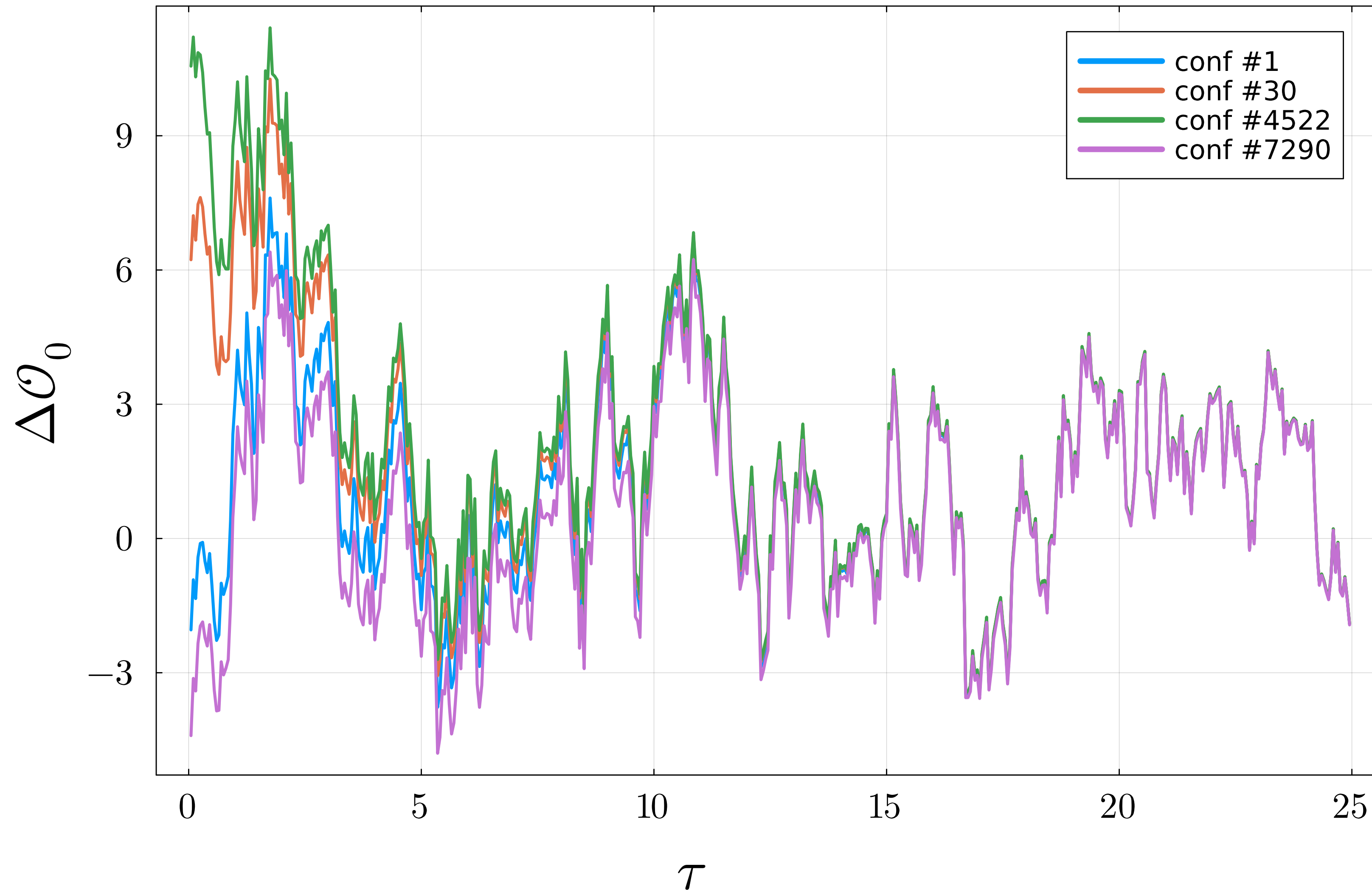
$$\log w = S[\phi] - S_J[\tilde{\phi}] + \log |1 + \varepsilon J_f|$$

Log-det computable with explicit differentiation + backprop

$$\log \det \left(1 + \varepsilon \frac{df}{d\phi} \right) = \varepsilon \operatorname{tr} \frac{df}{d\phi} + \mathcal{O}(\varepsilon^2)$$

How do we train $\hat{\Sigma}_\theta$?

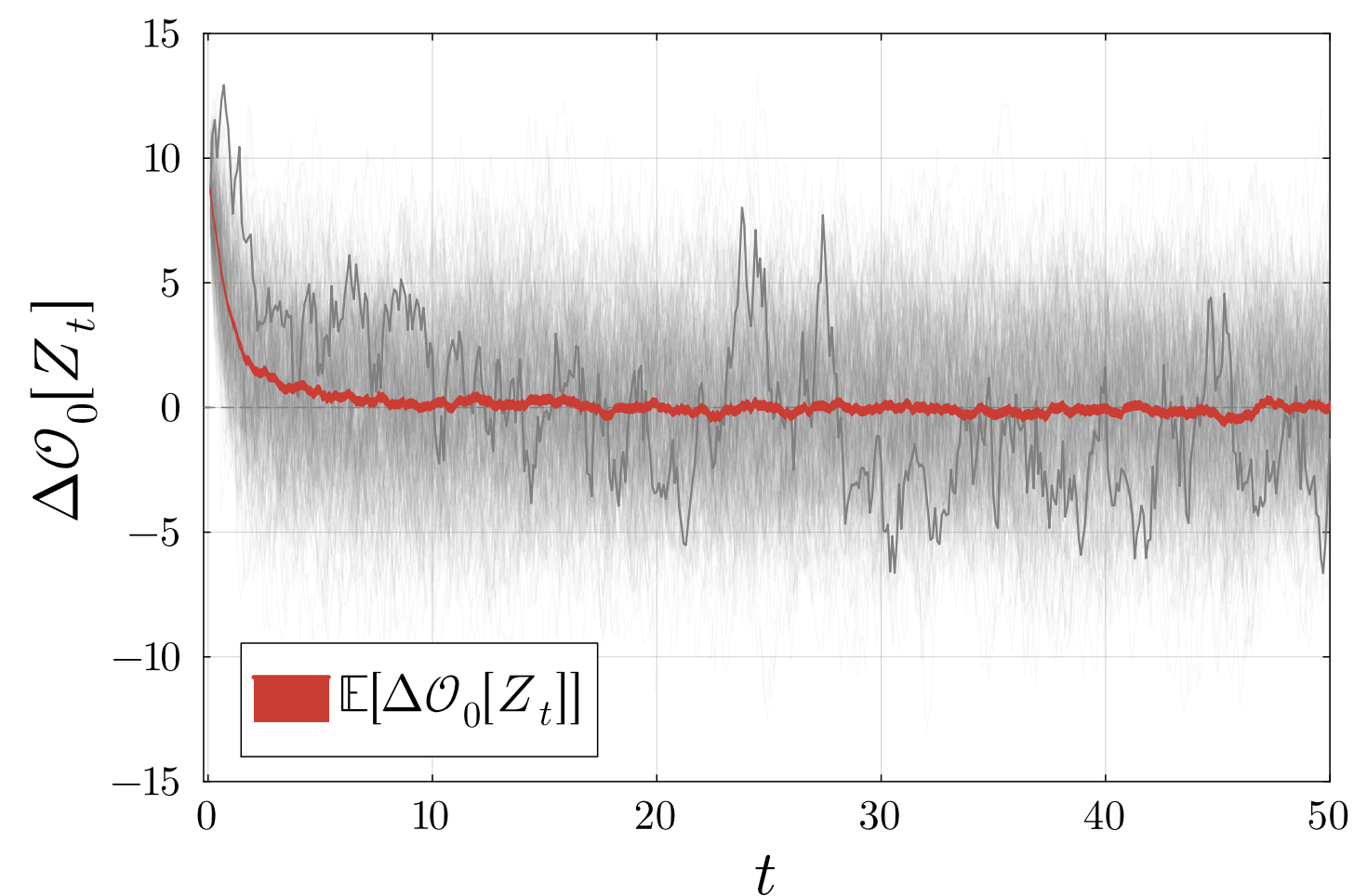
Maximally coupled noise



Feynman-Kac formula

$$\varphi(\phi) = \int_0^\infty d\tau \mathbb{E} \left[\mathcal{O}_0[Z_\tau] - \langle \mathcal{O}_0 \rangle \mid Z_0 = \phi \right]$$

Langevin evolution makes the integrand to converge to zero exponentially in τ



Free-field theory check $S = \phi K \phi$

Langevin dynamics = Ornstein-Uhlenbeck process

$$\mathbb{E}[Z_\tau | Z_0 = \phi] = e^{-K\tau} \phi$$

Feynman-Kac formula gives the \mathcal{O} -mom propagator

$$\varphi = \sum_{\vec{x}} K^{-1} \phi \quad f = \nabla \varphi = \sum_{\vec{x}} K^{-1}$$

Define Langevin autocorrelation function

$$\Gamma(\tau) = \left\langle \Delta \mathcal{O}_0[Z_\tau] \Delta \mathcal{O}_0[Z_0] \right\rangle_{Z_0 \sim r}$$

Green-Kubo relation:

$$\langle \varphi \Delta \mathcal{O}_0 \rangle = - \int_0^\infty d\tau \Gamma(\tau)$$

$$\varphi(\phi) = \int_0^\infty d\tau \mathbb{E} \left[\mathcal{O}_0[Z_\tau] - \langle \mathcal{O}_0 \rangle \mid Z_0 = \phi \right]$$

Feynman-Kac: numerical implementation

1. Select one sample ϕ . Compute HMC force ∇S

2. Integrate Langevin trajectory (EM scheme, with dt and T)

2.1 generate Gaussian noise upfront. `eps = randn(T//dt*size(phi))`

2.2 initial config: `Z[0]. = phi`

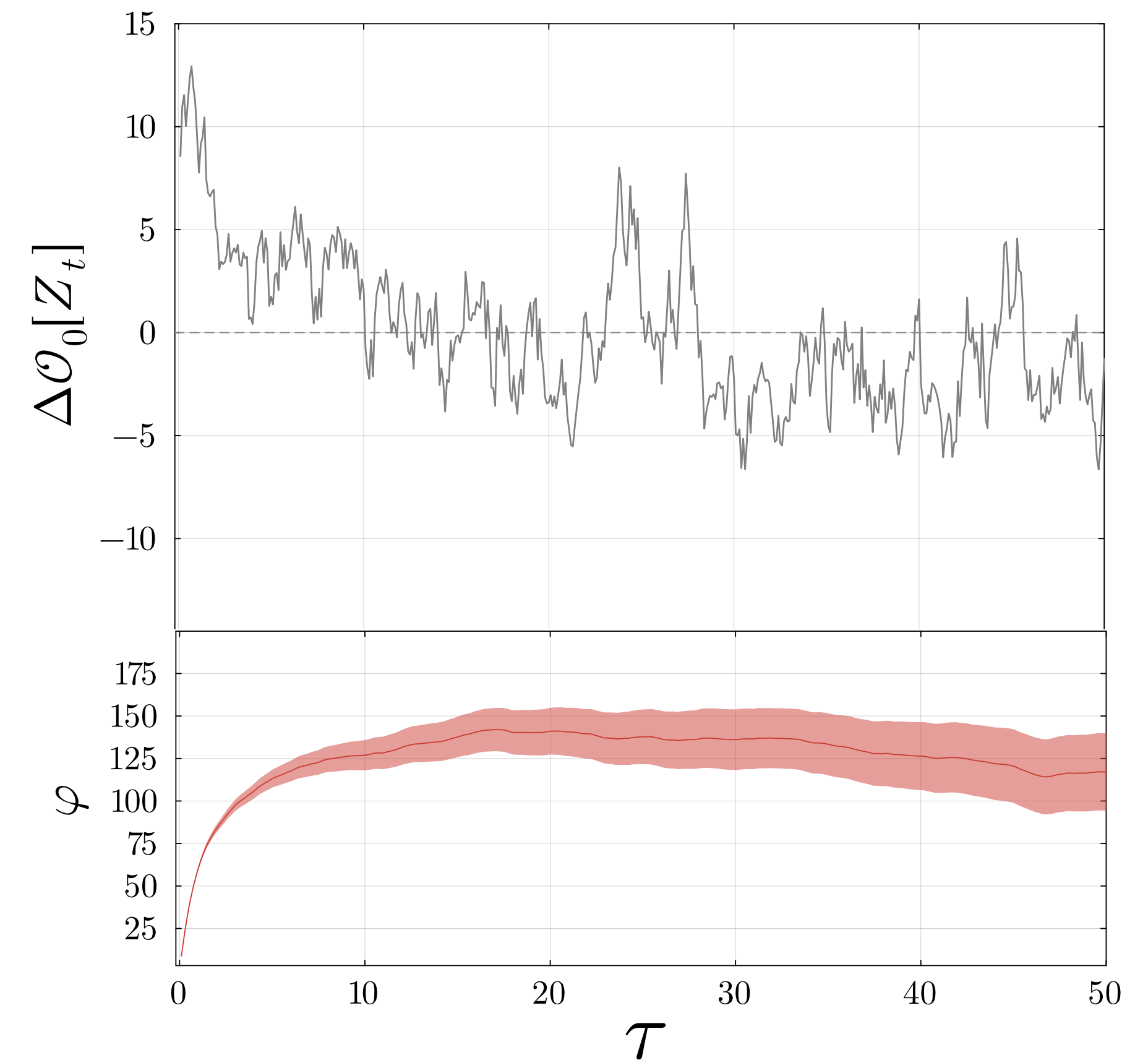
2.3 repeat: `Z[t+1] = Z[t] - \nabla S*dt + sqrt(2*dt)*eps[t]`

3. Repeat for N_w walkers

4. Compute integral (correlated cumulative sum in $[0, T]$)

5. Compute the gradient wrt the original conf

6. Repeat for all configurations



$$\varphi(\phi) = \int_0^\infty d\tau \mathbb{E} \left[\mathcal{O}_0[Z_\tau] - \langle \mathcal{O}_0 \rangle \mid Z_0 = \phi \right]$$

Feynman-Kac: numerical implementation

[Kanwar-Albergo] - hep-lat/2603.00252

1. Select one sample ϕ . Compute HMC force ∇S

2. Integrate Langevin trajectory (EM scheme, with dt and T)

2.1 generate Gaussian noise upfront. `eps = randn(T//dt*size(phi))`

2.2 initial config: `Z[0]. = phi, int=0.`

2.3 repeat: `Z[t+1] = Z[t] - \nabla S*dt + sqrt(2*dt)*eps[t]`

2.4 accumulate: `int += volume_sum(Z[t+1])`

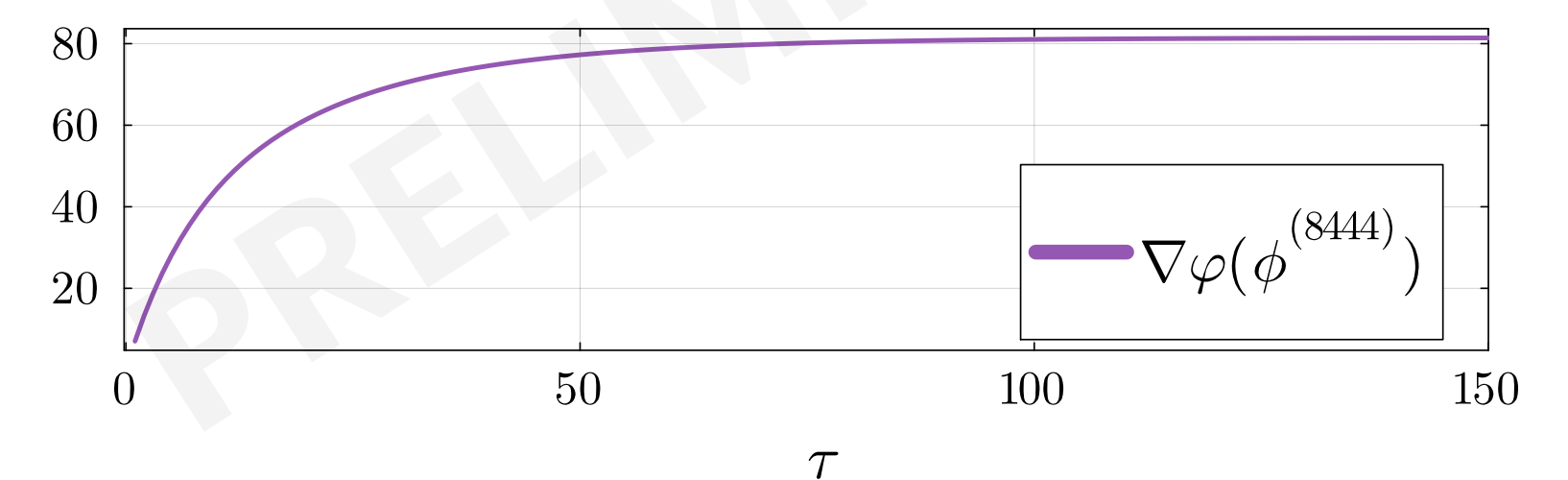
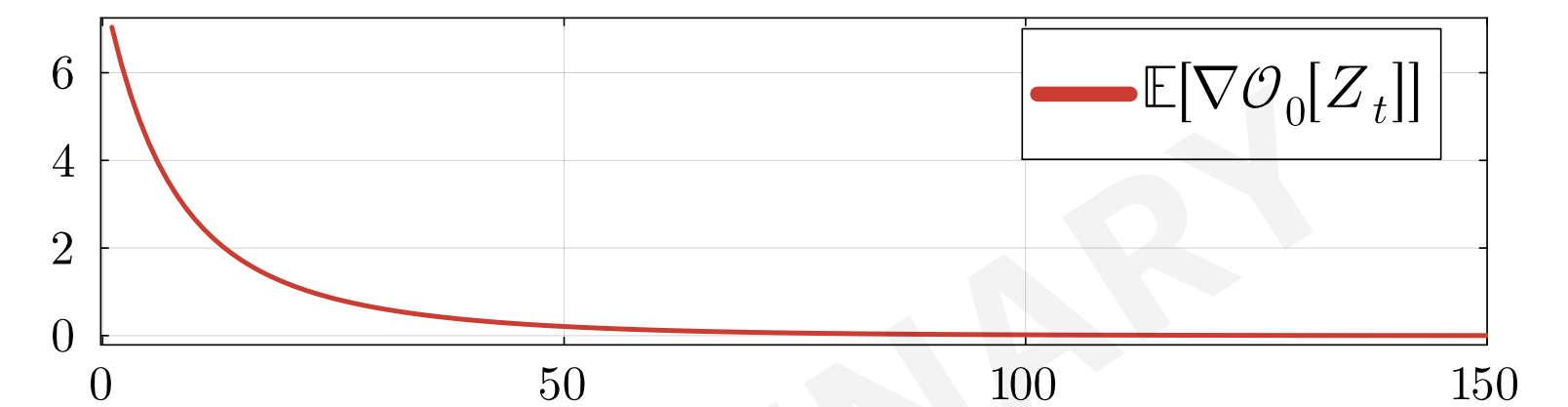
3. Compute $\hat{\varphi}^{[0,T]}$ for single walker

4. Compute gradient $\nabla \hat{\varphi}^{[0,T]}$ for a single walker *

5. Repeat for N_w walkers with coupled noise

6. Repeat for all configurations

$$f(\phi) = \mathbb{E} \left[\nabla \underbrace{\int_0^\infty dt \mathcal{O}_0[Z_t]}_{\hat{\varphi}^{[0,T]}} \right]$$



Improved reweighting

$$\phi \sim e^{-S}$$

Configurations

$$e^{-(S - J\mathcal{O}_0)}$$

Target distribution

Transform confs before reweighting

$$\phi \longrightarrow \tilde{\phi} = \phi + \varepsilon f(\phi)$$

Weights becomes

$$w = \exp \left[-S_J[\tilde{\phi}] + S[\phi] + \log |1 + \varepsilon J_f| \right]$$

Find f that renders the (log-)weights constant!

$$\langle w \mathcal{O}_t \rangle_S$$

Scalar free theory:

$$\phi_p \rightarrow \tilde{\phi}_p = \phi_p + \frac{1}{2} \frac{\delta(\vec{p})}{\hat{p}^2 + \hat{m}^2} \varepsilon$$

f independent of ϕ , weights are simply

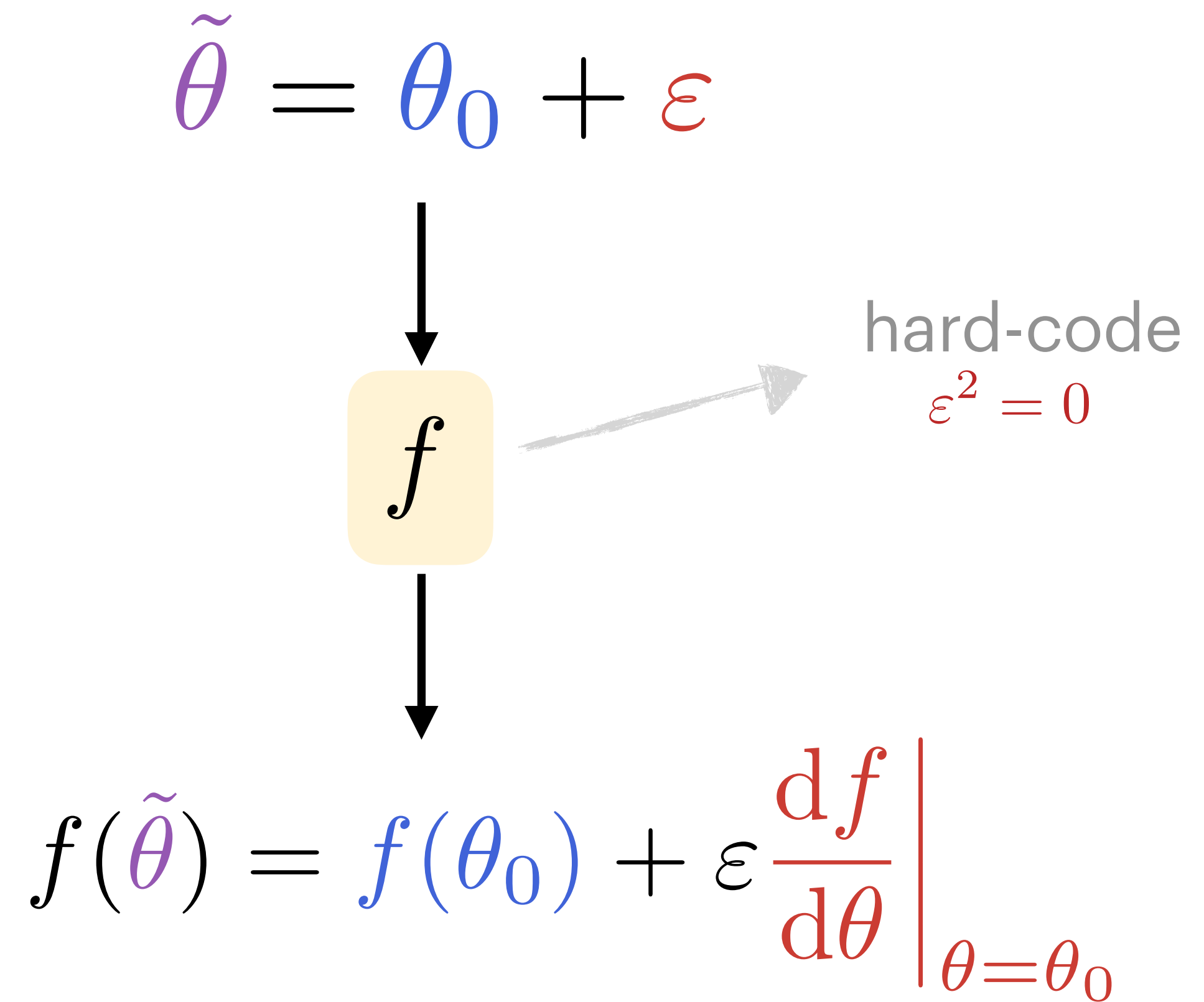
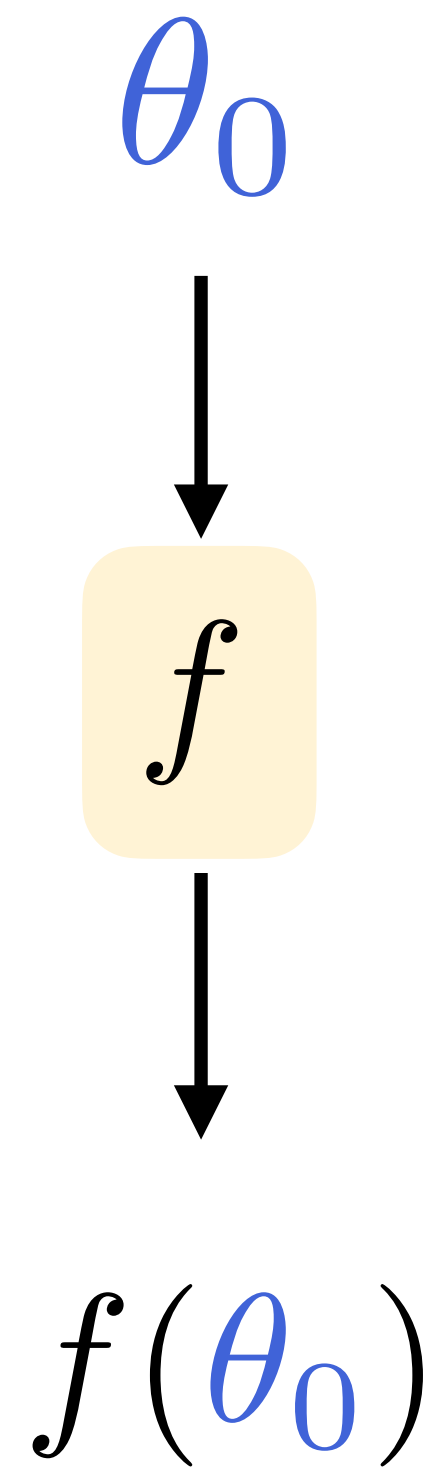
$$w = 1 + \varepsilon \left(\mathcal{O}_0 - f \cdot \nabla S \right) + \dots$$

The correlator gets a free control variate...

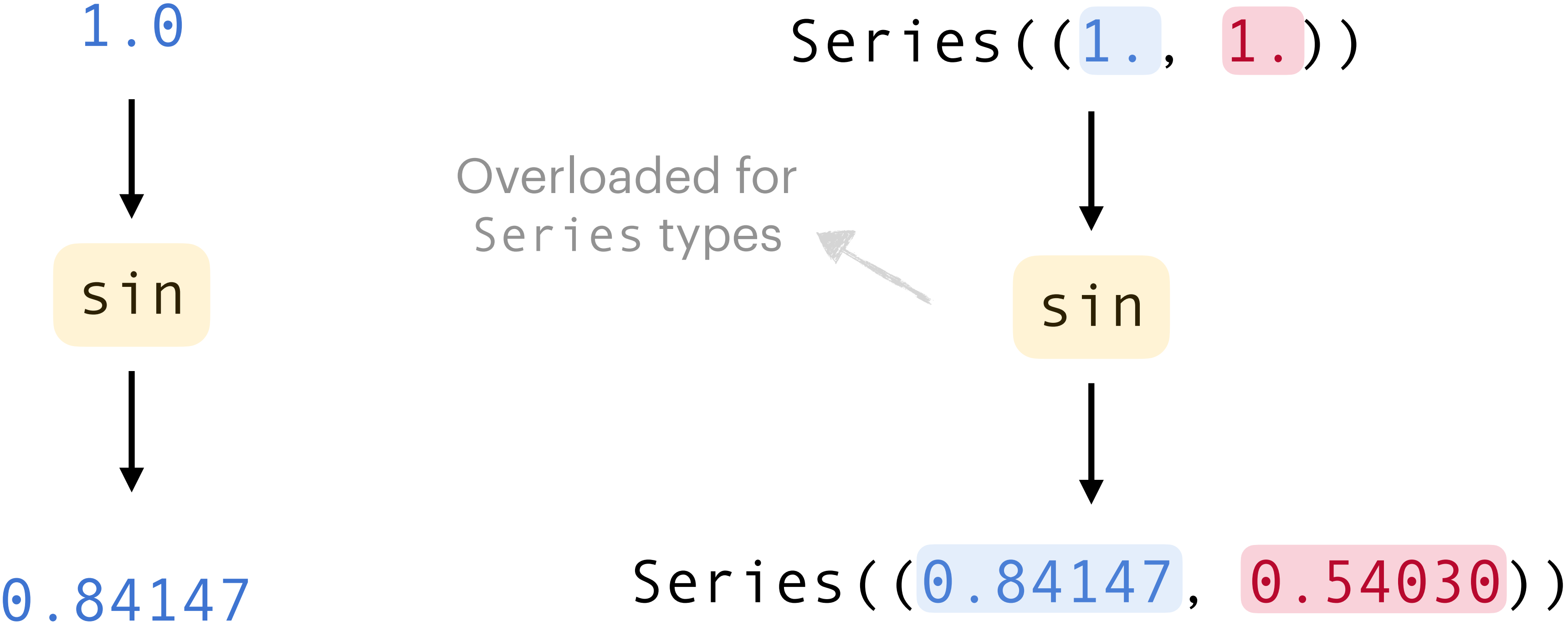
$$\langle w \mathcal{O}_t \rangle = \langle \mathcal{O}_t \rangle + \varepsilon \left[C(t) - \langle f \cdot \nabla (\mathcal{O}_t - S) \rangle \right]$$

zero on average but controls the variance!

(forward) Automatic Differentiation



(forward) Automatic Differentiation



(forward) Automatic Differentiation

MCMC samples with S_β

$\langle \mathcal{O} \rangle_{\beta_0} \{ \phi \}$

β'

weights

$$w \equiv e^{S_{\beta_0} - S_{\beta'}}$$

$$\langle \mathcal{O} \rangle_{\beta'} \equiv \frac{\langle w \mathcal{O} \rangle_{\beta_0}}{\langle w \rangle_{\beta_0}}$$

$\tilde{\beta}' = \beta_0 + \epsilon$

weights

$$e^{S_\beta - S_{\tilde{\beta}}} = 1 + (\dots)\epsilon$$

$$\frac{\langle e^{S_{\beta_0} - S_{\tilde{\beta}'}} \mathcal{O} \rangle}{\langle e^{S_{\beta_0} - S_{\tilde{\beta}'}} \rangle} = \langle \mathcal{O} \rangle + \epsilon \left. \frac{d}{d\beta} \right|_{\beta=\beta_0} \langle \mathcal{O} \rangle$$

(forward) Automatic Differentiation

MCMC samples with S

$\langle \mathcal{O} \rangle, \{\phi\}$

J

weights

$$w \equiv e^{S - (S - J\phi)}$$

$$\langle \mathcal{O} \rangle_J \equiv \frac{\langle w \mathcal{O} \rangle}{\langle w \rangle}$$

$\tilde{J} = 0 + \epsilon$

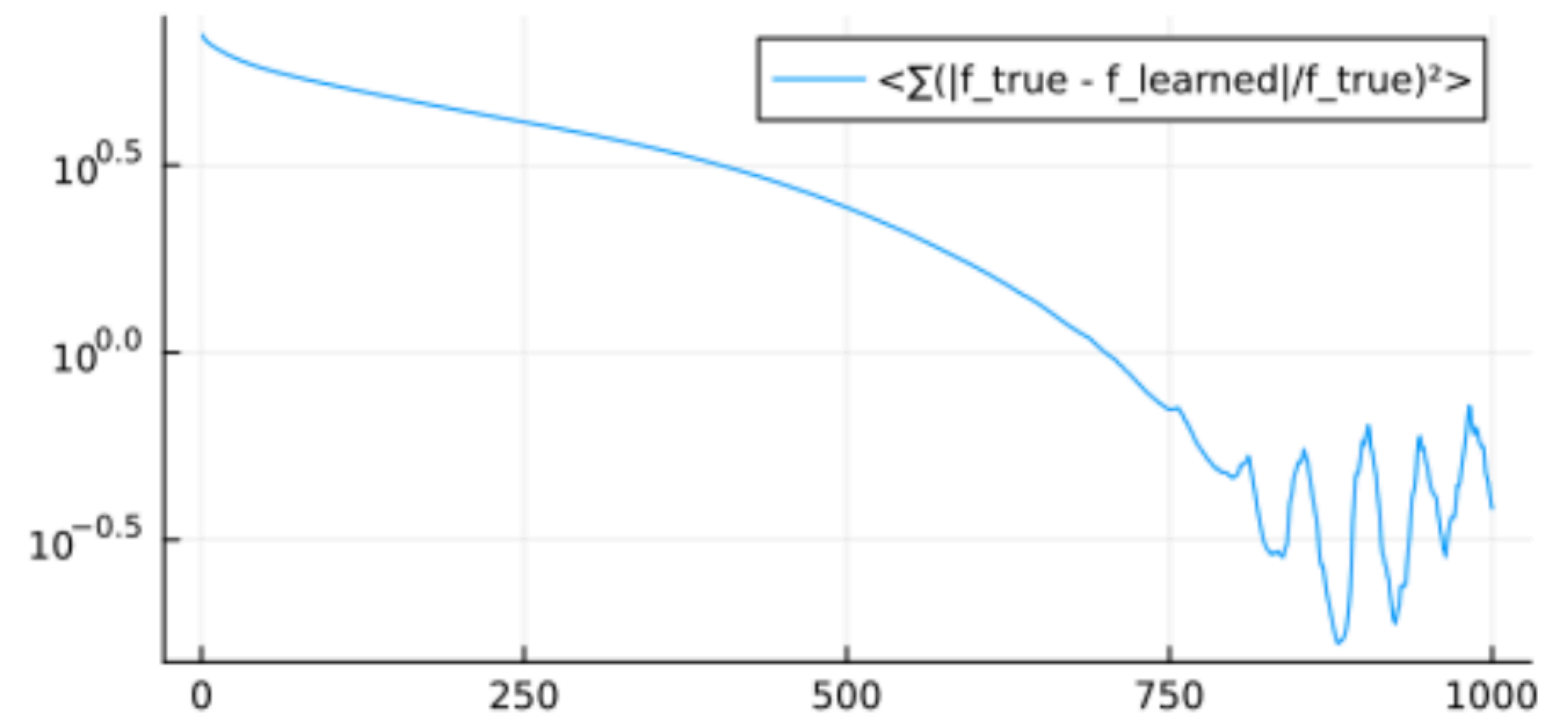
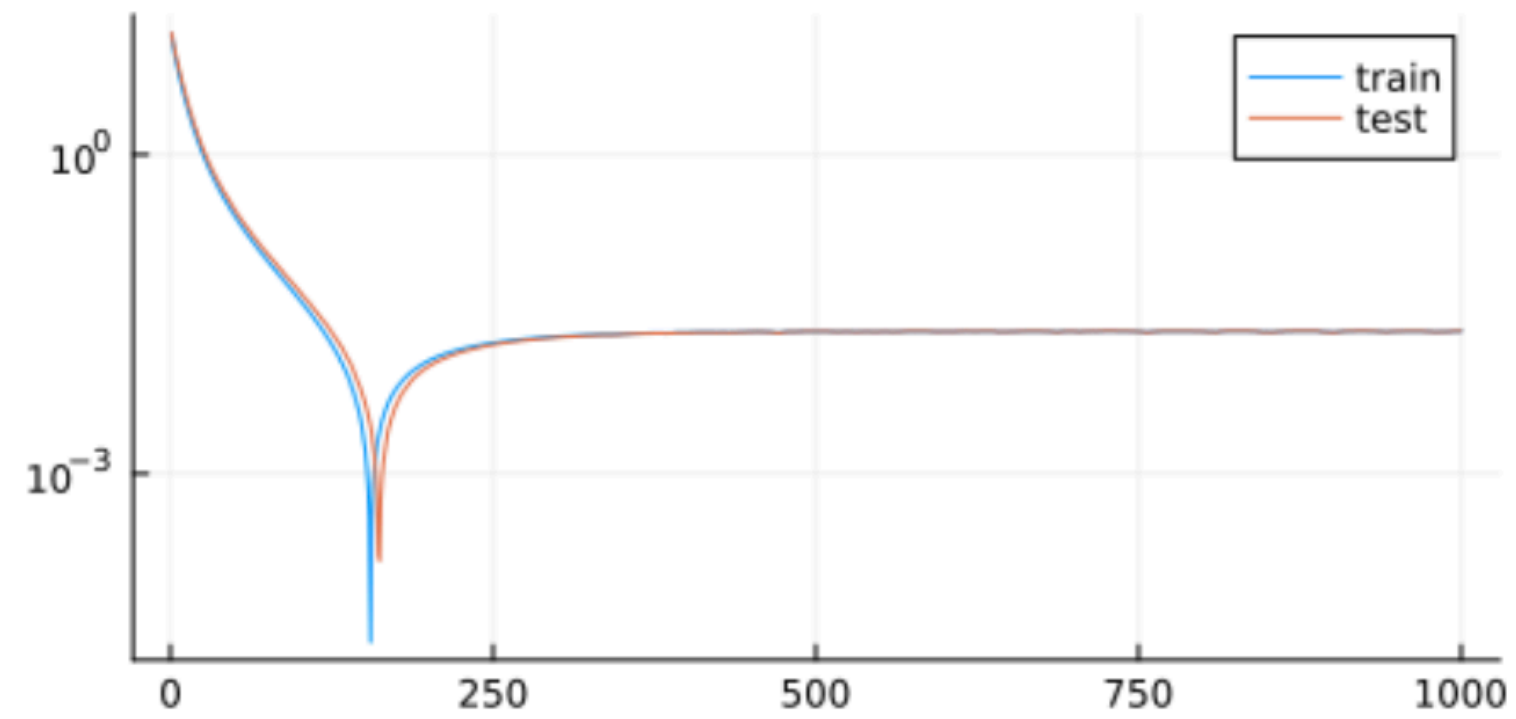
weights

$$e^{S - S\tilde{J}} = 1 + (\dots)\epsilon$$

$$\frac{\langle e^{S - S\tilde{J}} \mathcal{O} \rangle}{\langle e^{S - S\tilde{J}} \rangle} = \langle \mathcal{O} \rangle + \epsilon \left. \frac{d}{dJ} \right|_{J=0} \langle \mathcal{O} \rangle$$

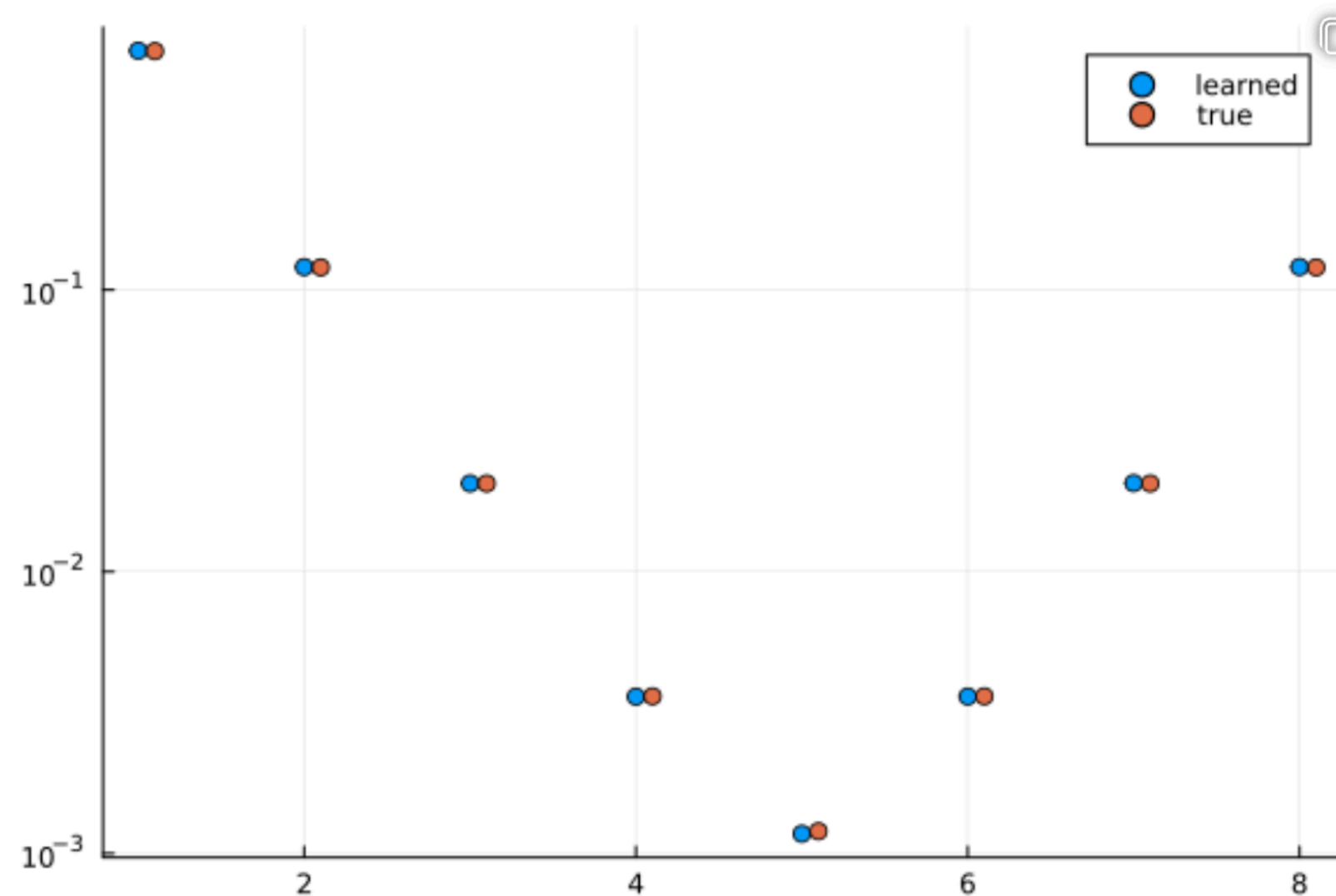
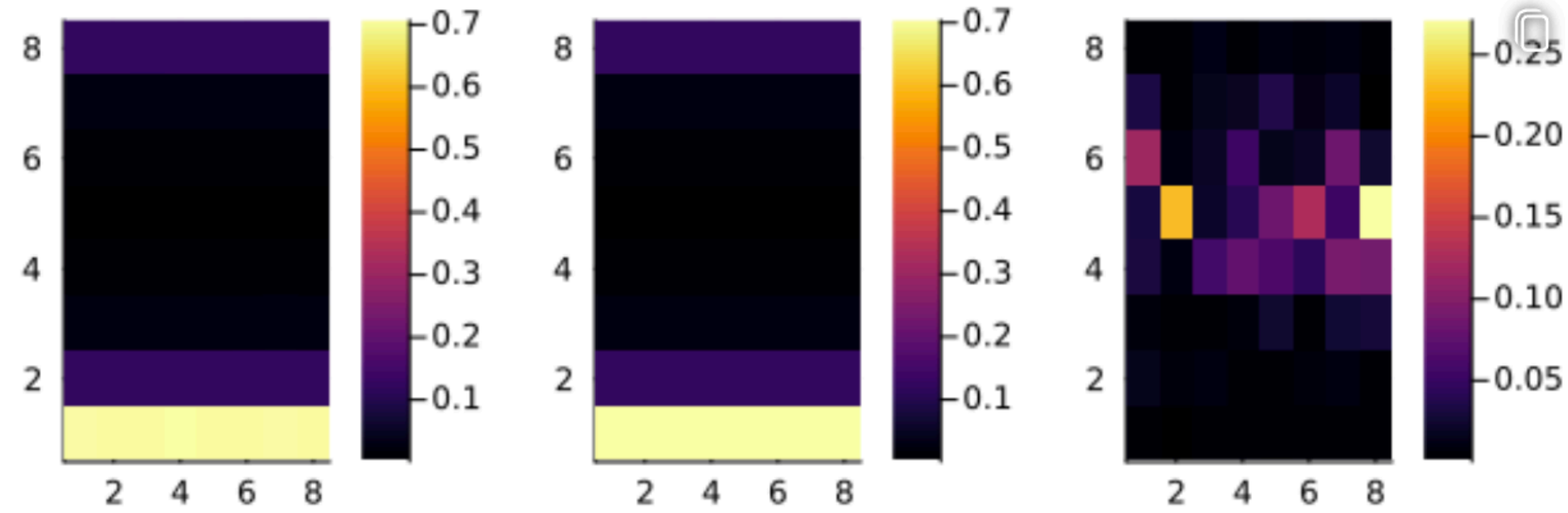
Some results

```
net(vol) = Chain(  
  FlattenLayer(),  
  Dense(prod(vol)=>prod(vol),σ),  
  ReshapeLayer((vol...,1))  
)
```



Vol: 8x8, 10K confs,
~30 sec

True - Learned =



Blue points have
error bars!!!

$$e^{-S}$$

Base distribution

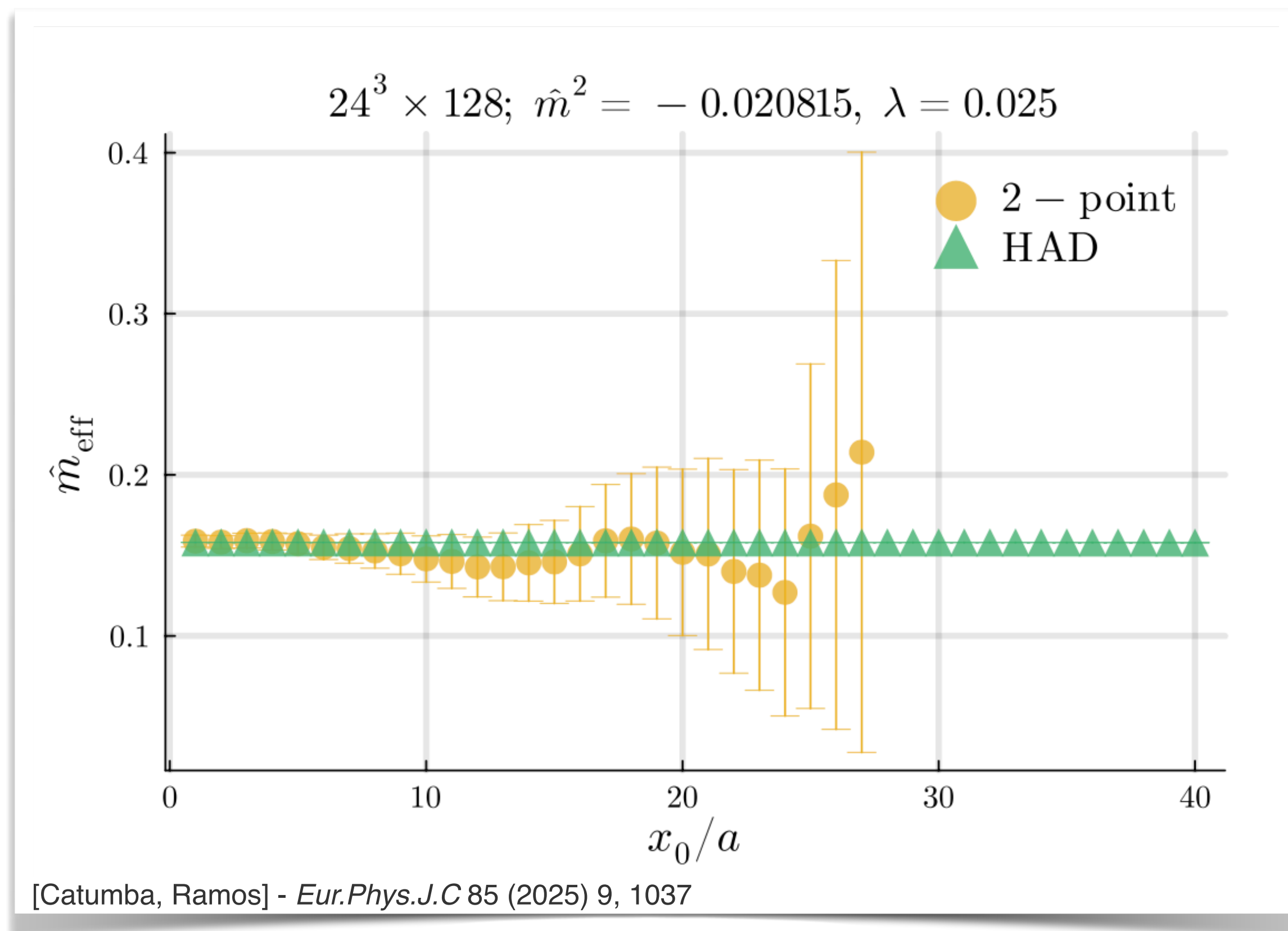
$$e^{-S+J\phi}$$

Target distribution

Stochastic (H)AD

[Catumba, Ramos] - *Eur.Phys.J.C* 85 (2025) 9, 1037

[Catumba, Ramos, Zaldivar] - *Comput.Phys.Commun.* 307 (2025) 109396



- Promote also fields and momenta to formal series

$$\phi \rightarrow \phi + \varepsilon \quad \pi \rightarrow \pi + \varepsilon$$

- Integrate HMC equations order by order

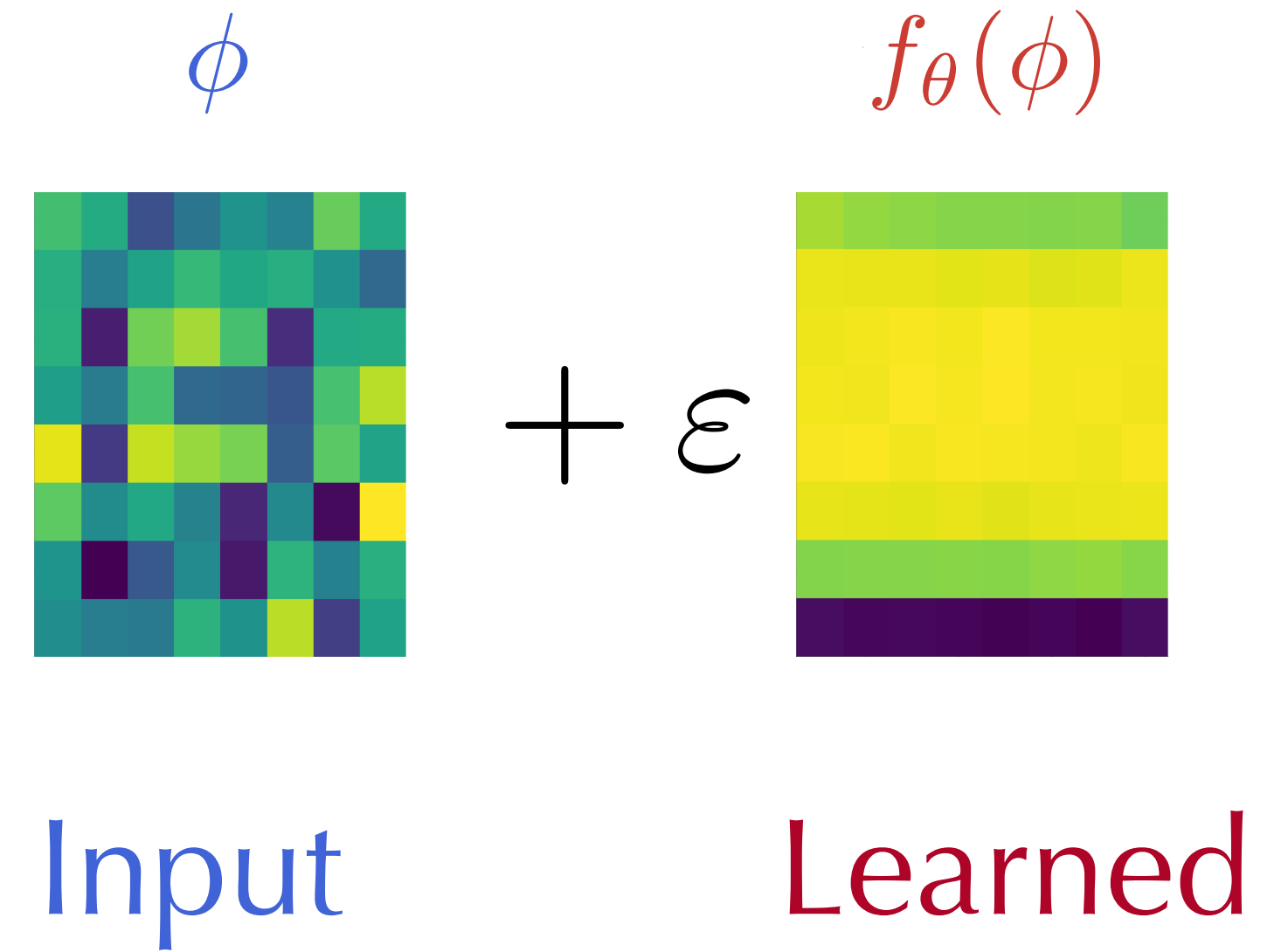
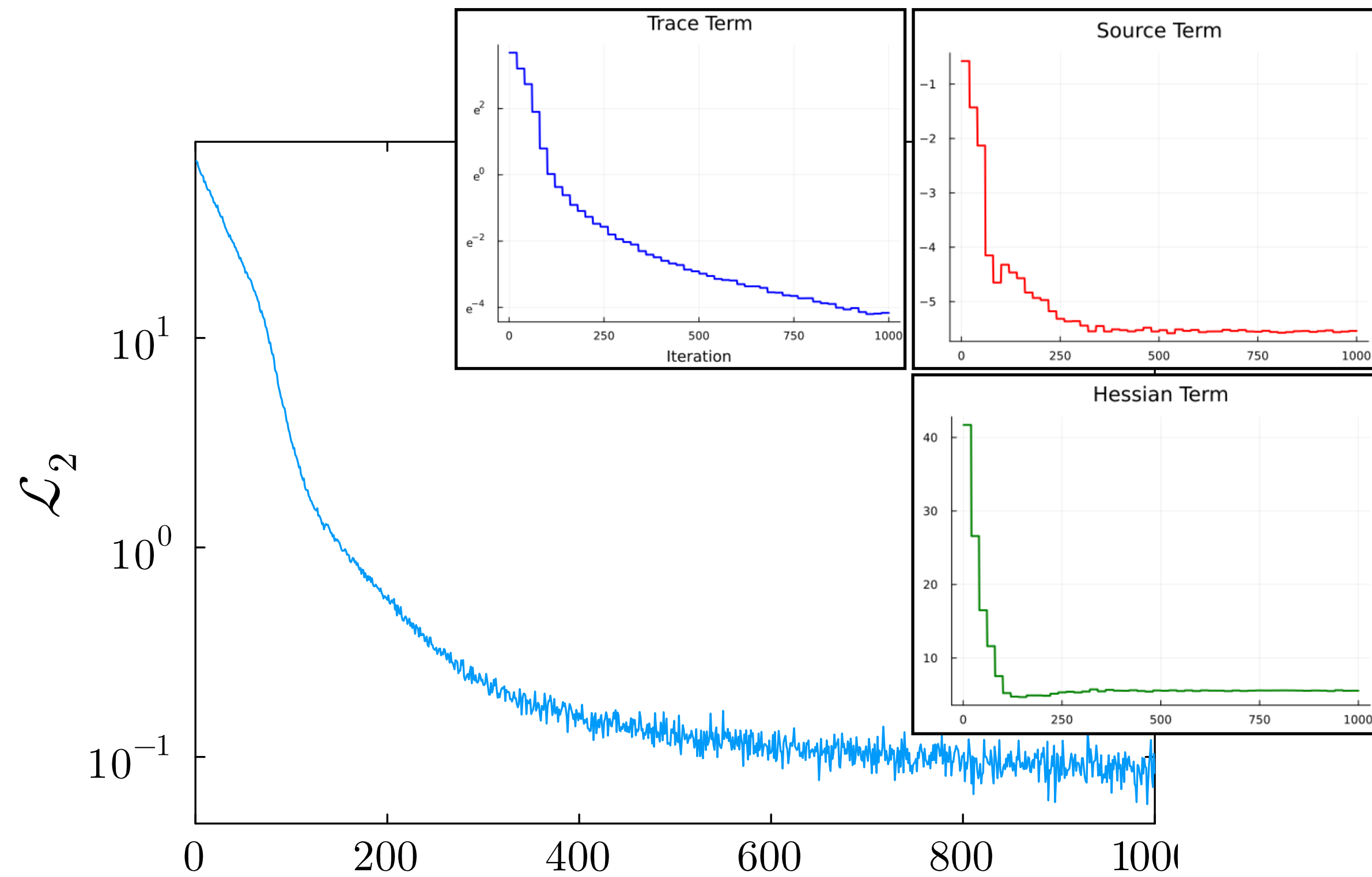
$$\dot{\phi} = \tilde{\pi} \quad \dot{\pi} = -\frac{\partial \tilde{S}_{\tilde{j}}}{\partial \tilde{\phi}}$$

- Samples now contains the dependence on the source

$$\tilde{\phi} = \phi_{\tau} + \phi_{\tau}^{(1)} \varepsilon$$

$$\mathcal{L}[f] = \mathbb{E}_r[f] + \frac{1}{2} \mathbb{E}_r \left[f^\perp H_S f + \|\nabla f\|_F^2 \right]$$

Some preliminary result



- The signal-to-noise degradation problem can be formulated as a **reweighing error** (overlap problem) in the computation of **derivatives of one-point functions**
- Stochastic Automatic Differentiation allows for the computation of **exact derivatives** of expectation values through reweighing with formal series
- A residual transformation of the configurations allows for systematic improvement of the signal-to-noise ratio in scalar theories
- Linear flows naturally frames the improvement procedure within a geometrical picture in the context of transport maps

Automatic Differentiation

- Extend parameters to power series at $\mathcal{O}(\varepsilon^N)$

$$\tilde{x} = x_0 + x_1\varepsilon + x_2\varepsilon^2$$

- Hard-code every elementary operation

$$\tilde{x}\tilde{y} = x_0y_0 + (x_0y_1 + x_1y_0)\varepsilon + (x_0y_2 + x_1y_1 + x_2y_0)\varepsilon^2$$

$$\exp(\tilde{x}) = e^{x_0} + e^{x_0}x_1\varepsilon + e^{x_0}\left(\frac{x_1^2}{2} + x_2\right)\varepsilon^2$$

$$\sin(\tilde{x}) = \dots$$

- Exact derivatives of any function f at x_0 are given by Taylor's theorem

$$f(x_0 + \varepsilon) = f(x_0) + f'(x_0)\varepsilon + \frac{1}{2}f''(x_0)\varepsilon^2$$

$$f(0 + \varepsilon) = \frac{1}{1 - \varepsilon} = 1 + \varepsilon + \varepsilon^2$$

```
julia> using FormalSeries
julia> f(x) = 1/(1-x)
julia> f(0.)
1.0
julia> x̃ = Series((1., 1.))
Series{Float64,2}((1.0,1.0))
julia> f(x̃)
Series{Float64,2}((1.0,1.0))
```


- The signal-to-noise degradation problem can be formulated as a **reweighing error** (overlap problem) in the computation of **derivatives of one-point functions**
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