

# Stratifying On-Shell Cluster Varieties

Jacob L. Bourjaily  
Niels Bohr Institute

based on work in collaboration with

S. Franco, D. Galloni, and C. Wen;

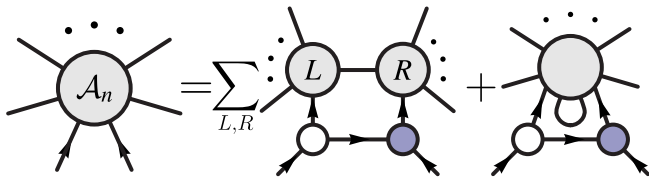
E. Herrmann, C. Langer, A. McLeod, and J. Trnka;

N. Arkani-Hamed, F. Cachazo, A. Goncharov, A. Postnikov, and J. Trnka

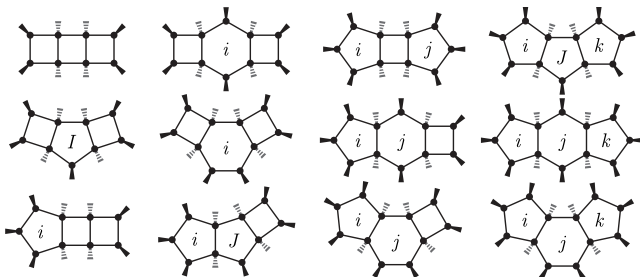
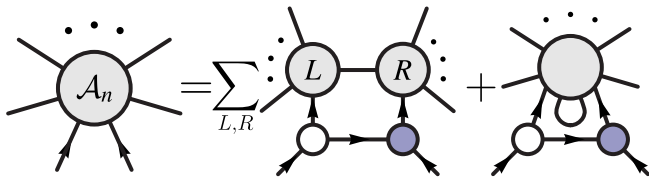
[arXiv:1911.09106] [arXiv:1909.09131] [arXiv:1608.00006] [arXiv:1412.8475] [arXiv:1212.5605]

# Enormous Advances in Understanding Scattering Amplitudes

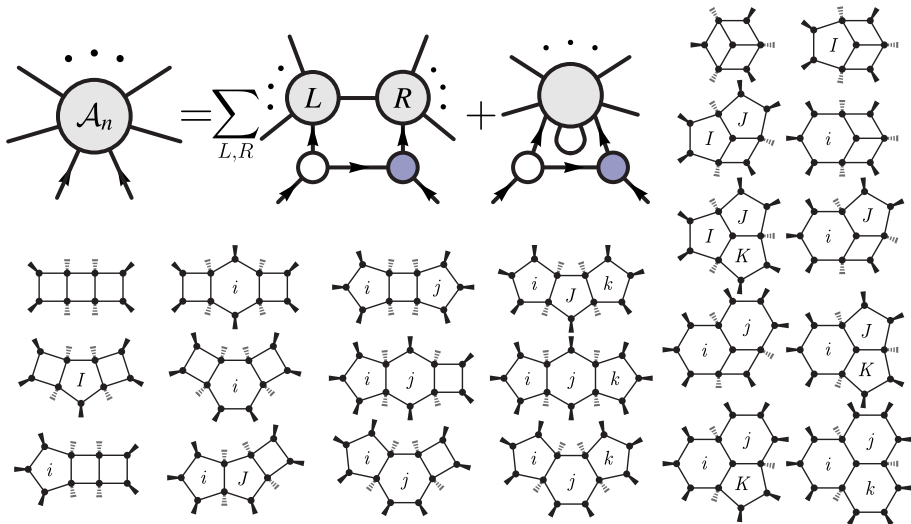
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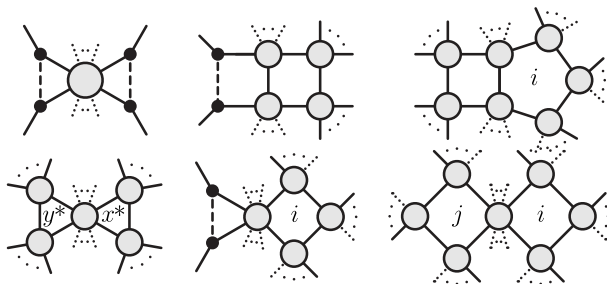
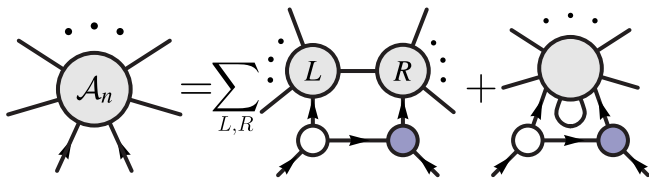
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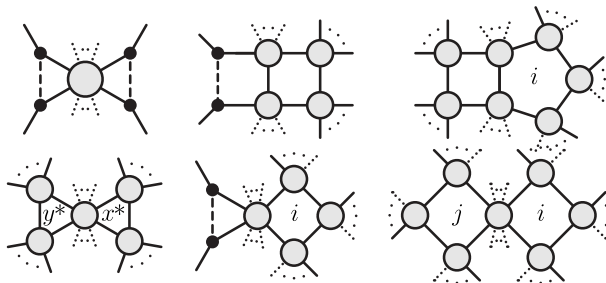
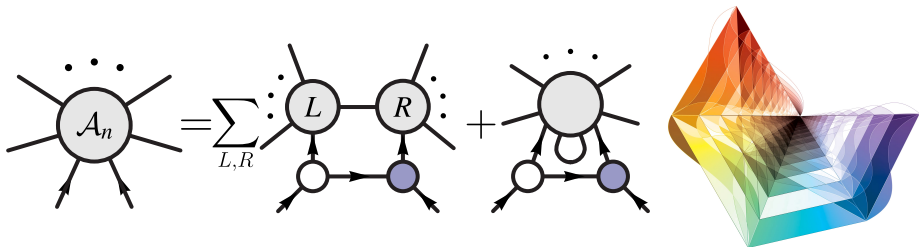
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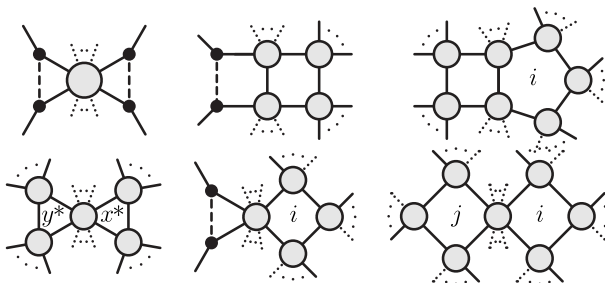
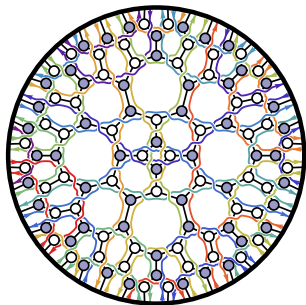
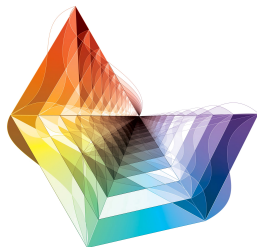
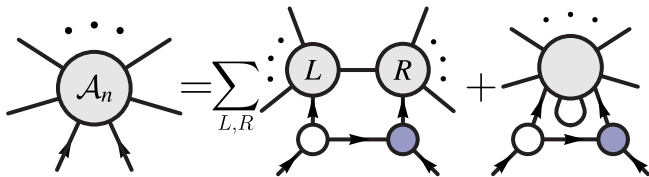
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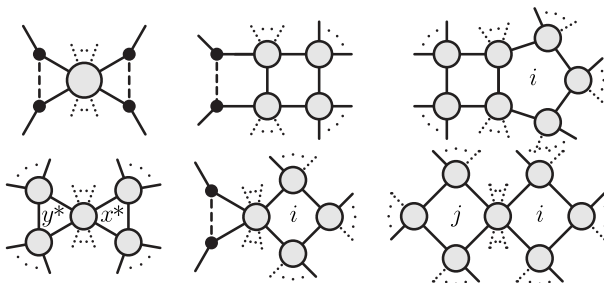
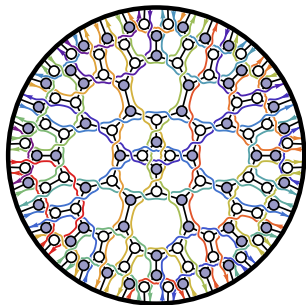
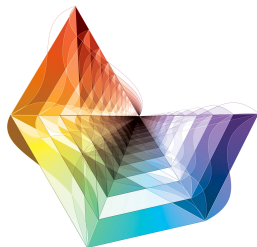
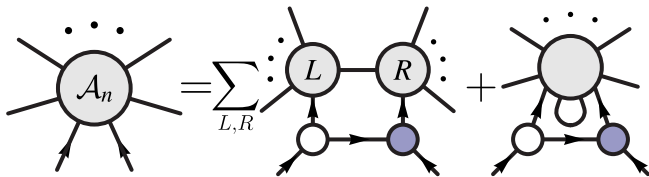


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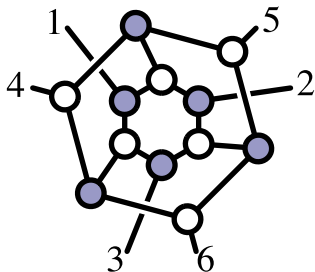


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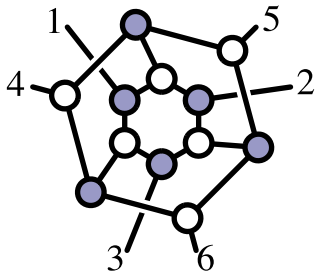
# On-Shell Physics/Grassmannian Geometry Correspondence

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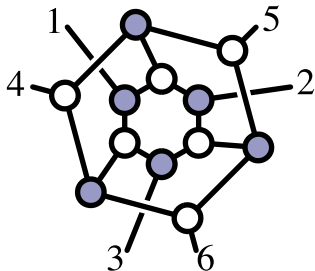
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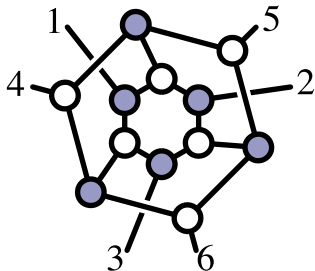
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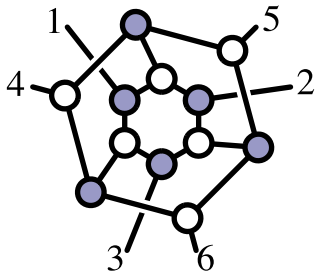
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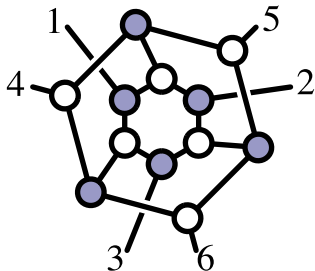
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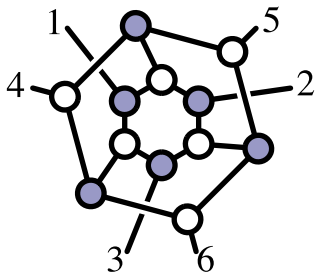
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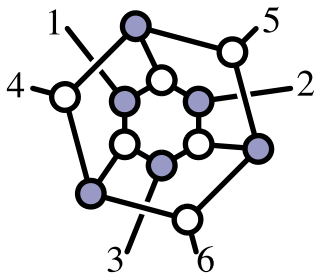
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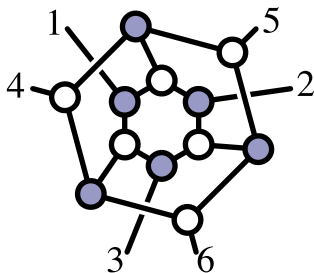
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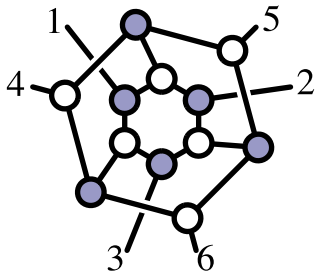
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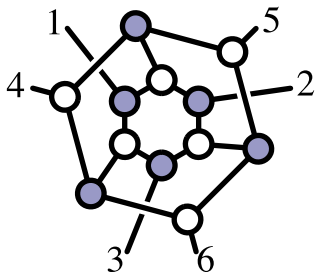
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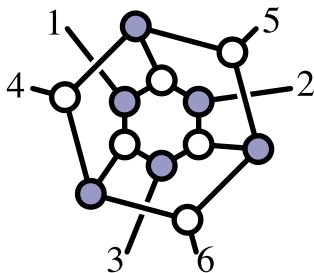
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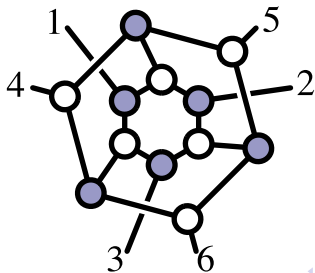
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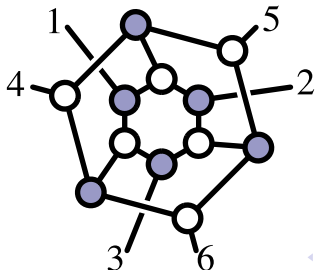
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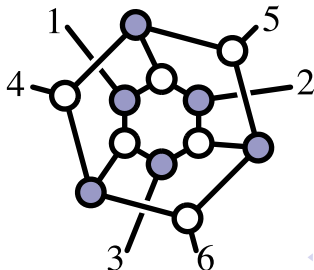
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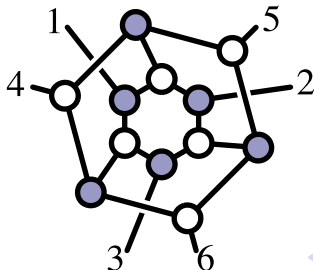
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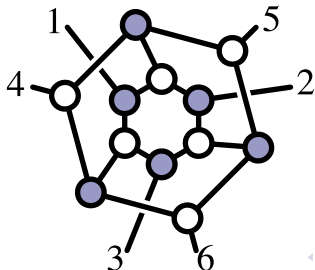
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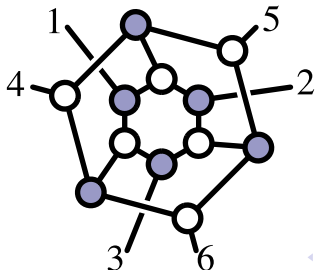
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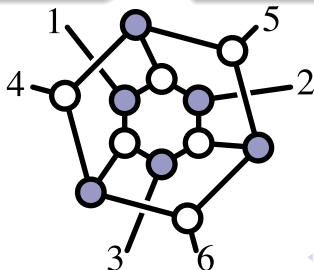


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On-Shell Physics

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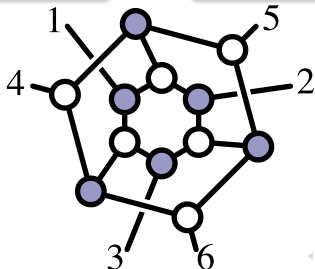
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## On-Shell Physics

- on-shell diagrams

## Grassmannian Geometry



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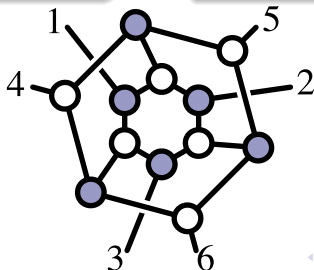
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- {strata  $C \in G(k, n)$ , volume-form  $\Omega_C$ }



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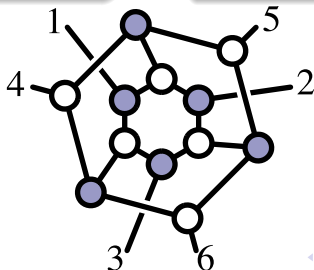
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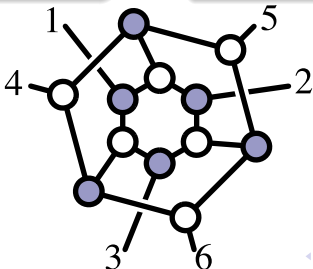
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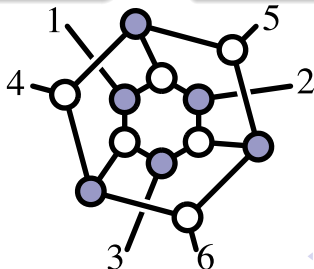
## On-Shell Physics

- on-shell diagrams
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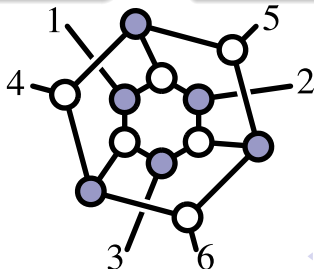
## On-Shell Physics

- on-shell diagrams
- physical symmetries
  - trivial symmetries (identities)



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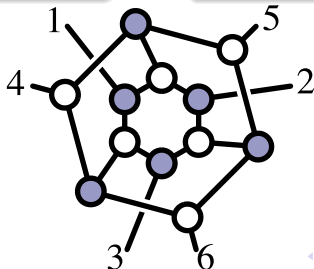
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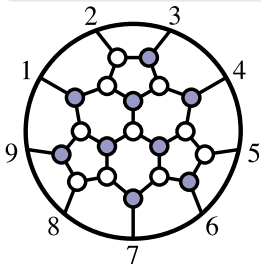
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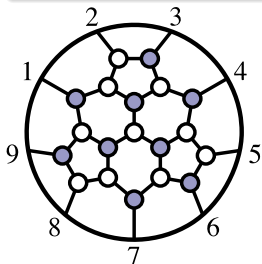
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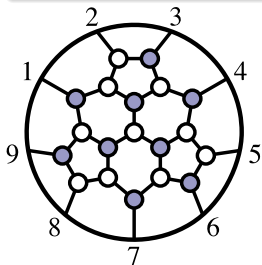
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  - bi-colored, **undirected**
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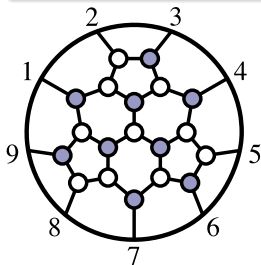
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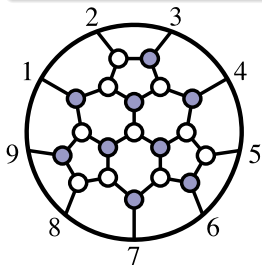
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$$C \equiv \begin{pmatrix} 1 & \alpha_8 & \alpha_5 + \alpha_8 \alpha_{14} & \alpha_5 \alpha_{11} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & \alpha_{10} & \alpha_4 + \alpha_{10} \alpha_{13} & \alpha_4 \alpha_7 & 0 & 0 \\ \alpha_3 \alpha_9 & 0 & 0 & 0 & 0 & 0 & 1 & \alpha_6 & \alpha_3 + \alpha_6 \alpha_{12} \\ \alpha_9 & 0 & \alpha_1 & \alpha_1 \alpha_{11} & 0 & \alpha_1 \alpha_2 & \alpha_1 \alpha_2 \alpha_7 & 0 & 1 \end{pmatrix}$$

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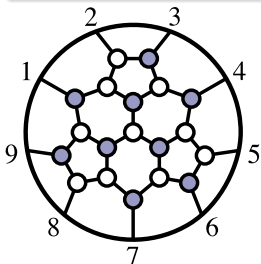
## On-Shell Physics: planar $\mathcal{N}=4$

- on-shell diagrams
  - bi-colored, **undirected**, **planar**
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  - trivial symmetries (identities)



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- {strata  $C \in G(k, n)$ , volume-form  $\Omega_C$ }
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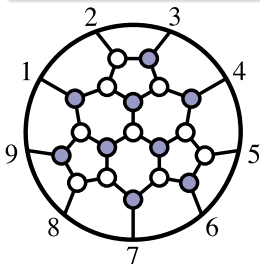
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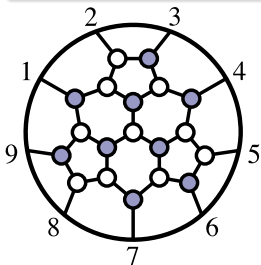
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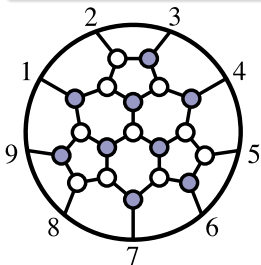
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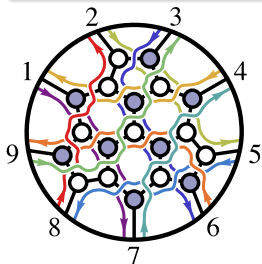
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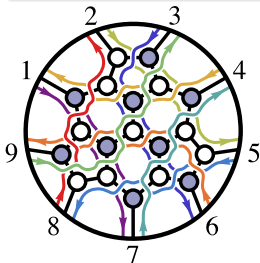
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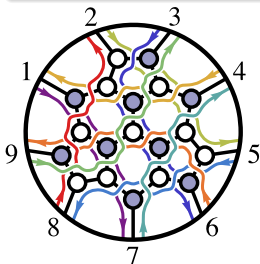
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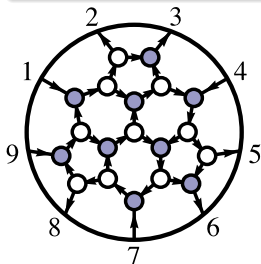
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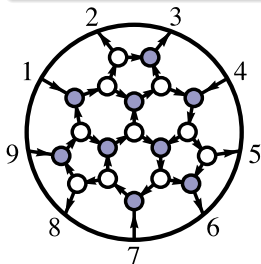
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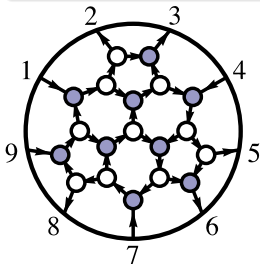
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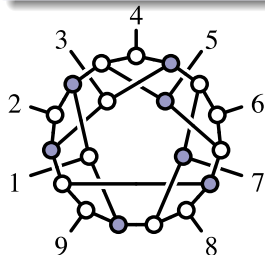
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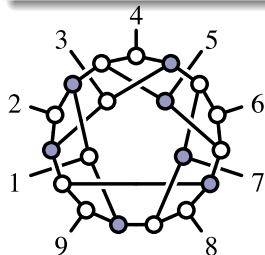
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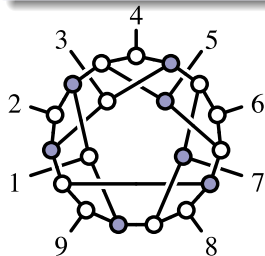
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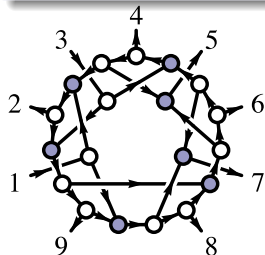
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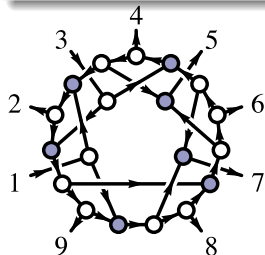


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$$C^{\perp} \equiv \begin{pmatrix} \alpha_1 & 1 & 0 & \alpha_2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \alpha_3 & 1 & 0 & \alpha_4 & 0 & 0 & 0 \\ 0 & 0 & 0 & \alpha_5 & 1 & \alpha_6 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & \alpha_7 & \alpha_8 \\ 0 & 0 & 0 & 0 & 0 & \alpha_9 & 1 & \alpha_{10} & 0 \\ \alpha_{11} & 0 & 0 & 0 & 0 & 0 & 0 & 1 & \alpha_{12} \\ 0 & \alpha_{13} & \alpha_{14} & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\Omega_C \equiv \left( \frac{d\alpha_1}{\alpha_1} \wedge \dots \wedge \frac{d\alpha_{14}}{\alpha_{14}} \right) \times \left( 1 + \alpha_2 \alpha_4 \alpha_{13} (\alpha_8 + \alpha_7 \alpha_{12}) \right)^{\mathcal{N}-4}$$

## Grassmannian Geometry

- {strata  $C \in G(k, n)$ , volume-form  $\Omega_C$ }
  - cluster variety(?),  $(\prod_i \frac{d\alpha_i}{\alpha_i}) \times \mathcal{J}^{\mathcal{N}-4}$
- volume-preserving diffeomorphisms
  - cluster coordinate mutations, ...

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$$f_{\Gamma} \equiv \prod_i \left( \sum_{h_i, q_i} \int d^3 \text{LIPS}_i \right) \prod_v \mathcal{A}_v \equiv \int \Omega_C \delta(C, p, h)$$

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# Organization and Outline

- 1 **A New Class of Physical Observables: On-Shell Functions**
  - Beyond (Mere) Scattering Amplitudes: On-Shell Functions
  - Physically Observable Data Describing Massless Particles in 4d
  - Basic Building Blocks:  $S$ -Matrices for Three Massless Particles
- 2 **Building-Up the Grassmannian Correspondence: On-Shell Varieties**
  - *Grassmannian* Representations of On-Shell Functions
  - Iterative Construction of Grassmannian ‘On-Shell’ Varieties
  - Characteristics of Grassmannian Representations
- 3 **The Classification of On-Shell (Cluster) Varieties**
  - Warm-Up: Classifying On-Shell Functions of  $G(2,n)$
  - Exploration: the Stratification of On-Shell Varieties in  $G(3,6)$
- 4 **More to Explore: ‘Color-Dressed’ On-Shell Functions**
  - Color-Dressed On-Shell Diagrams in sYM
  - Application: All Two-Loop ‘ $G(2,n)$ ’ Amplitudes in sYM

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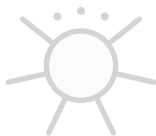
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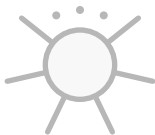
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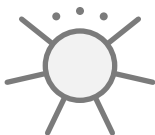
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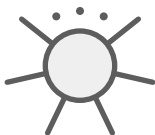
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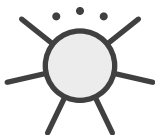
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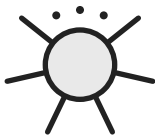
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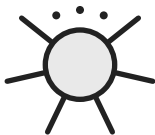
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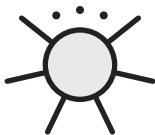
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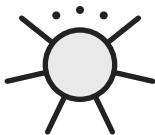
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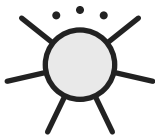
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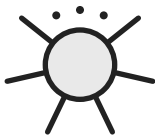
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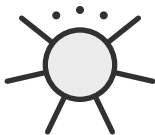
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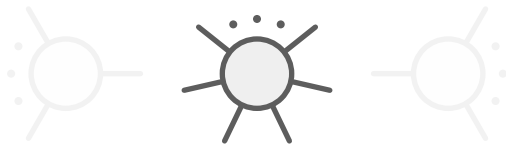
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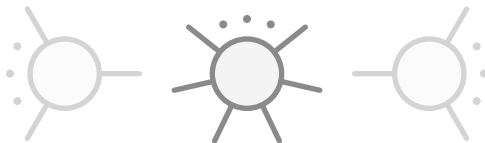
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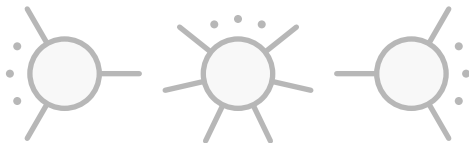
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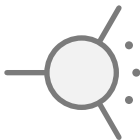
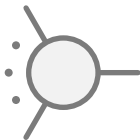
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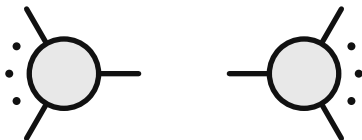
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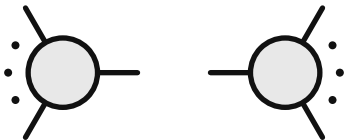
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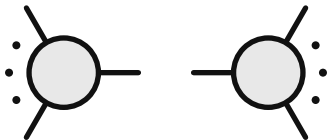
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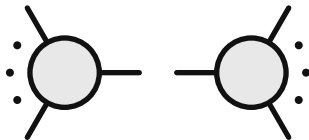
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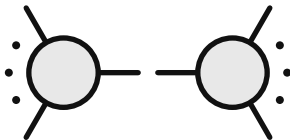
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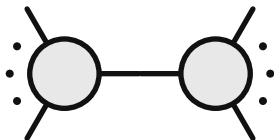
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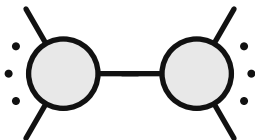
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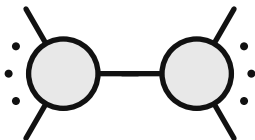
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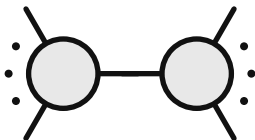
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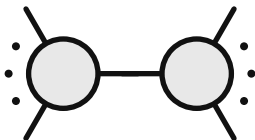
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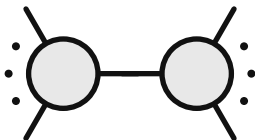
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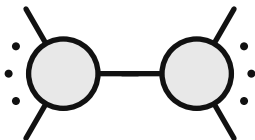
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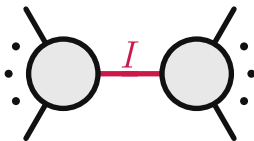
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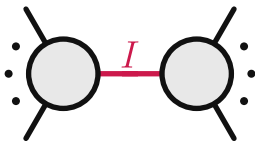
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**Internal Particles:**

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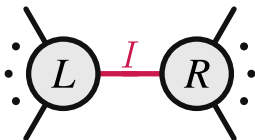
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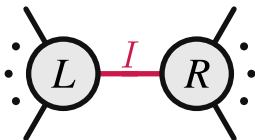


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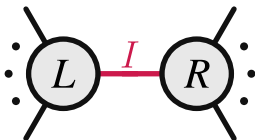
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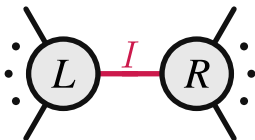


**Internal Particles:** **locality** dictates that we multiply each amplitude, and **unitarity** dictates that we marginalize over unobserved states—integrating over the Lorentz-invariant phase space (“LIPS”) for each particle  $I$ ,

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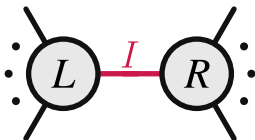


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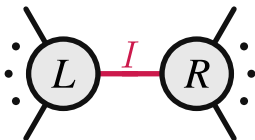


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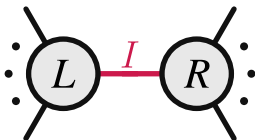


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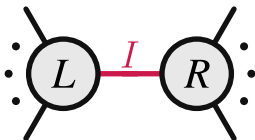


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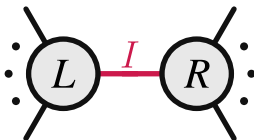


**Internal Particles:** **locality** dictates that we multiply each amplitude, and **unitarity** dictates that we marginalize over unobserved states—integrating over the Lorentz-invariant phase space (“LIPS”) for each particle  $I$ , and summing over the possible states (helicities, masses, colours, etc.).

$$\sum_{\text{states } I} \int d^3\text{LIPS}_I \mathcal{A}_L(\dots, I) \times \mathcal{A}_R(I, \dots)$$

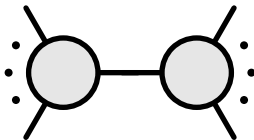
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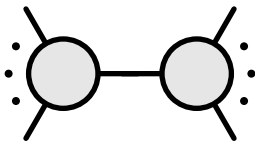


**On-Shell Functions:**



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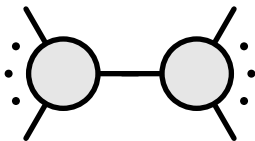
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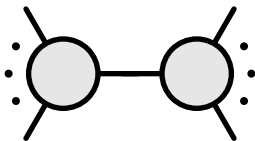


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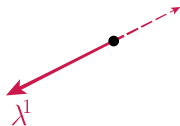
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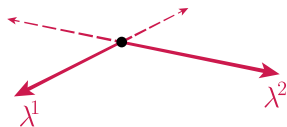
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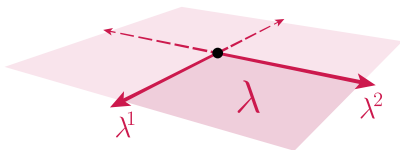
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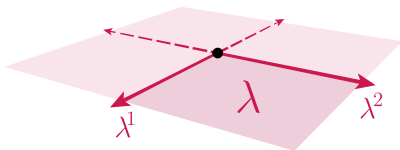
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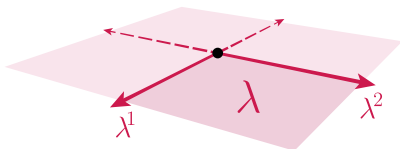
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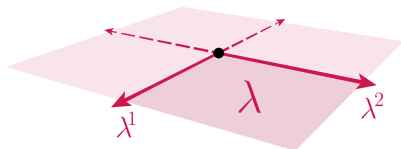
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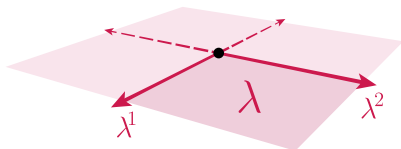
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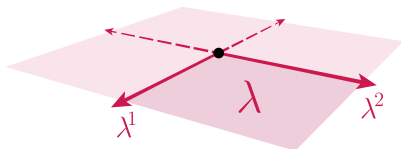
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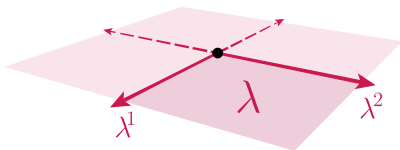
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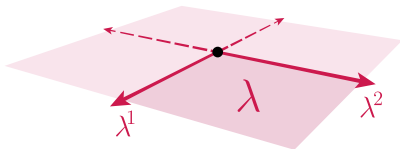
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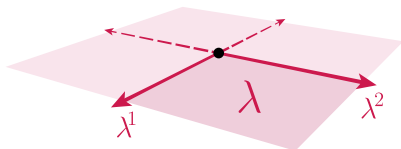
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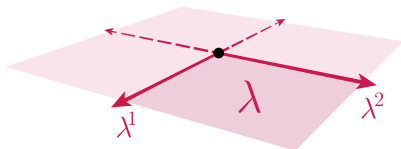
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the *span* of  $k$  vectors in  $\mathbb{C}^n$

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Thus, all the kinematical data can be described by a pair of  $(2 \times n)$  matrices:

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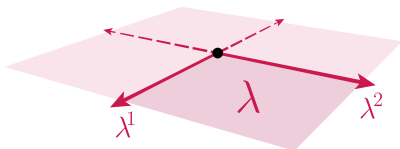
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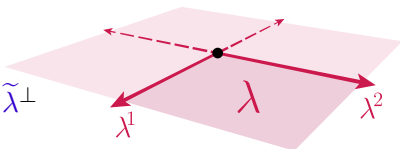
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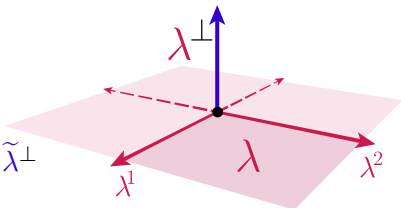
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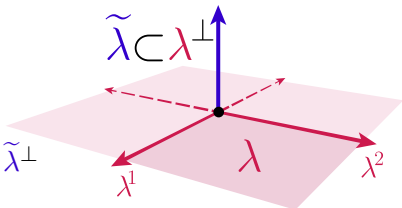
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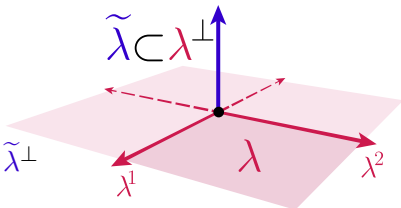
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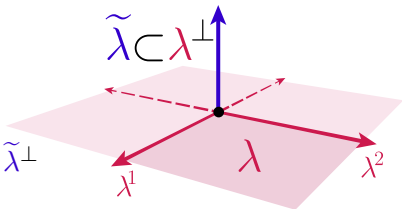
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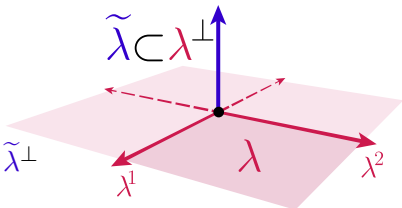
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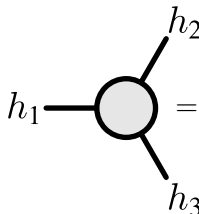


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# Building Blocks: the S-Matrix for Three Massless Particles

Momentum conservation and Poincaré-invariance **uniquely** fix the kinematic dependence of the amplitude for three massless particles (to all loop orders!).

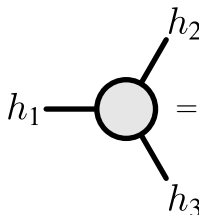


A Feynman diagram showing a central grey circle with three external lines. The left line is horizontal and labeled  $h_1$ . The top-right line is labeled  $h_2$ . The bottom-right line is labeled  $h_3$ .

$$= f(\lambda_1 \tilde{\lambda}_1, \lambda_2 \tilde{\lambda}_2, \lambda_3 \tilde{\lambda}_3) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})$$

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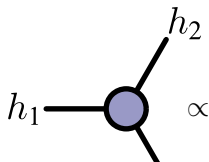
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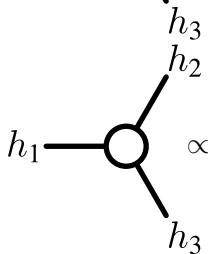
$$\propto \langle 12 \rangle^{h_3 - h_1 - h_2} \langle 23 \rangle^{h_1 - h_2 - h_3} \langle 31 \rangle^{h_2 - h_3 - h_1}$$

$$h_1 + h_2 + h_3 \leq 0$$

$$\lambda^\perp \equiv (\langle 23 \rangle \langle 31 \rangle \langle 12 \rangle) \supset \tilde{\lambda}$$

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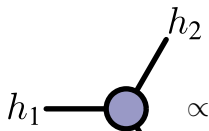
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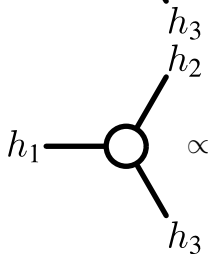
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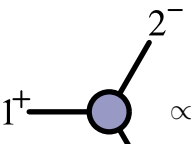
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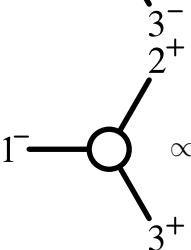
$$\begin{aligned}
 & 1^+ \text{---} \bigcirc \begin{cases} 2^- \\ 3^- \end{cases} \propto \langle 12 \rangle^{h_3-h_1-h_2} \langle 23 \rangle^{h_1-h_2-h_3} \langle 31 \rangle^{h_2-h_3-h_1} \\
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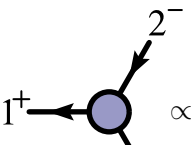
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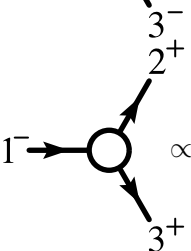
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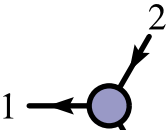
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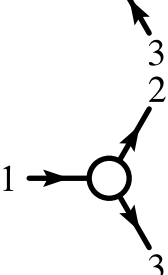
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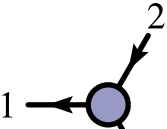
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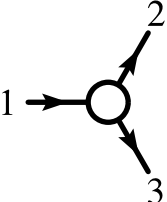
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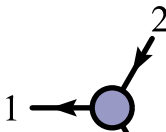
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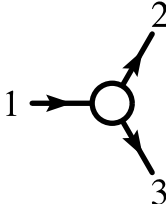
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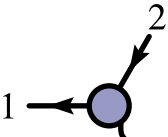
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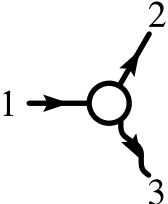
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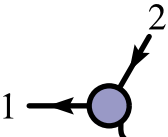


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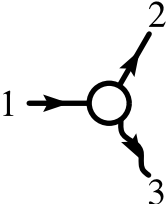


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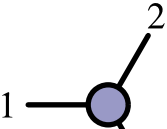
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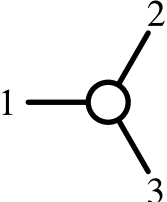
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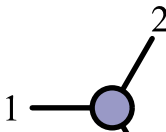
$$\propto \frac{\delta^{2 \times 4}(\lambda \cdot \tilde{\eta})}{\langle 12 \rangle \langle 23 \rangle \langle 31 \rangle} \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda}) \equiv \mathcal{A}_3^{(2)}$$



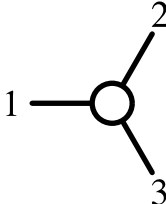
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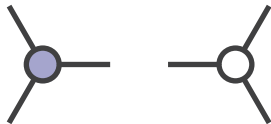
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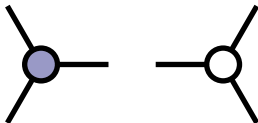
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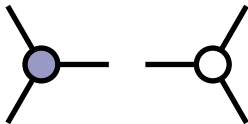
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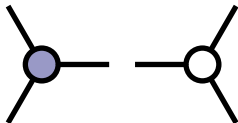
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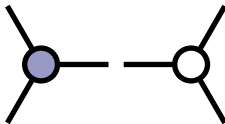
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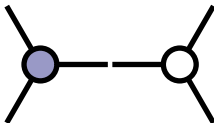
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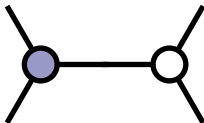
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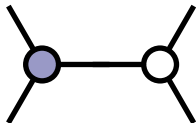
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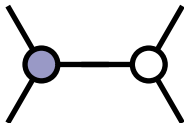
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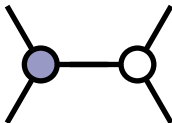
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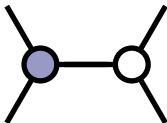
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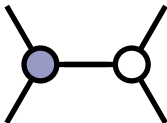
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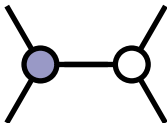
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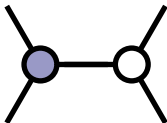
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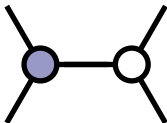
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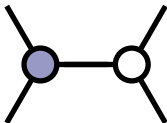
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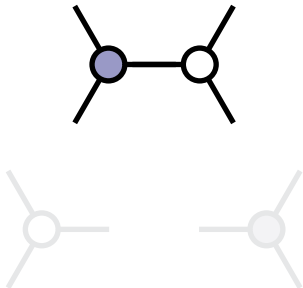
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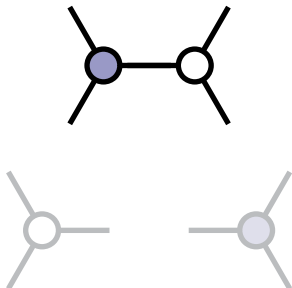
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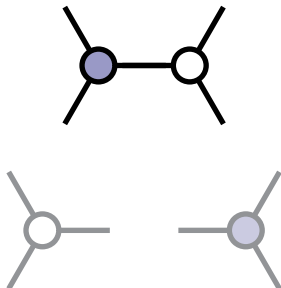
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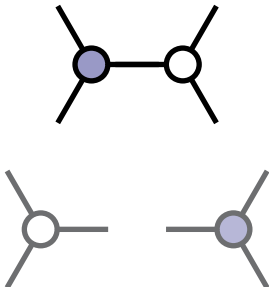
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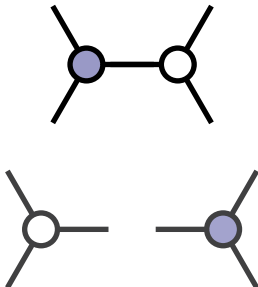
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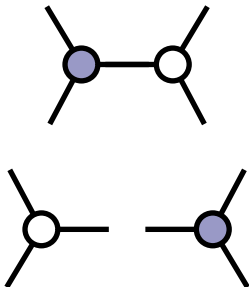
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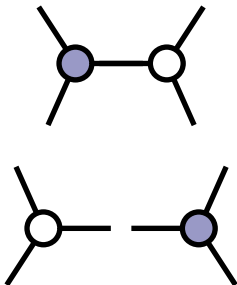
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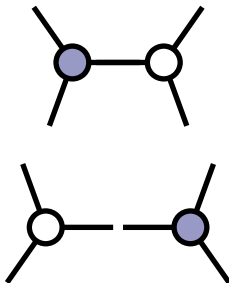
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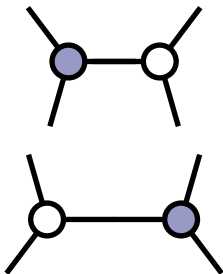
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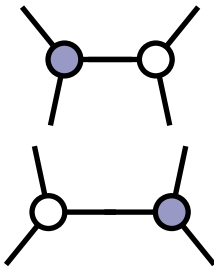
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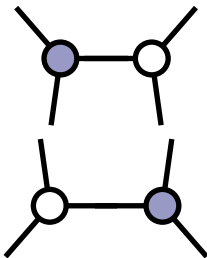
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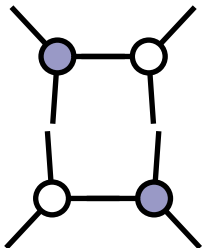
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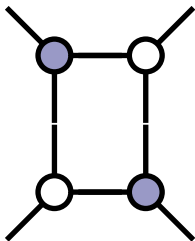
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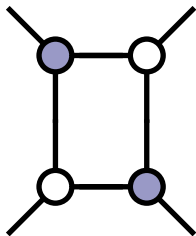
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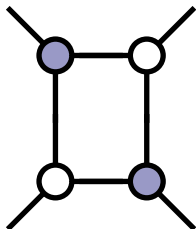
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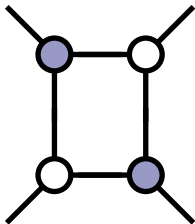
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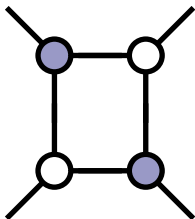
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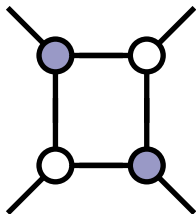
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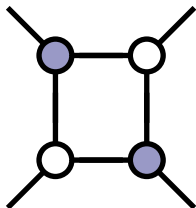
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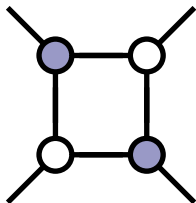
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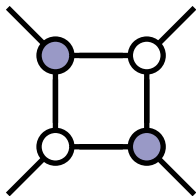
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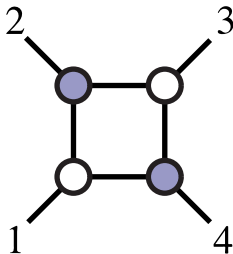
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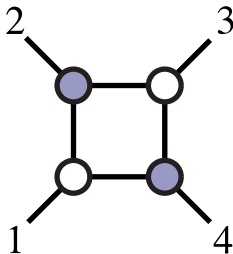
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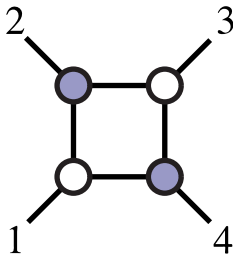
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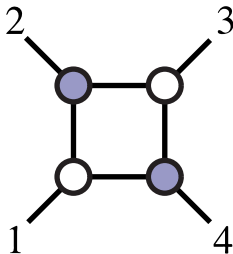
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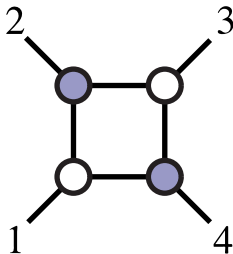
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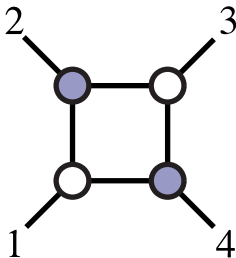
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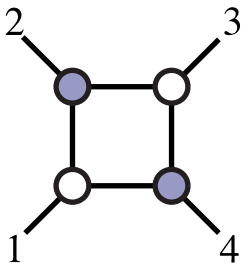
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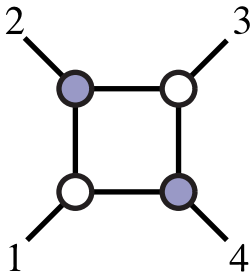
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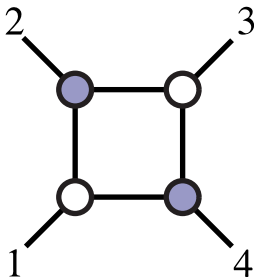
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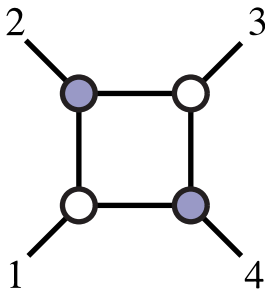
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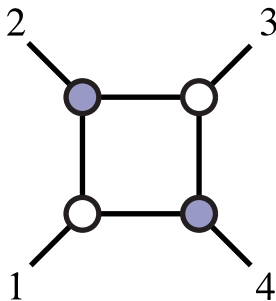
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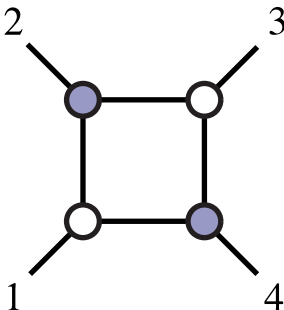
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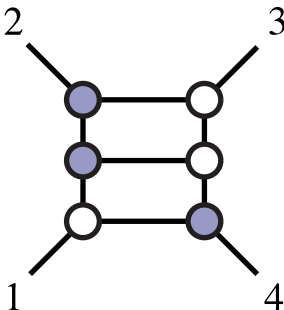
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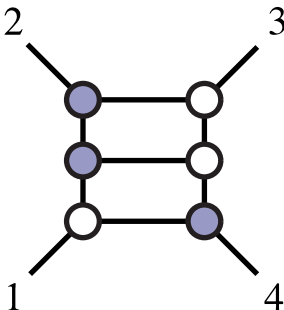
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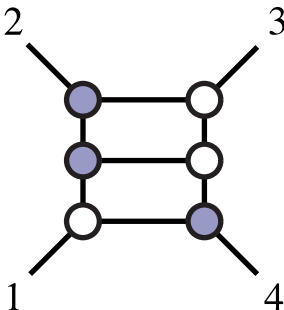
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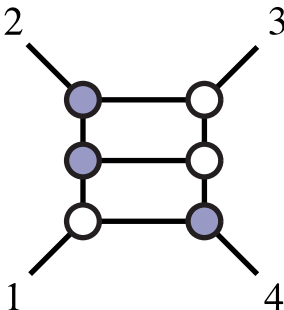
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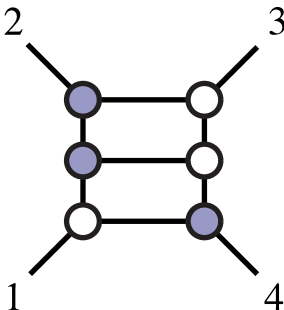
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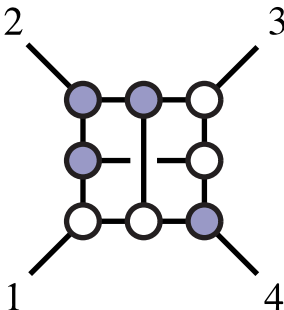
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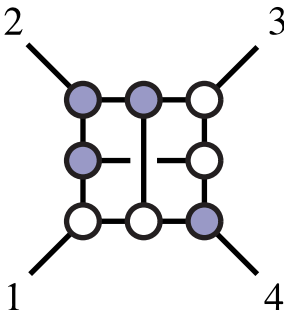
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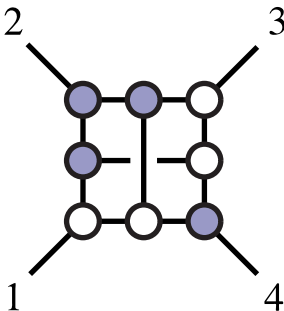
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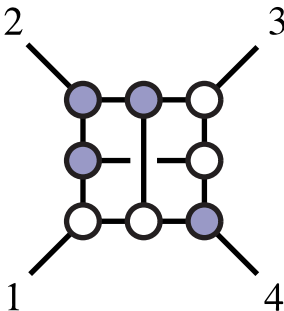
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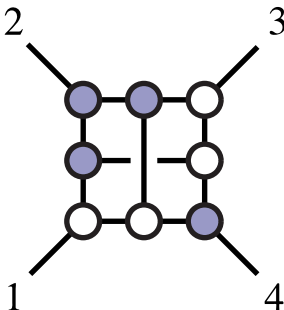
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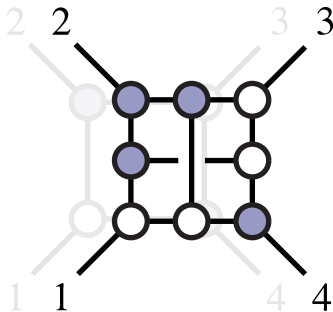
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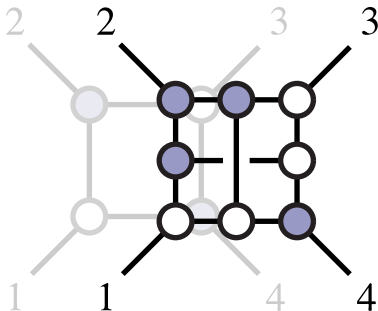
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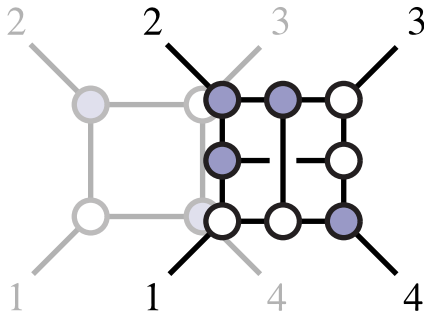
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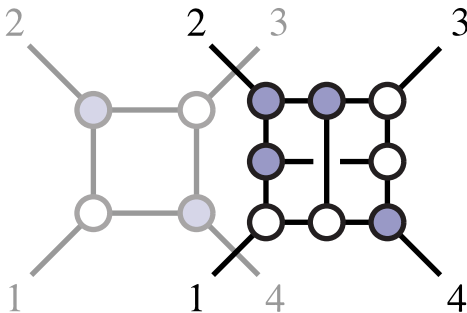
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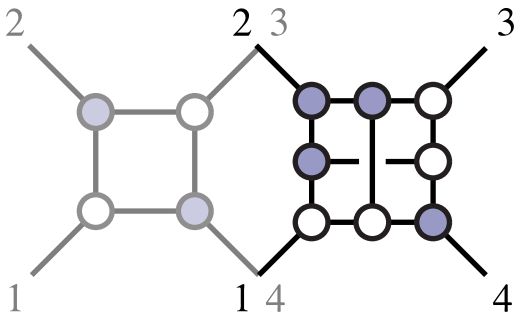
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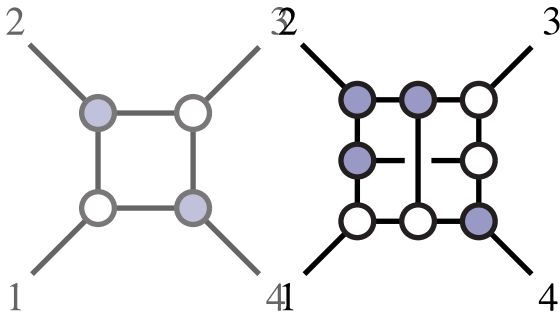
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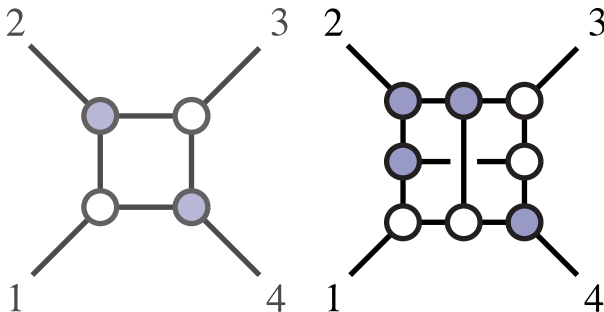
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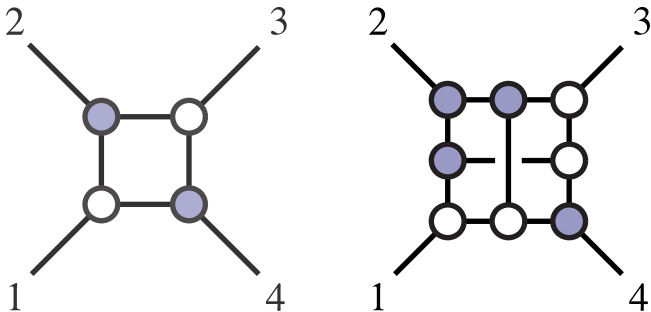
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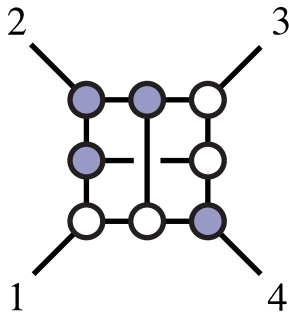
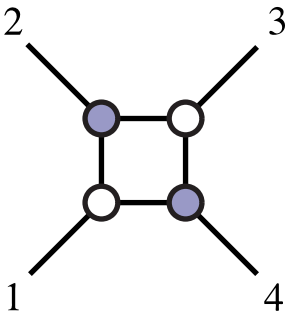
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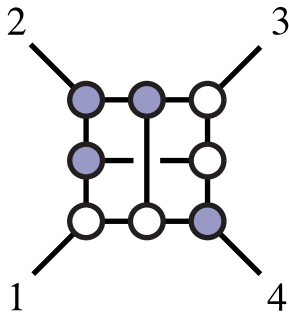
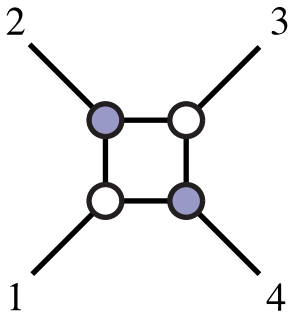
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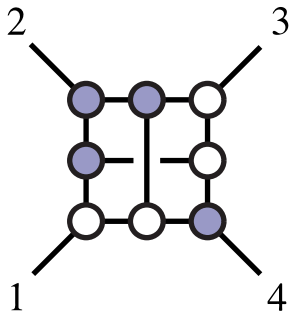
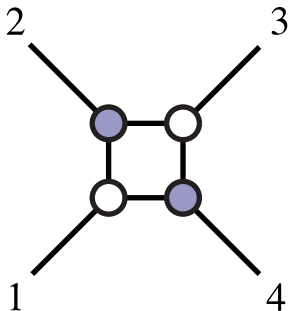
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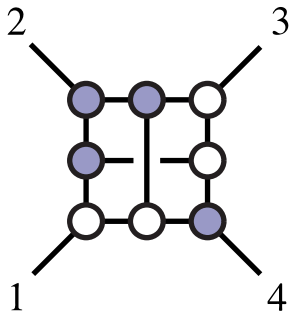
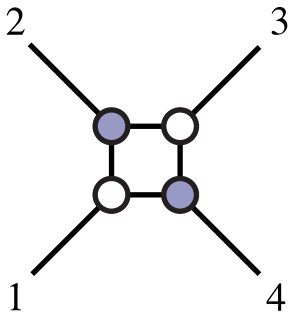
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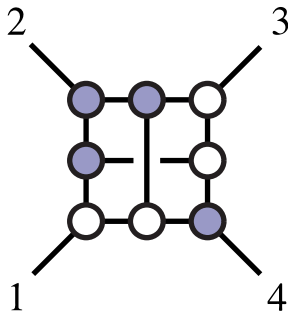
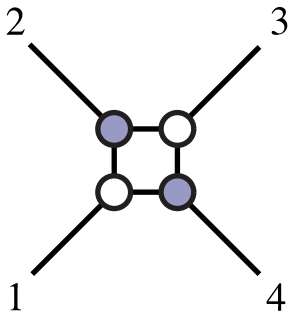
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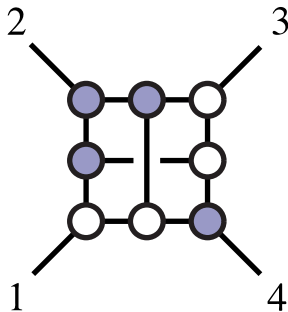
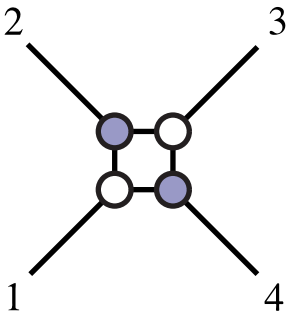
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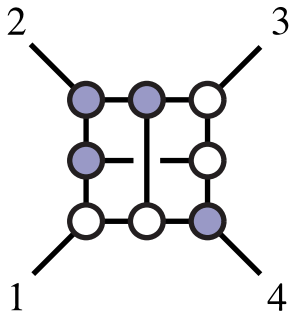
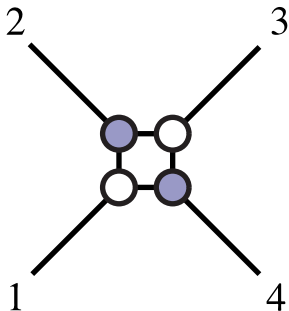
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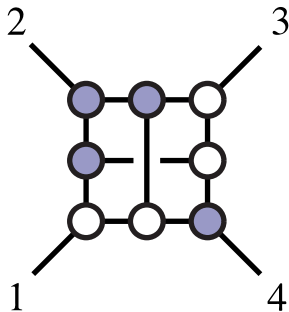
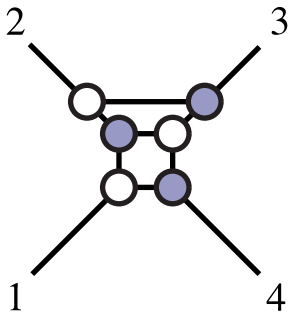
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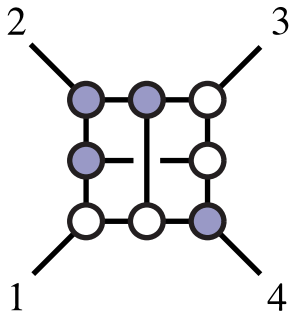
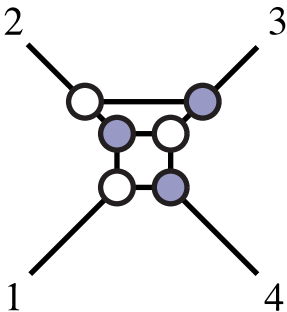
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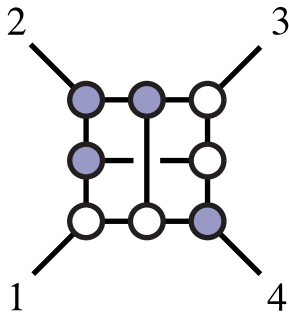
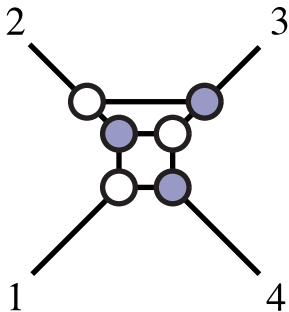
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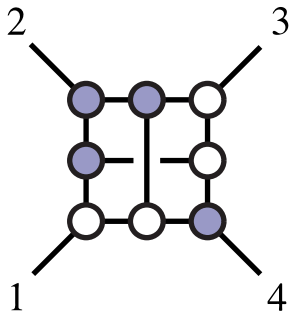
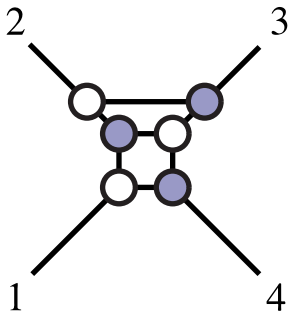
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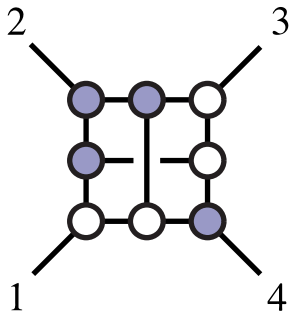
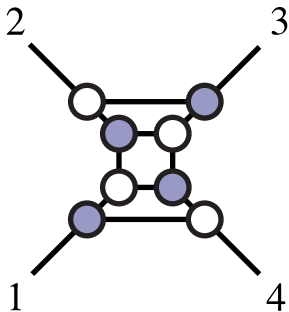
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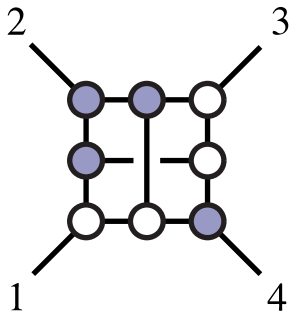
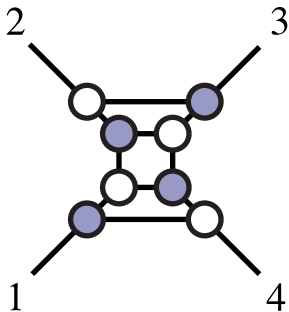
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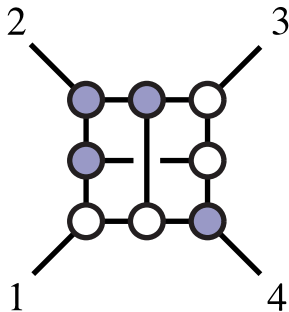
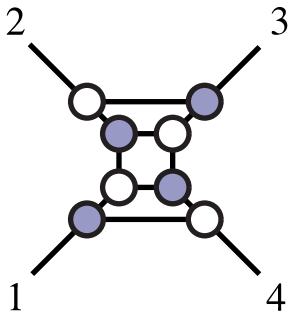
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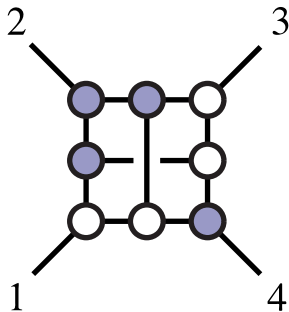
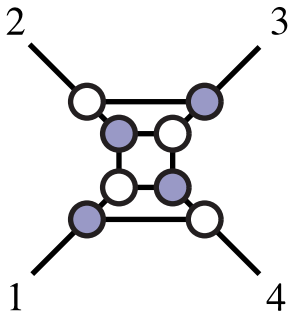
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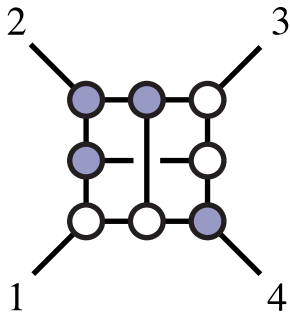
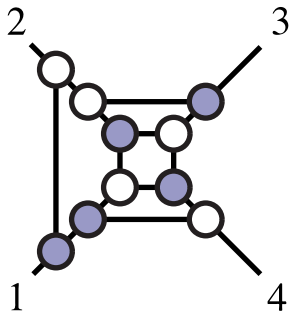
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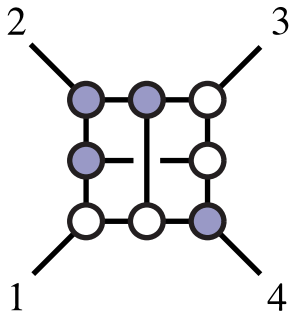
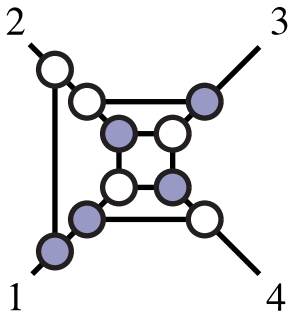
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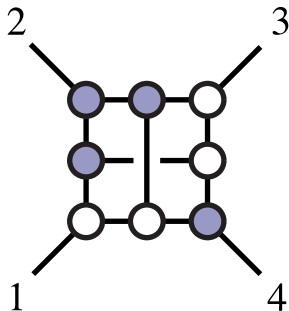
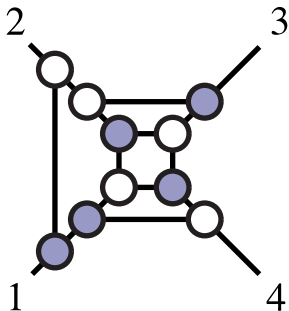
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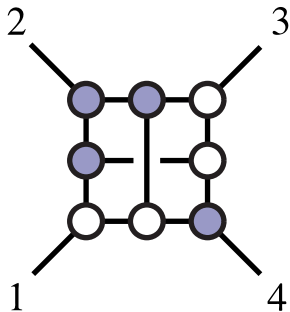
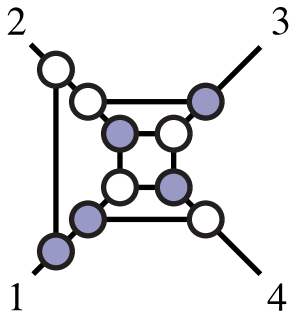
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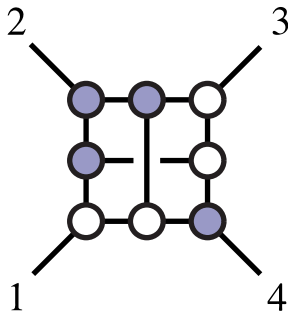
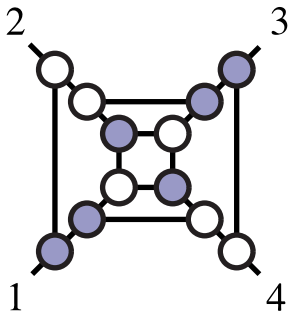
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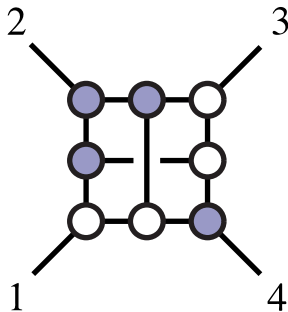
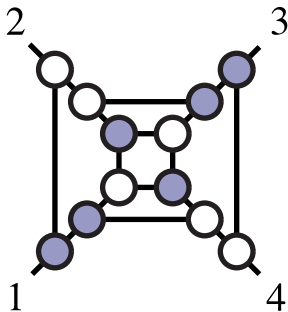
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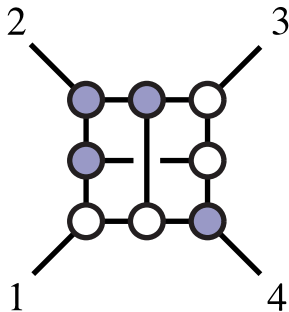
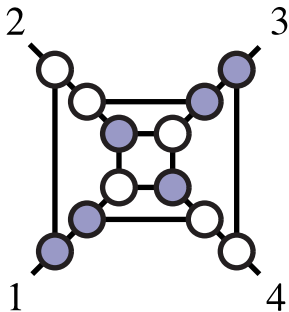
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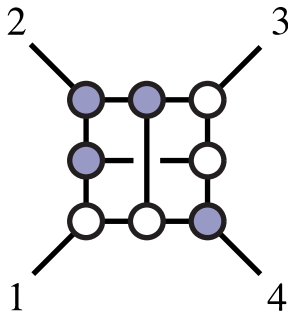
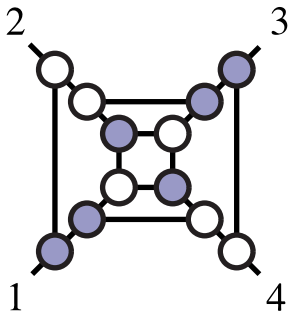
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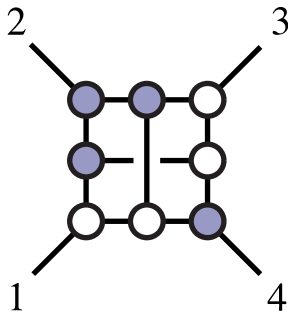
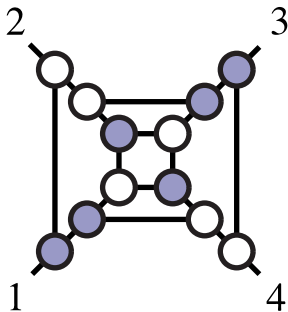
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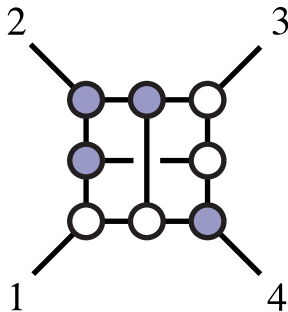
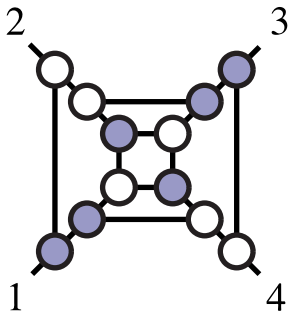
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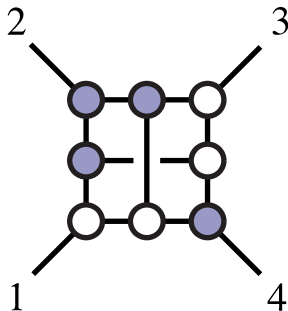
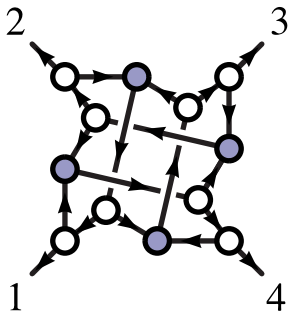
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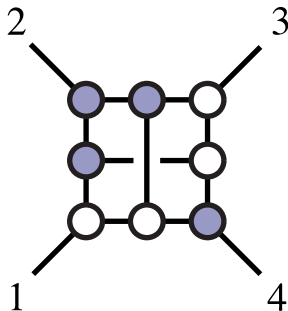
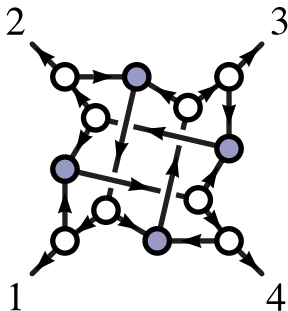
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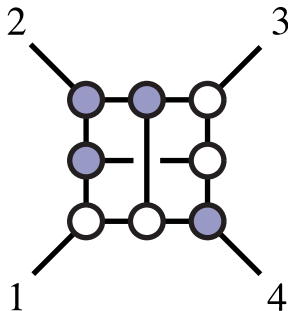
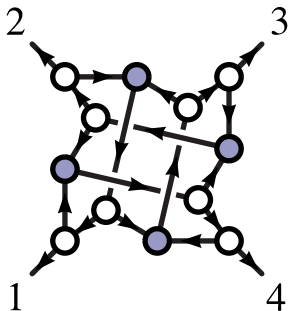
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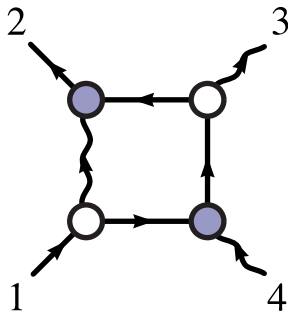
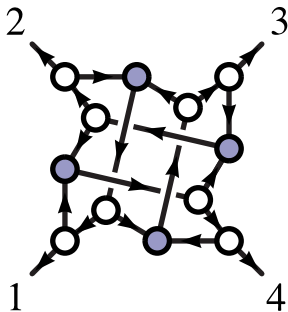
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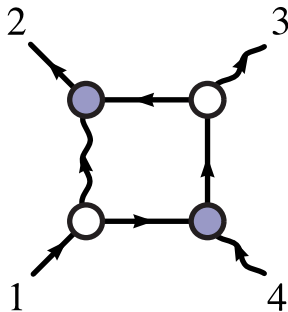
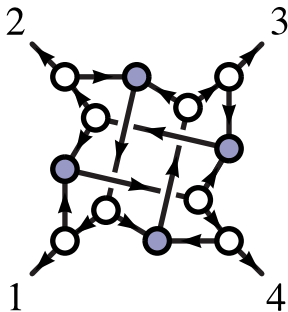
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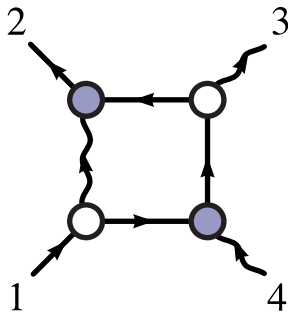
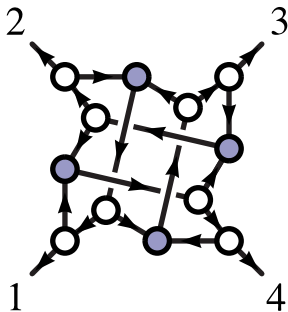
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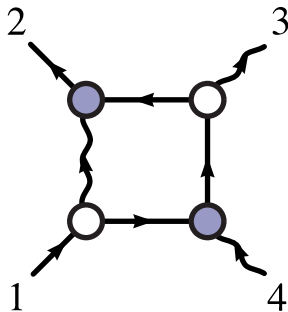
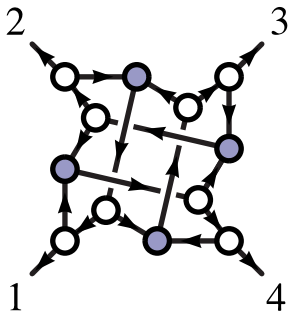
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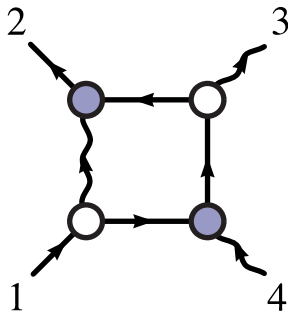
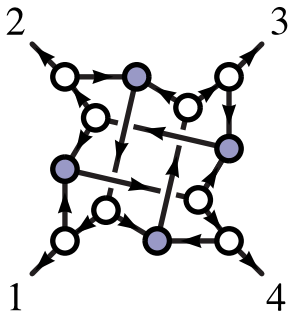
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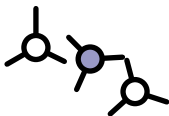
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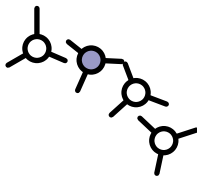
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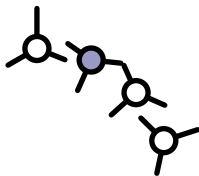
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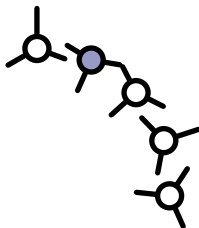
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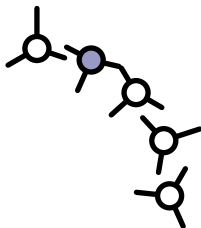
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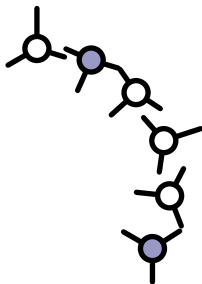
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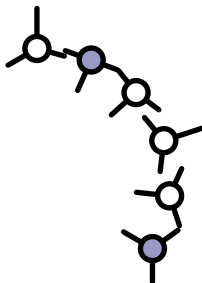
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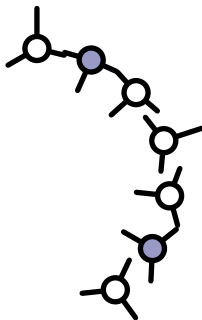
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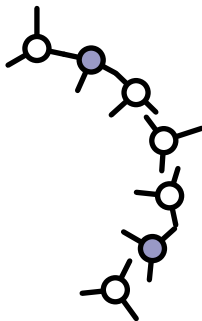
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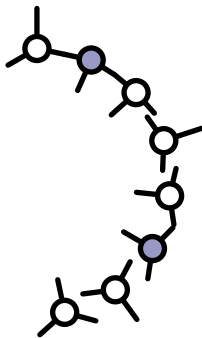
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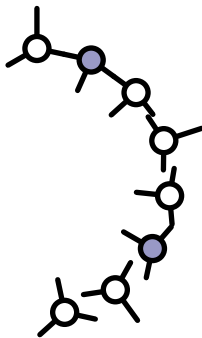
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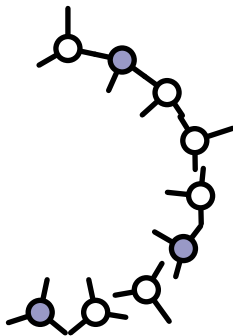
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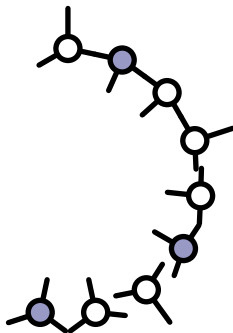
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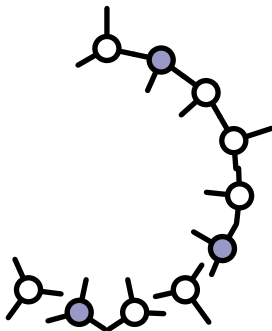
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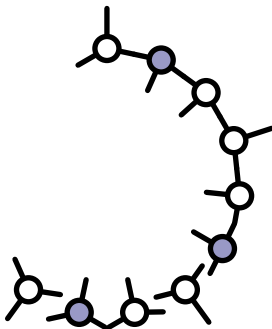
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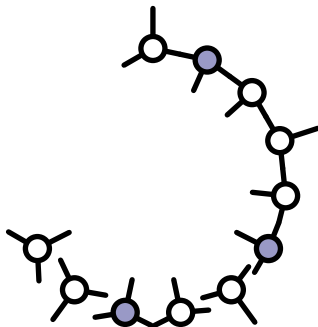
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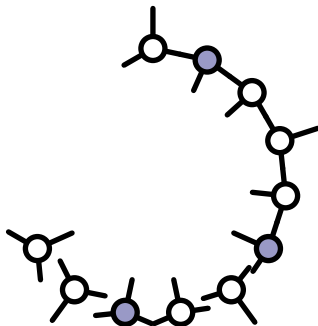
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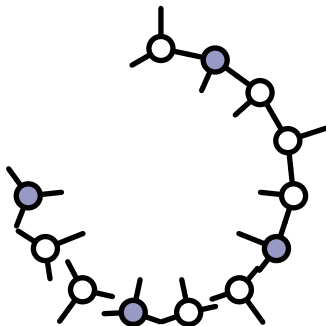
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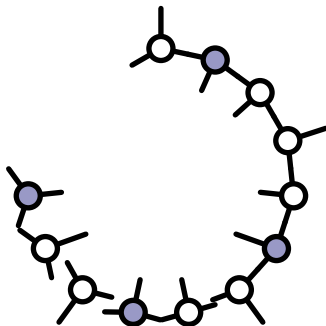
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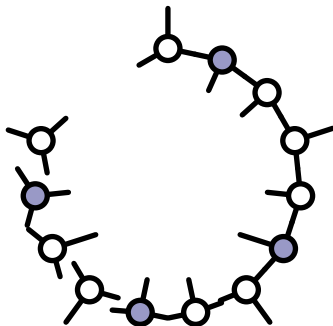
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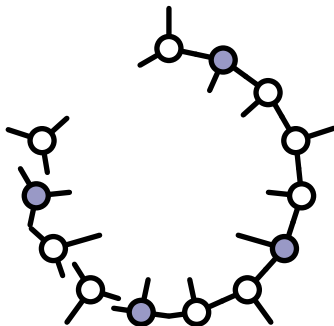
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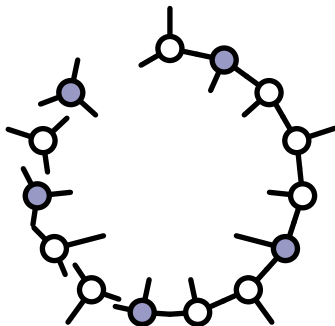
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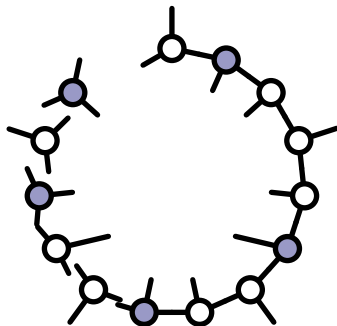
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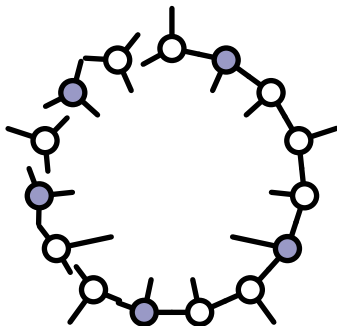
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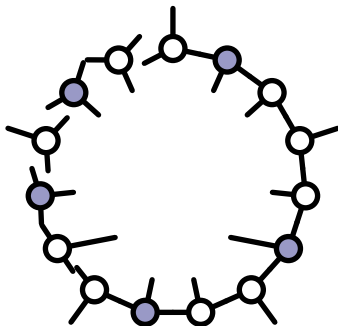
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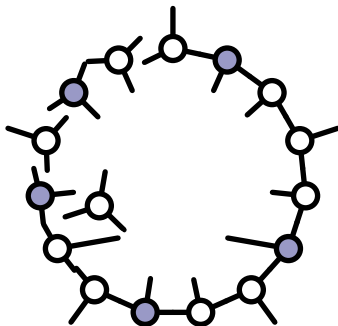
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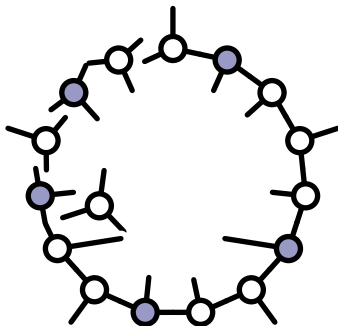
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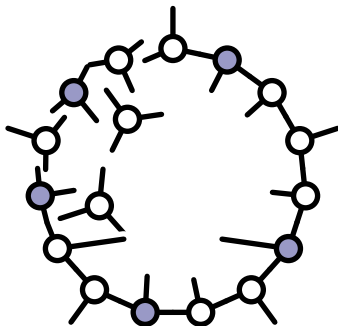
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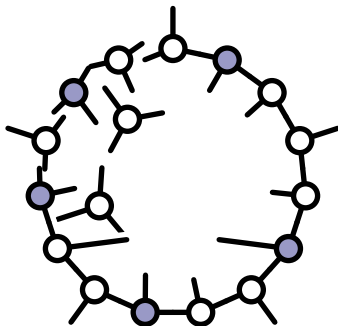
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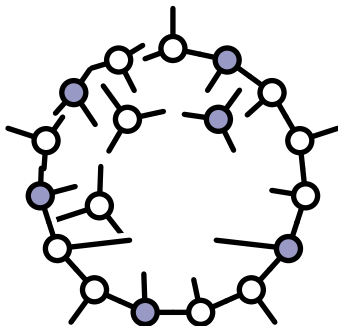
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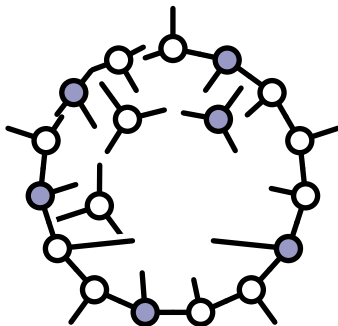
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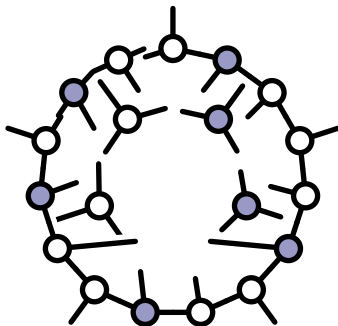
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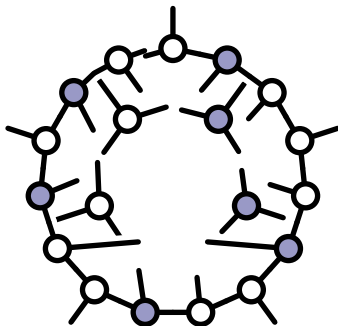
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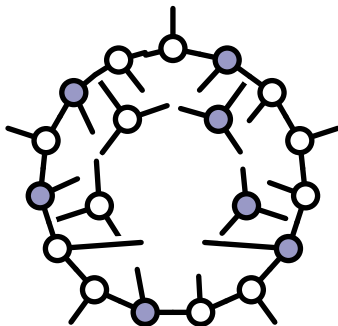
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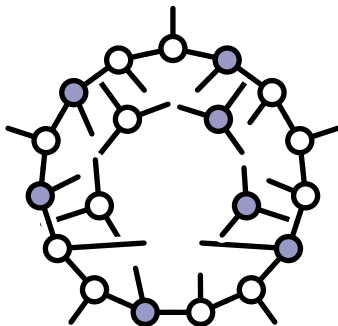
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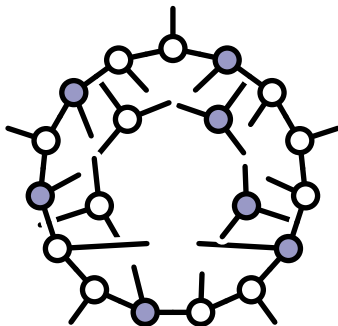
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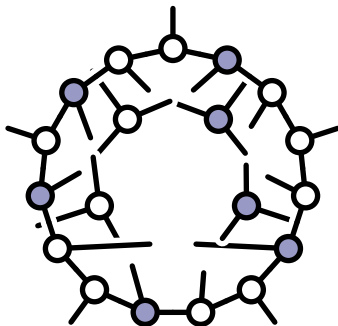
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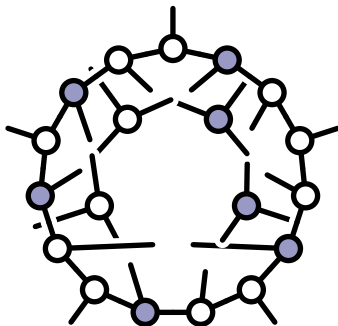
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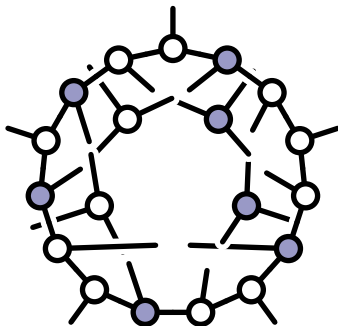
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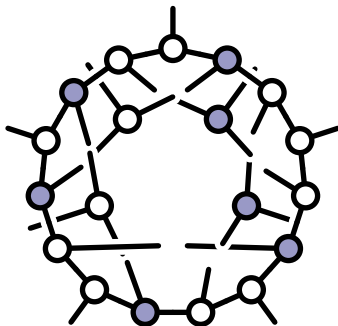
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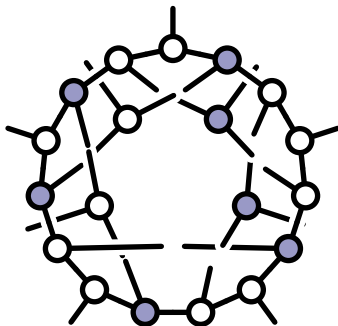
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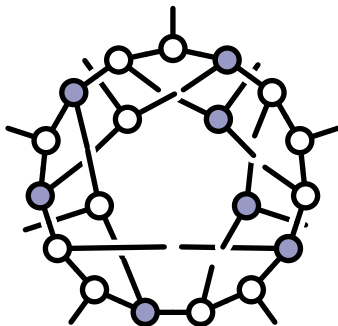
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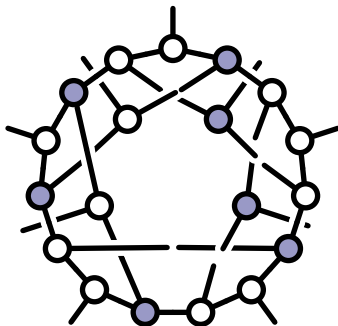
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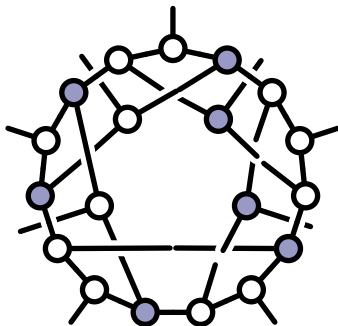
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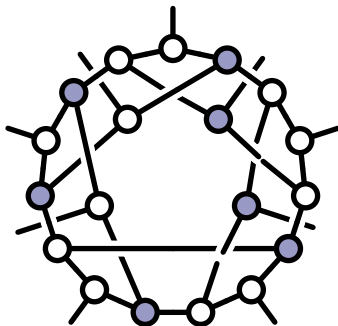
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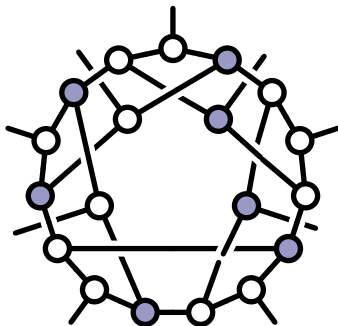
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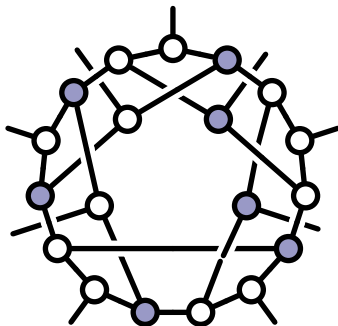
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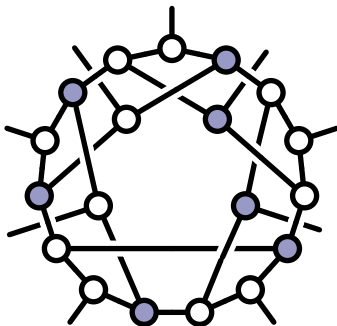
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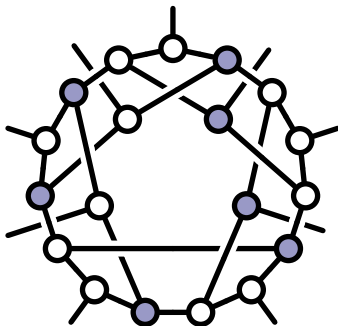
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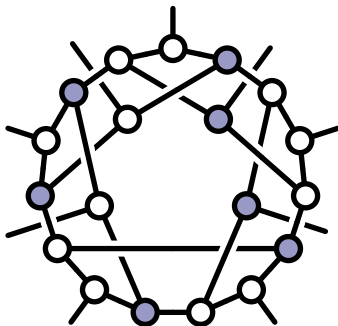
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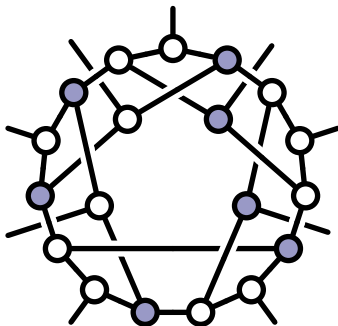
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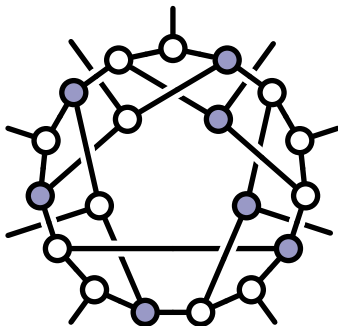
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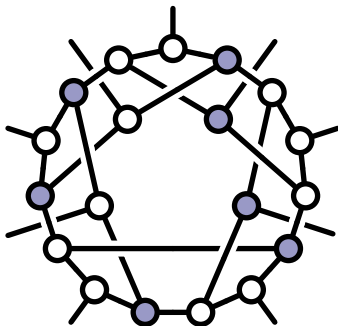
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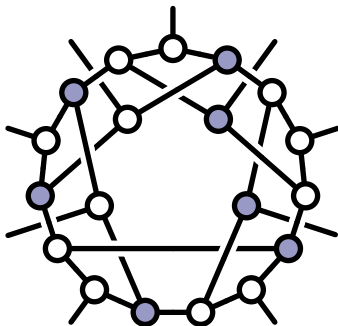
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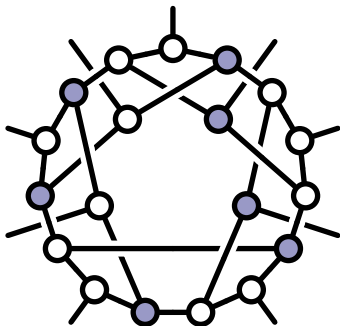
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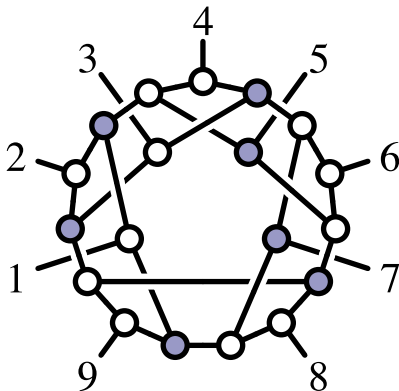
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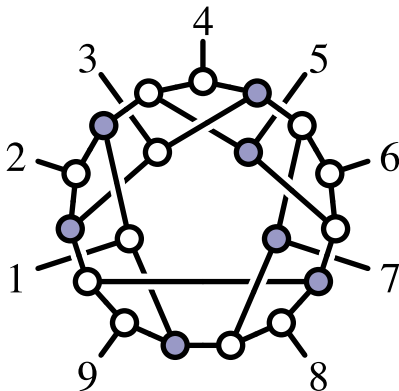
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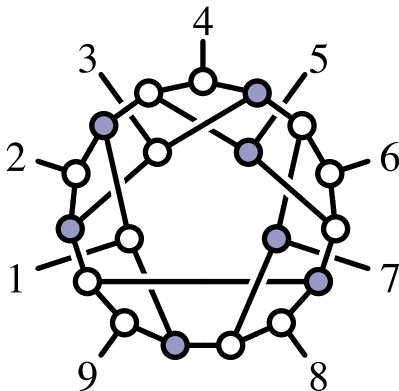
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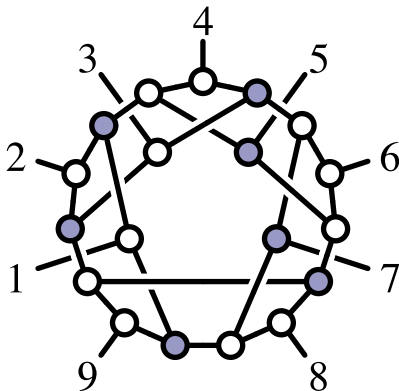
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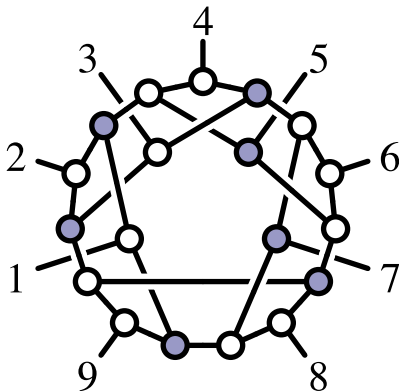
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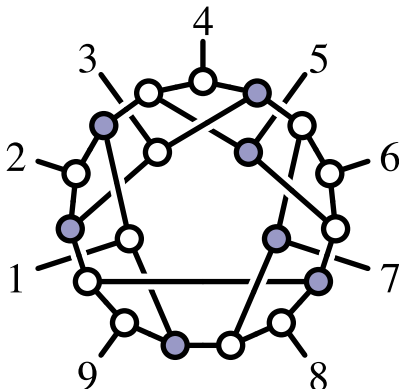
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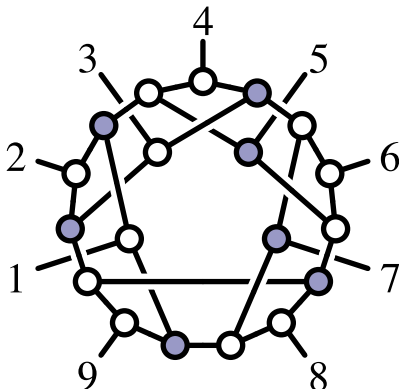
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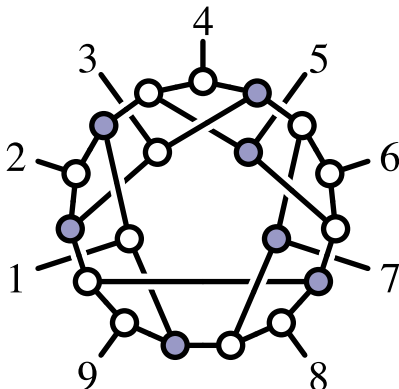
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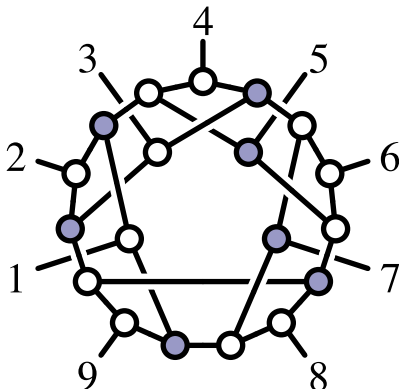
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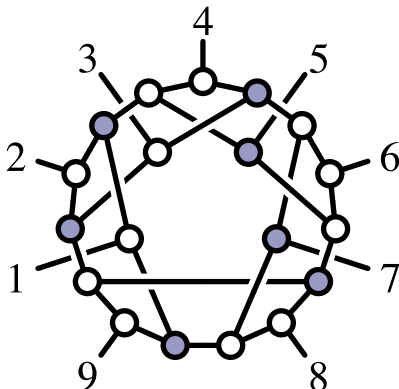
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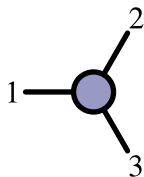


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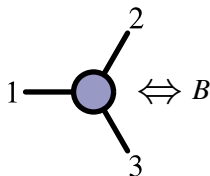
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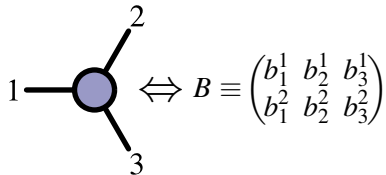
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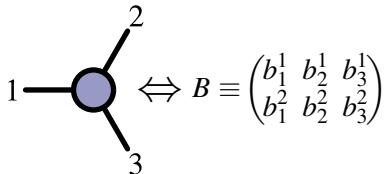


A diagram showing a central blue circle representing a vertex. Three black lines extend from the circle: one to the left labeled '1', one to the top-right labeled '2', and one to the bottom-right labeled '3'. To the right of the vertex is a double-headed arrow pointing to the matrix equation  $B \equiv \begin{pmatrix} b_1^1 & b_2^1 & b_3^1 \\ b_1^2 & b_2^2 & b_3^2 \end{pmatrix}$ .

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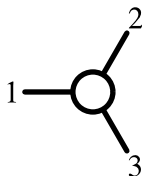
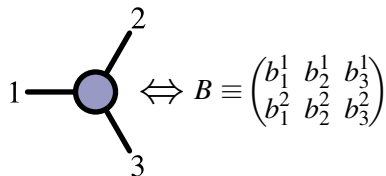
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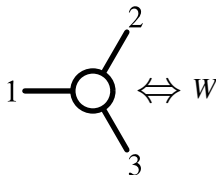
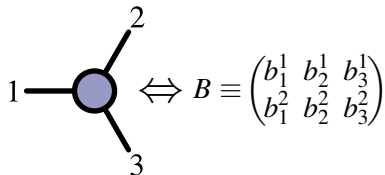


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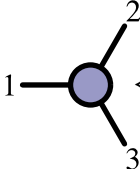


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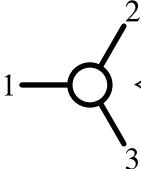
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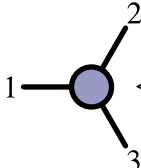
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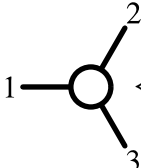


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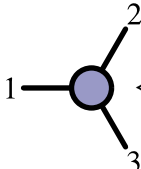
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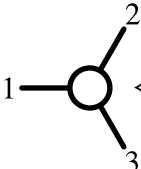
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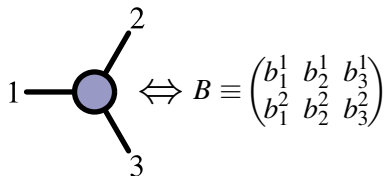
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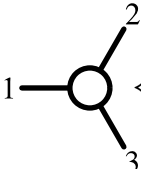
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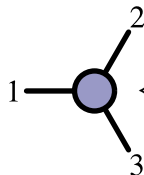
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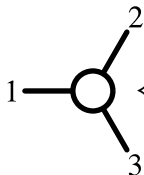
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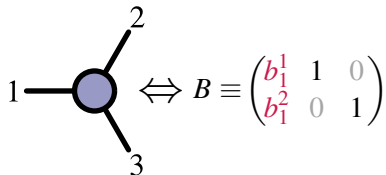
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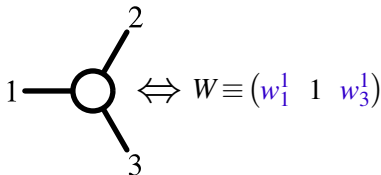
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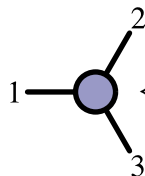
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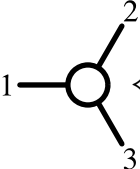
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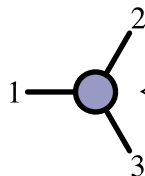
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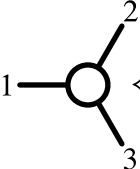
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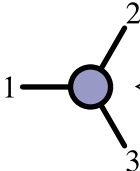
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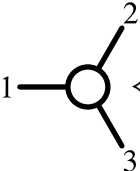
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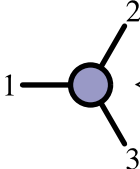
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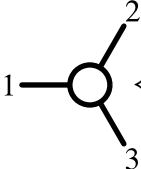
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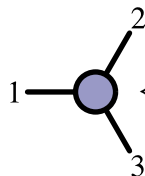
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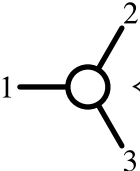
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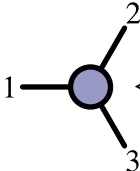
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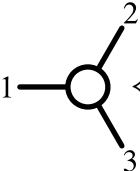
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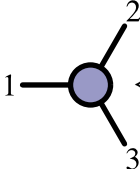
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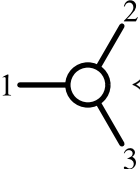


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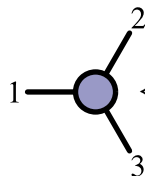
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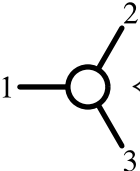
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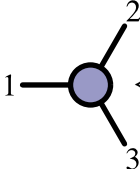
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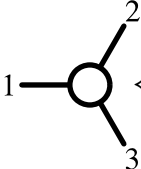
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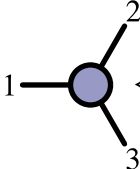
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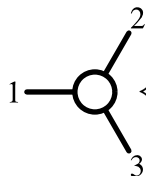
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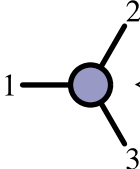
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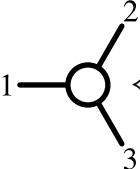
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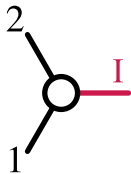
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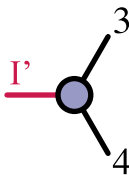
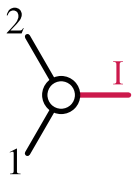
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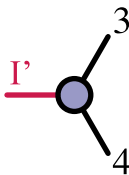
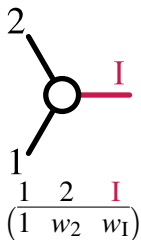
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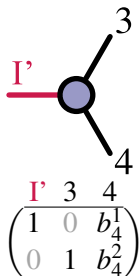
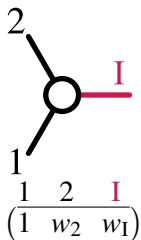
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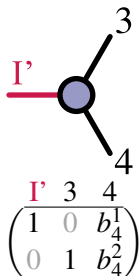
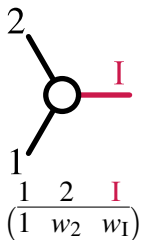
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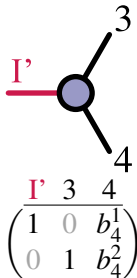
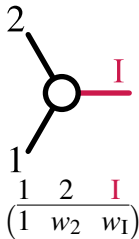
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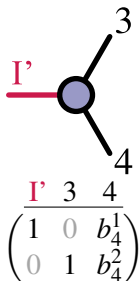
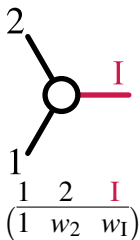
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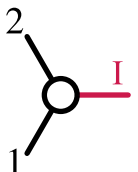
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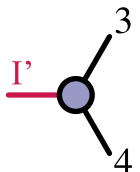
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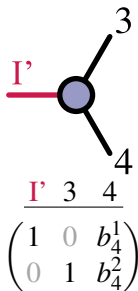
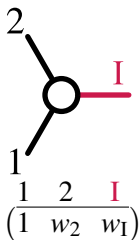
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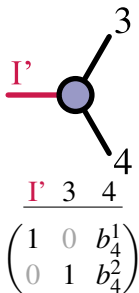
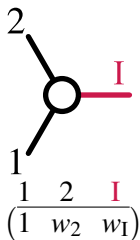
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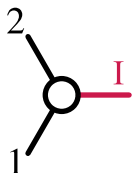
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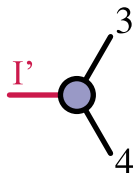
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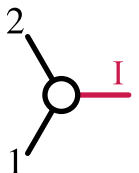
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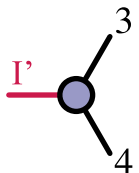
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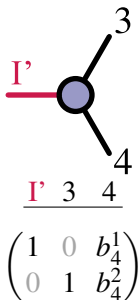
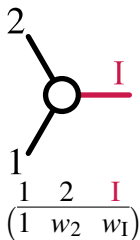
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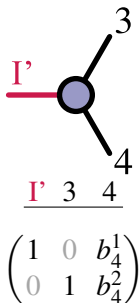
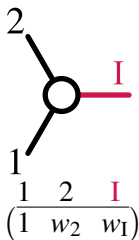
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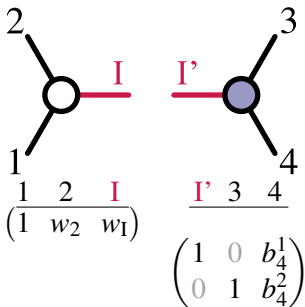
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$$(f_1, f_2) \mapsto f_1 \times f_2$$

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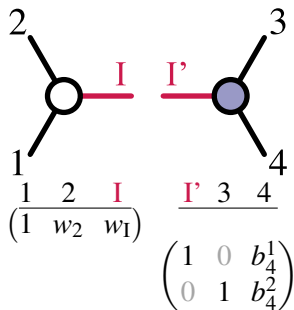
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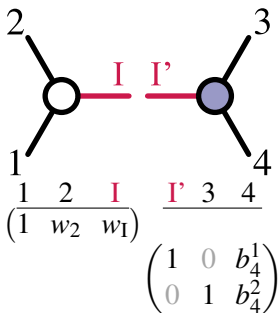
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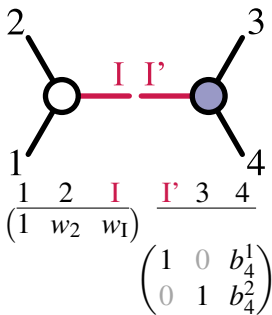
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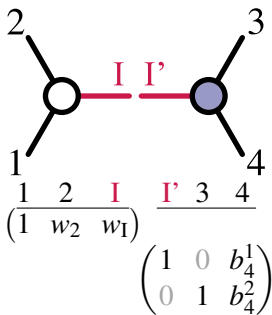
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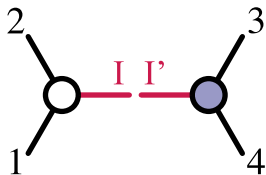
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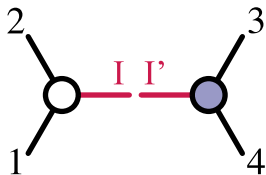
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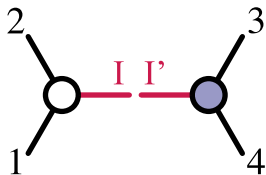
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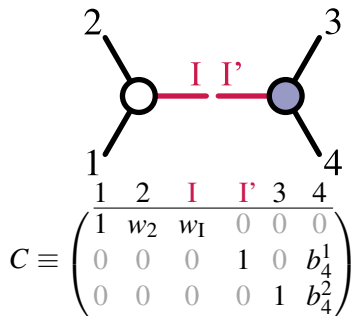
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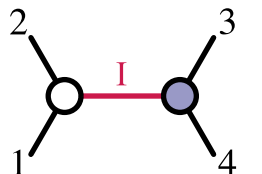
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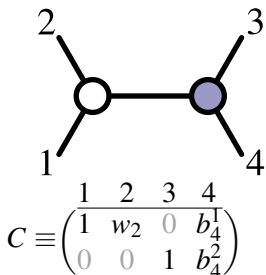
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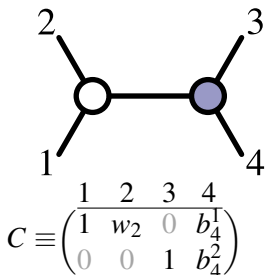
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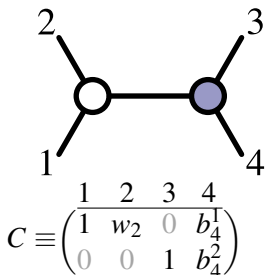
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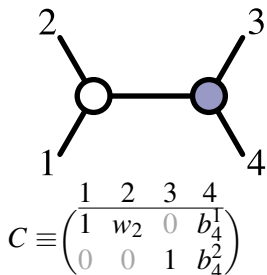
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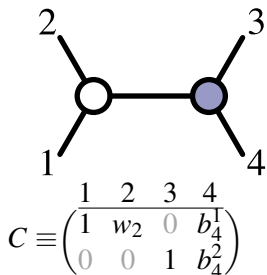
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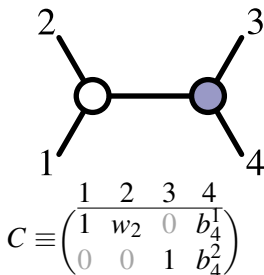
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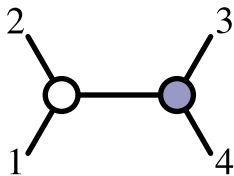
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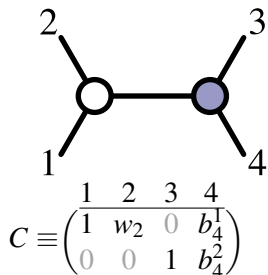
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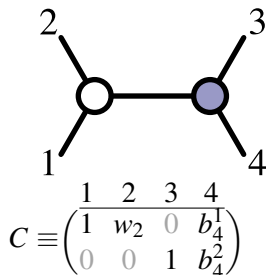
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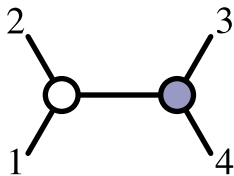
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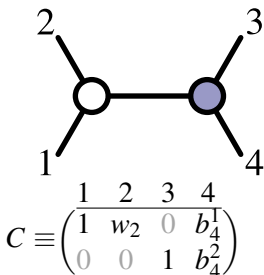
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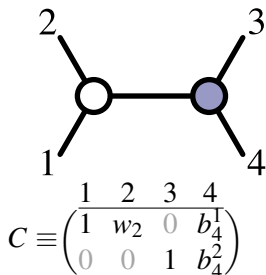
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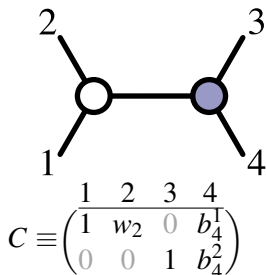
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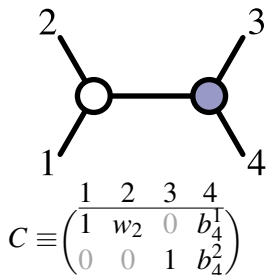
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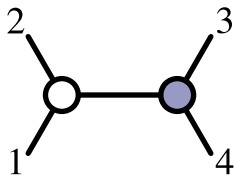
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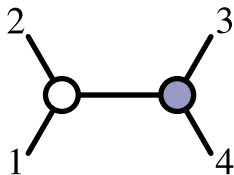
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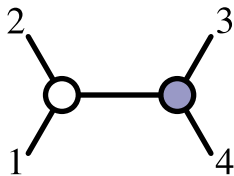
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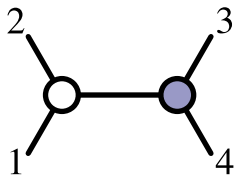
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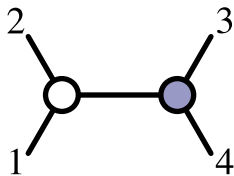
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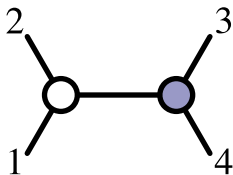
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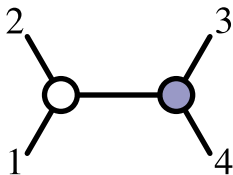
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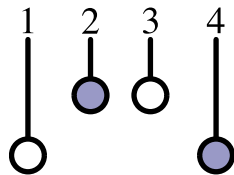
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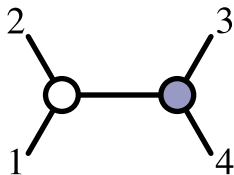
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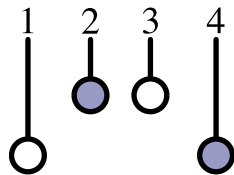
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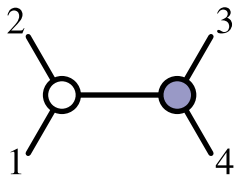
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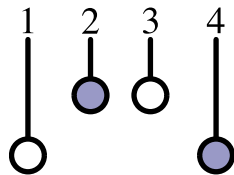
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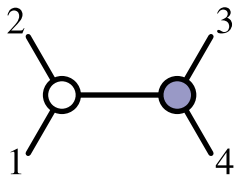
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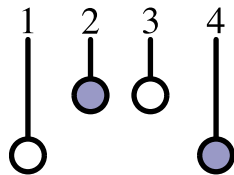
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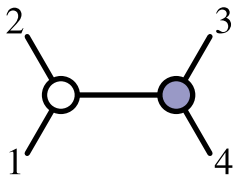
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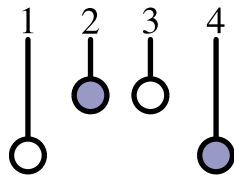
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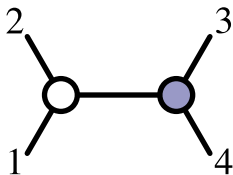
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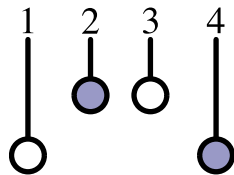
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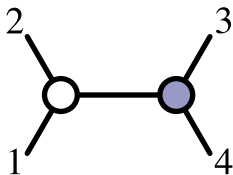
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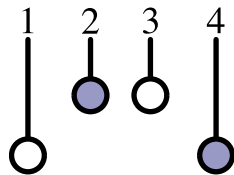
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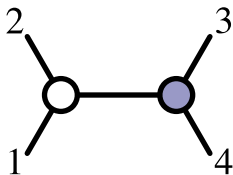
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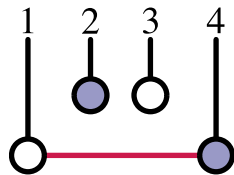
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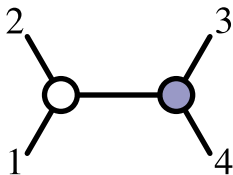
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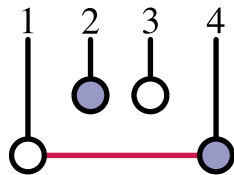
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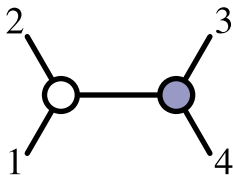
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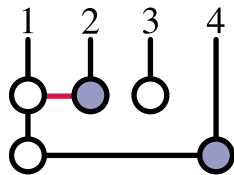
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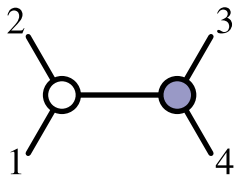
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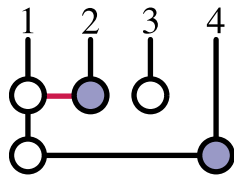
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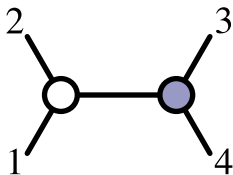
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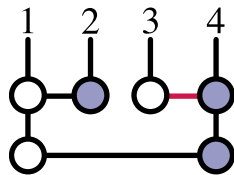
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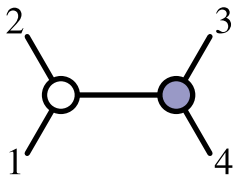
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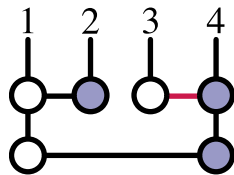
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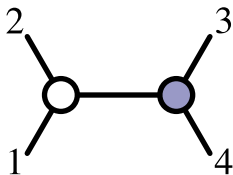
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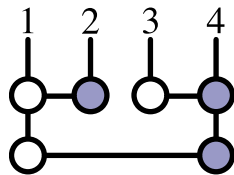
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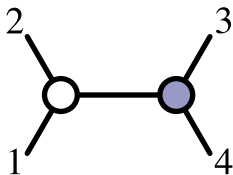
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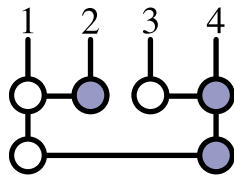
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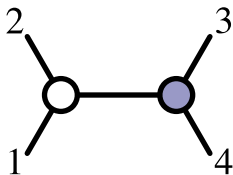
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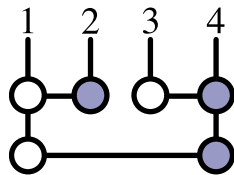
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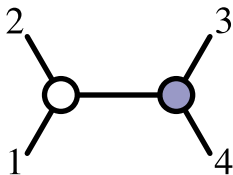
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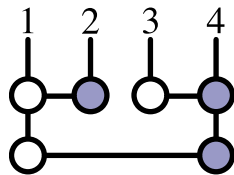
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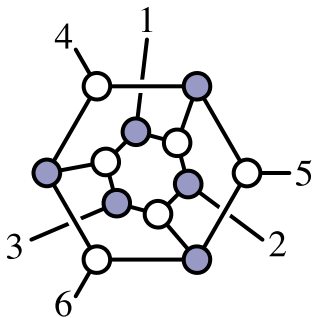
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A more direct way to construct  $C(\alpha)$  is via **boundary measurements**:

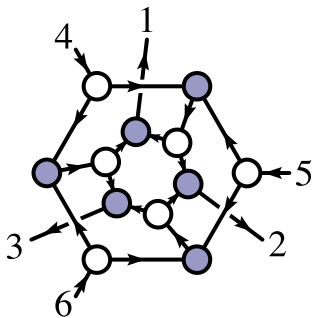
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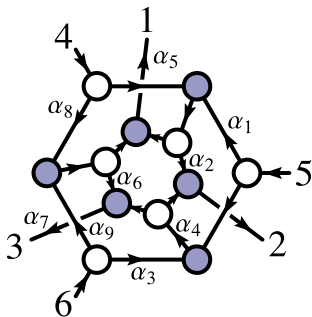
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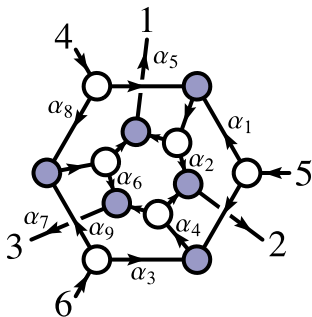
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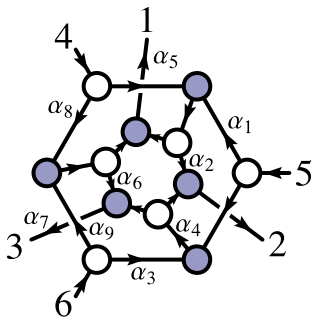
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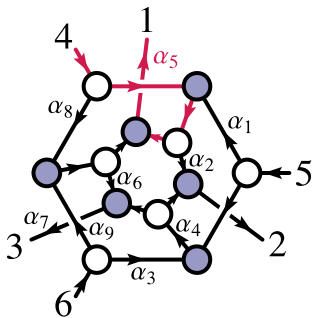
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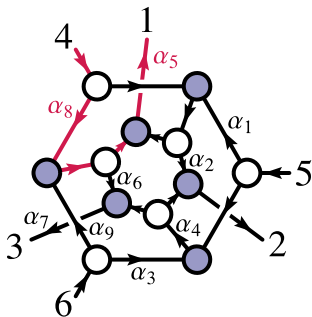
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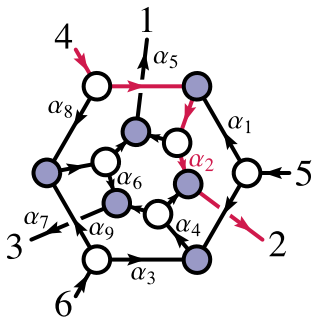
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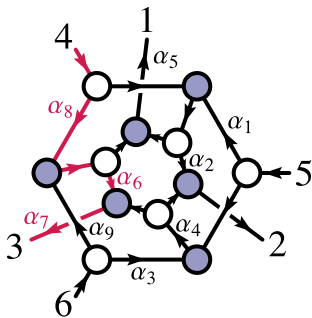
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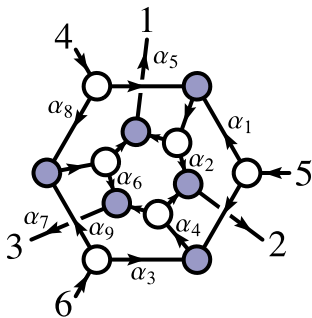
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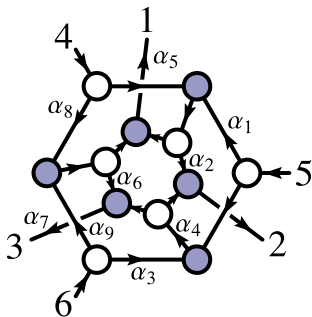


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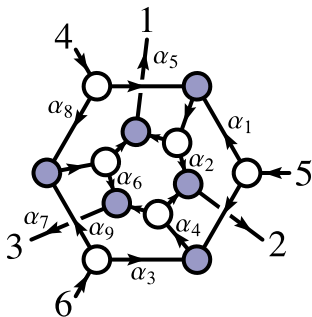


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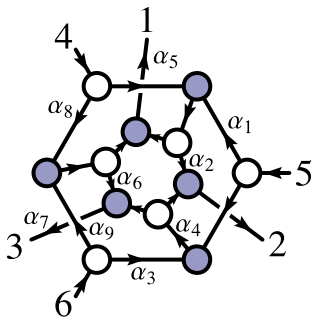


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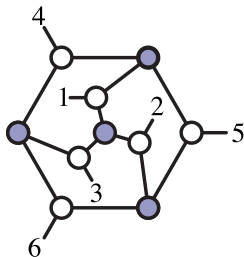


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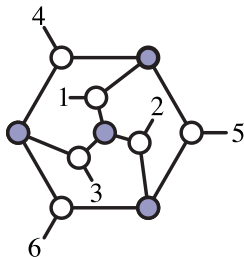
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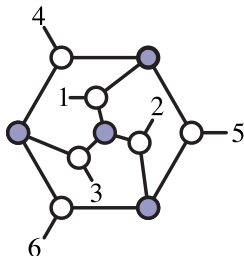


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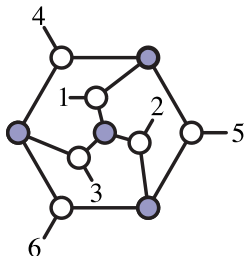


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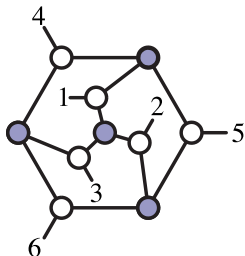


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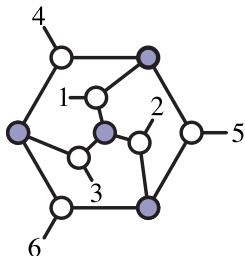
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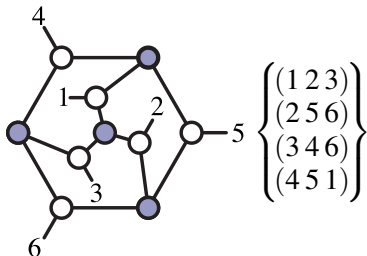
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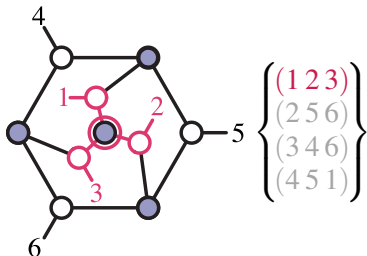
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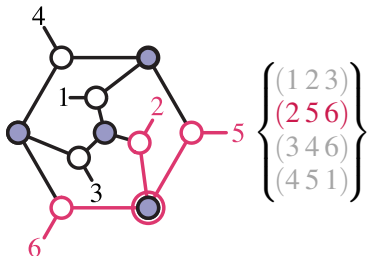
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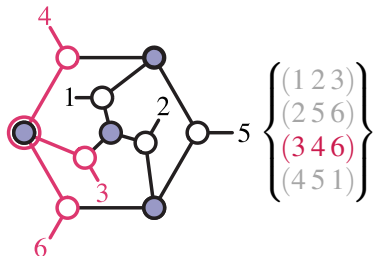
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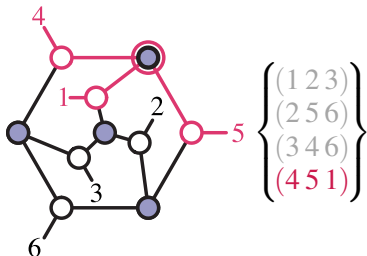
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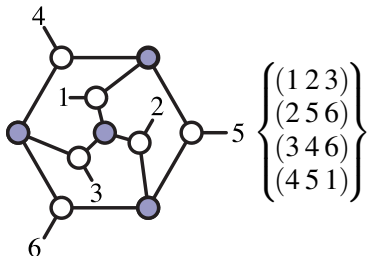
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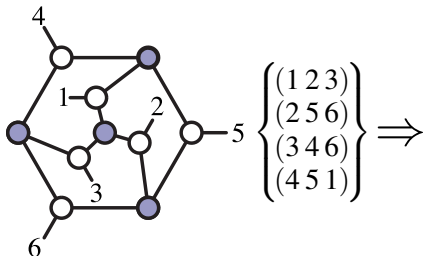
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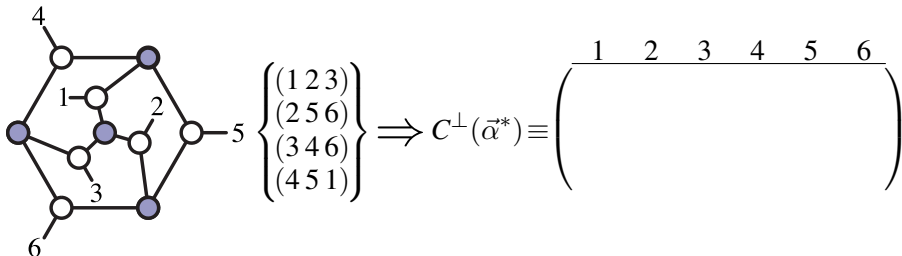
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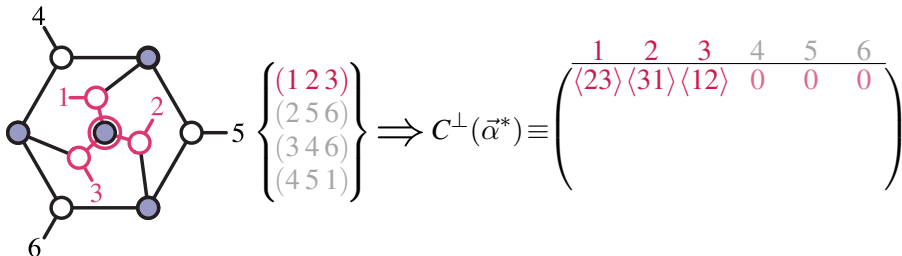
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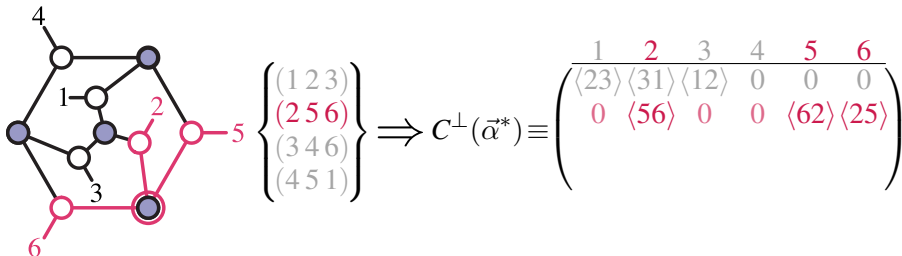
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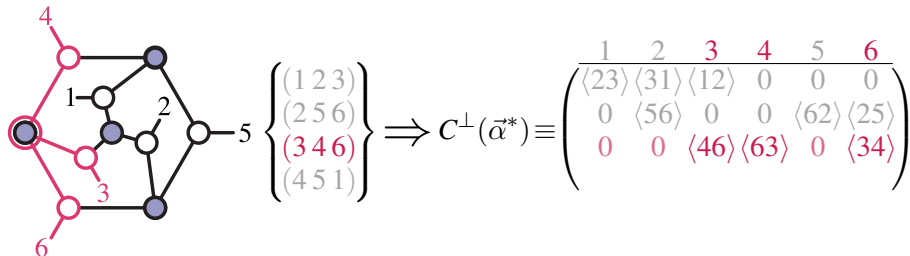
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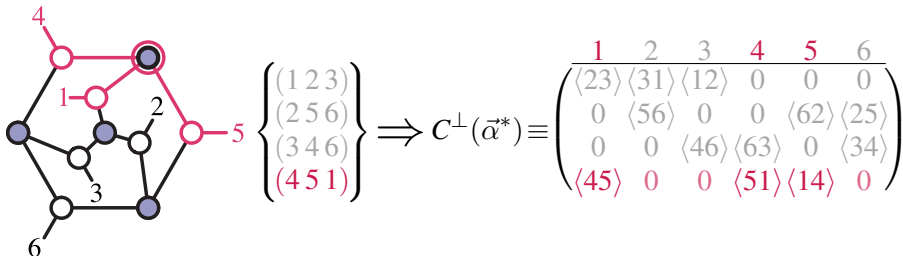
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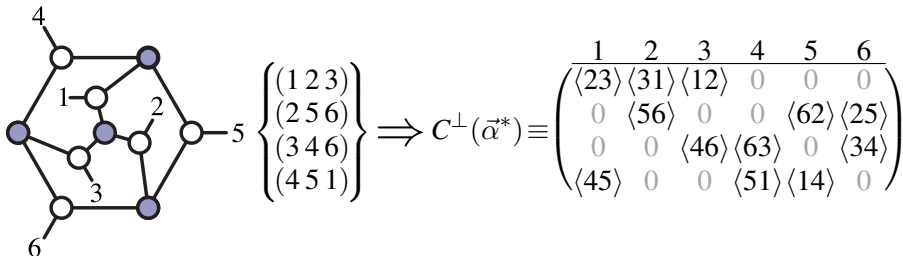
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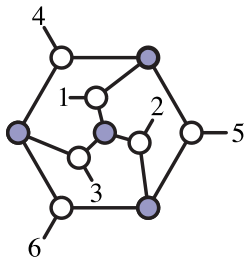
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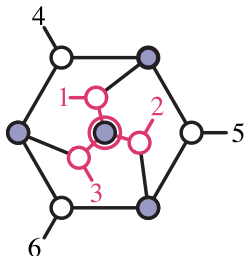
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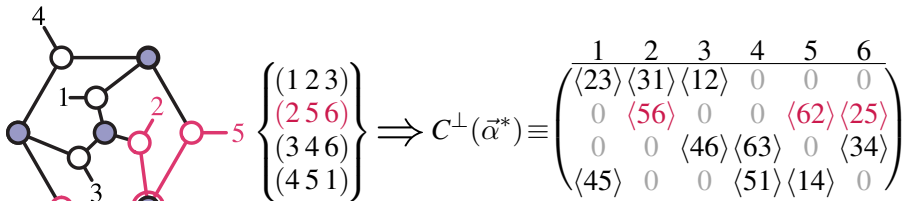
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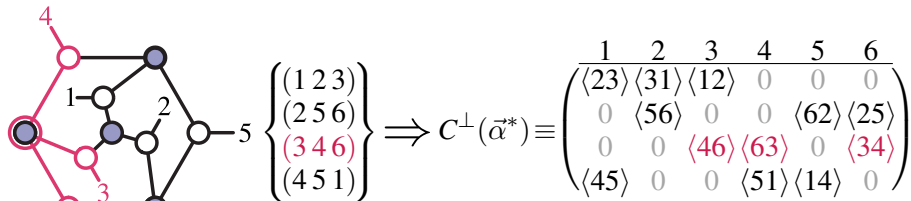
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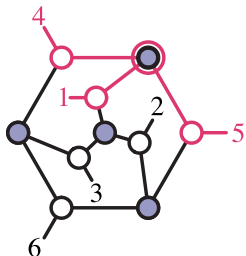
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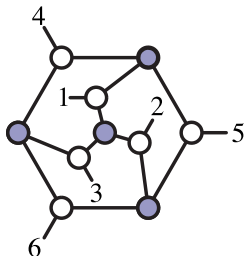
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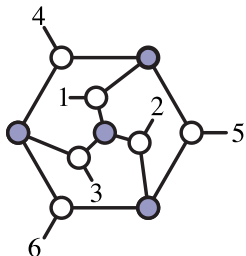
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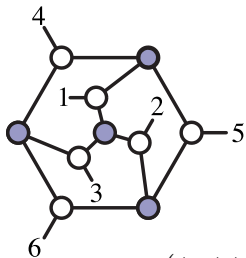
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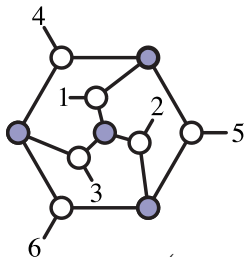
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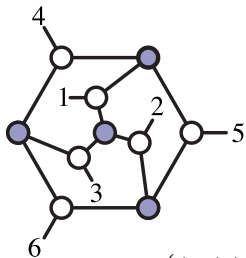
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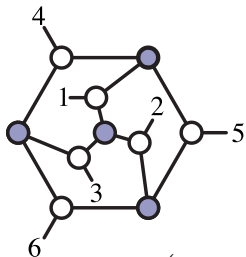
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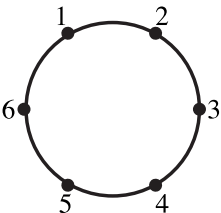
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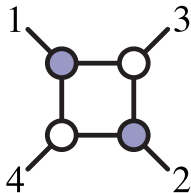
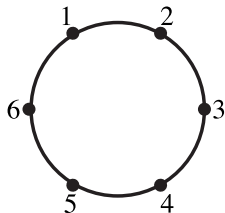
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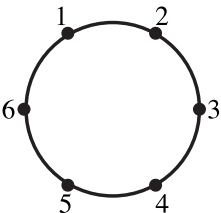
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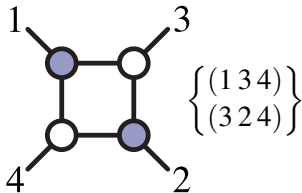
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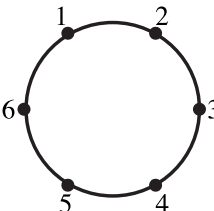
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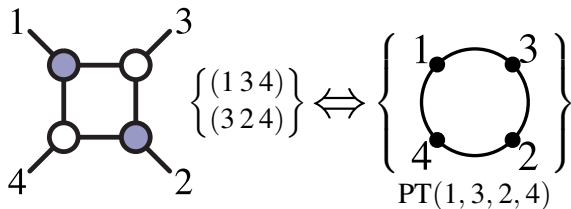
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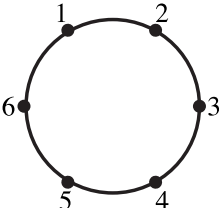
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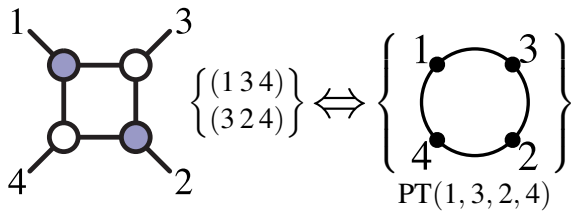
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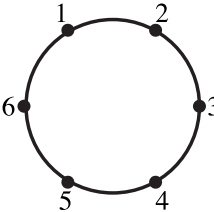
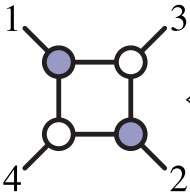
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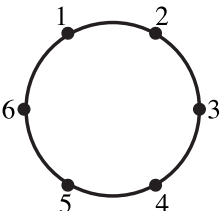
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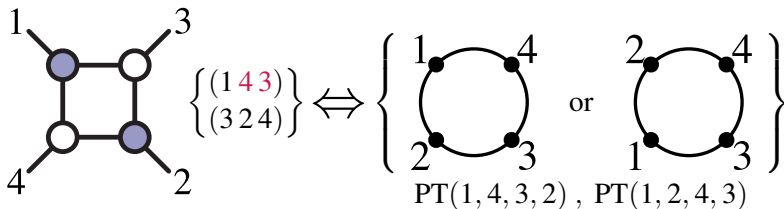
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$$\left\{ \begin{matrix} (1\ 4\ 3) \\ (3\ 2\ 4) \end{matrix} \right\} \Leftrightarrow \left\{ \begin{matrix} \text{PT}(1, 4, 3, 2) & \text{or} & \text{PT}(1, 2, 4, 3) \end{matrix} \right\}$$

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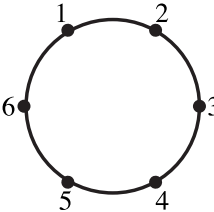
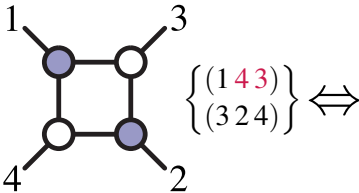
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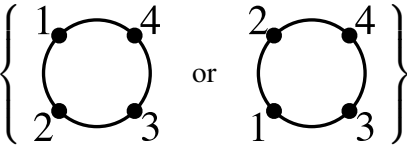




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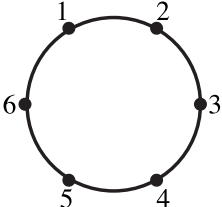
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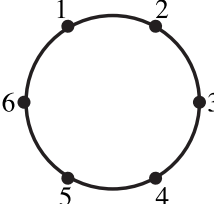
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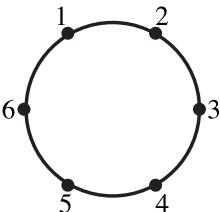
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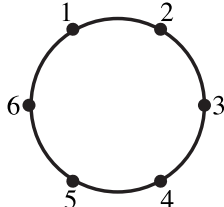
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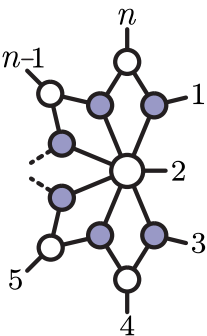
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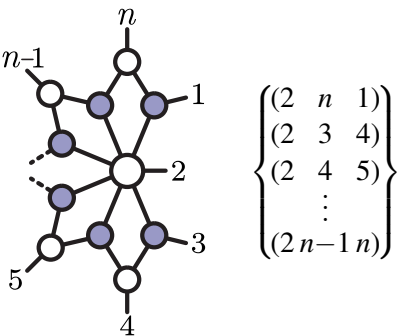
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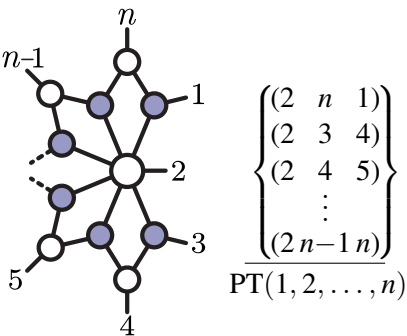
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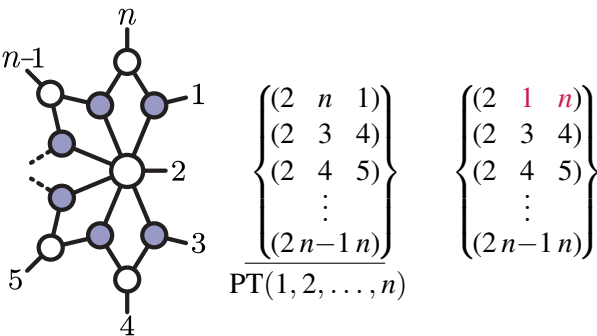
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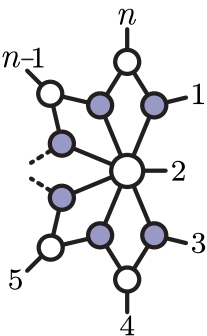
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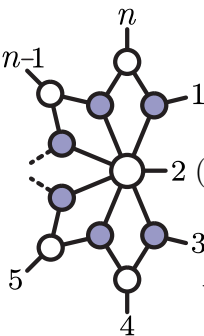
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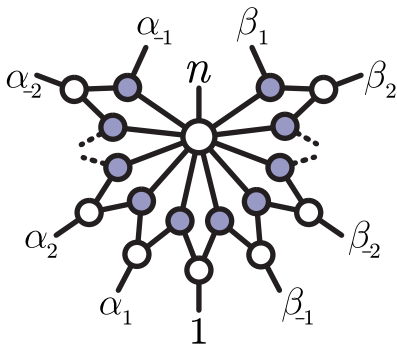
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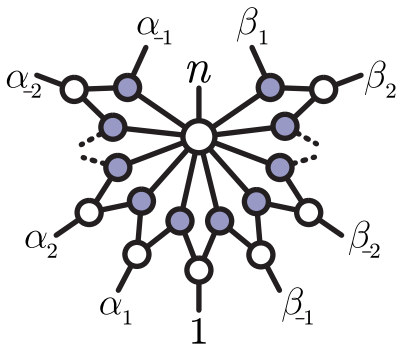
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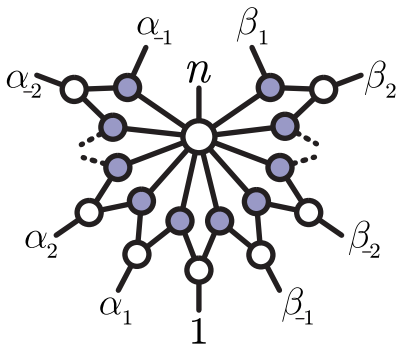
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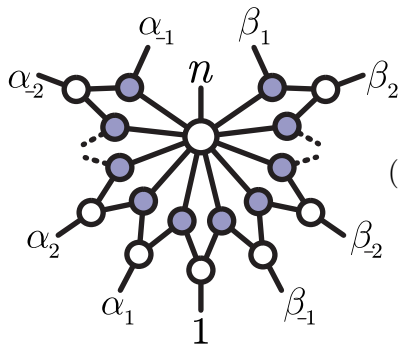
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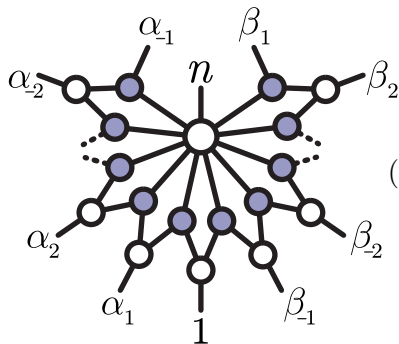
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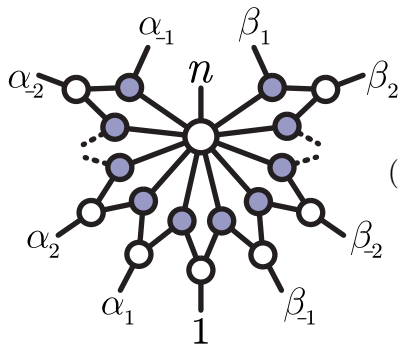


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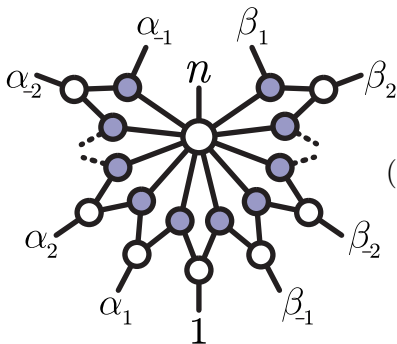


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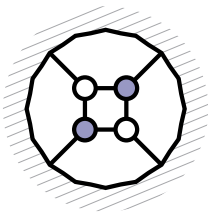
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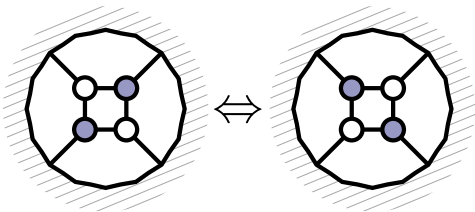
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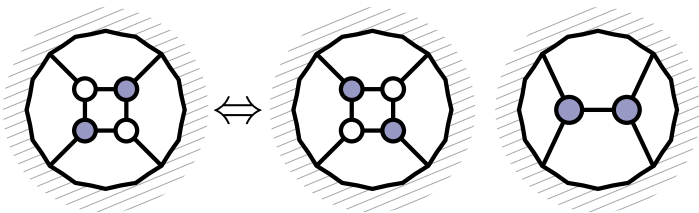
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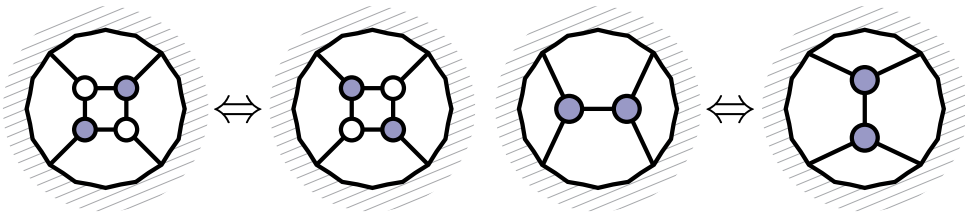
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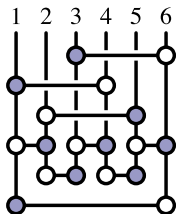
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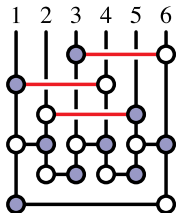
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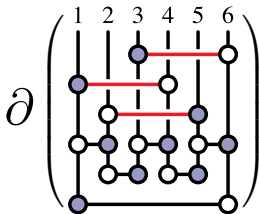
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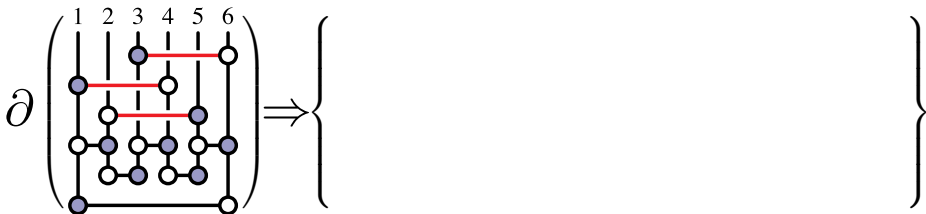
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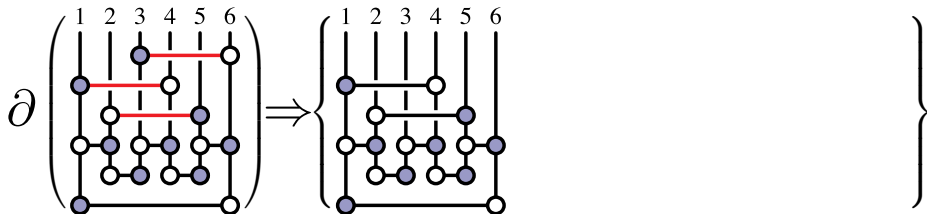
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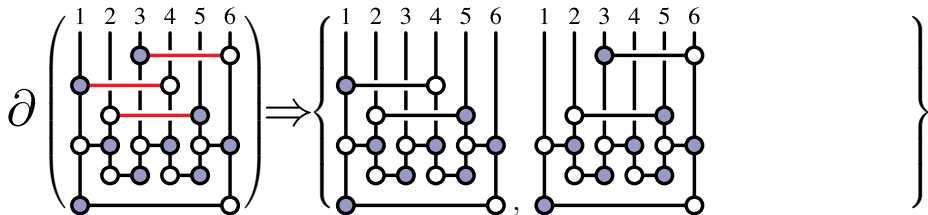
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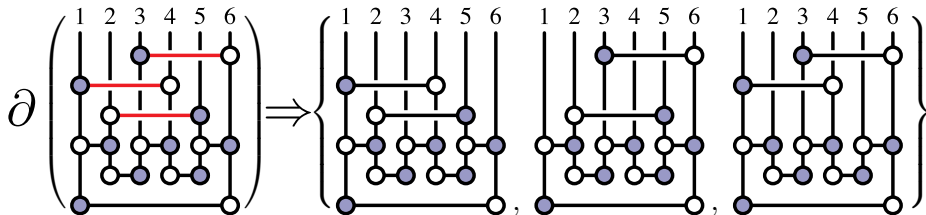
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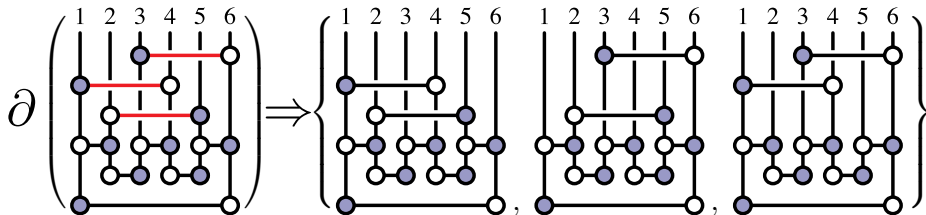
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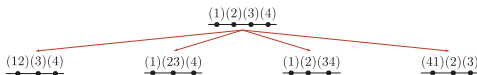
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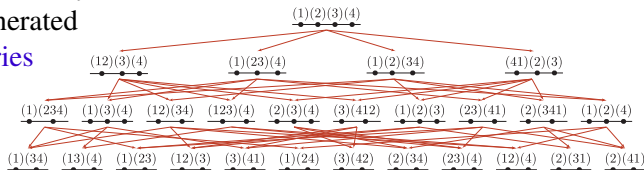
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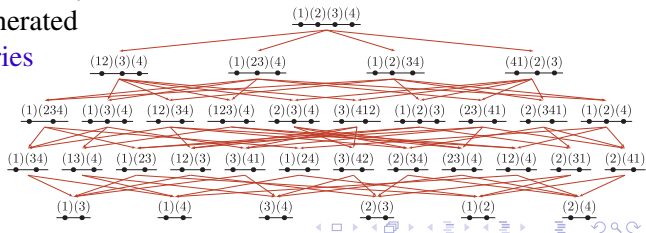
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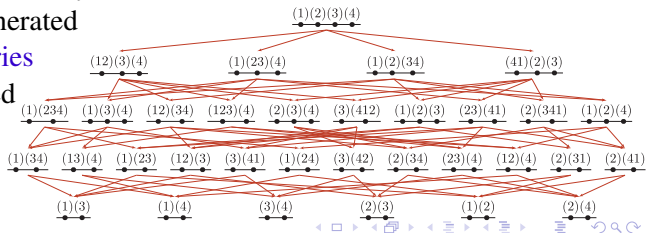
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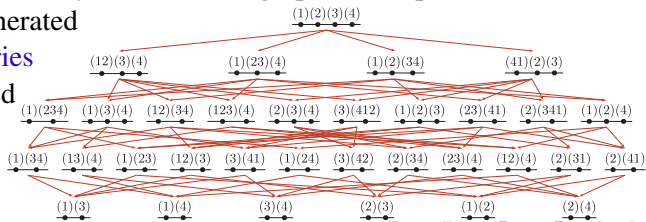
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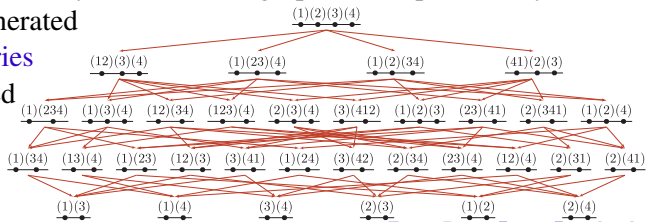
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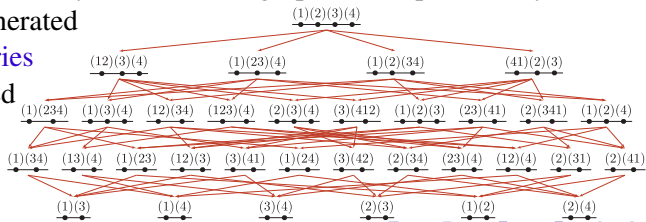
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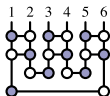
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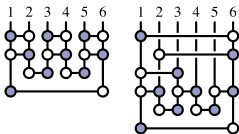
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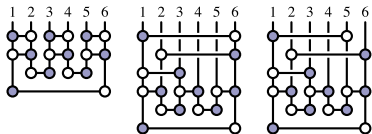
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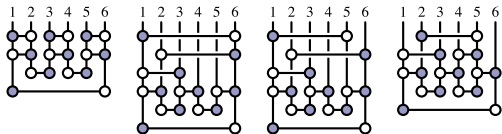
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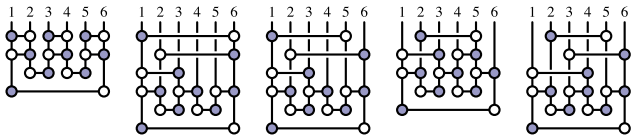


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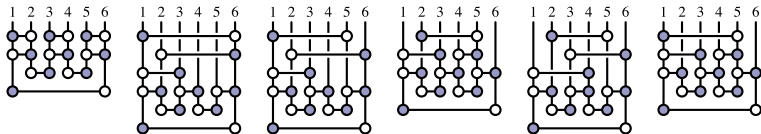




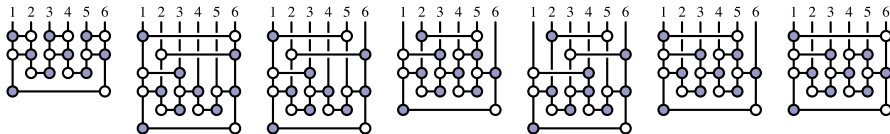
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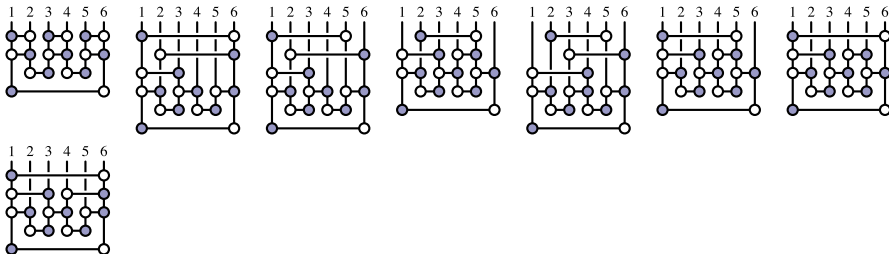
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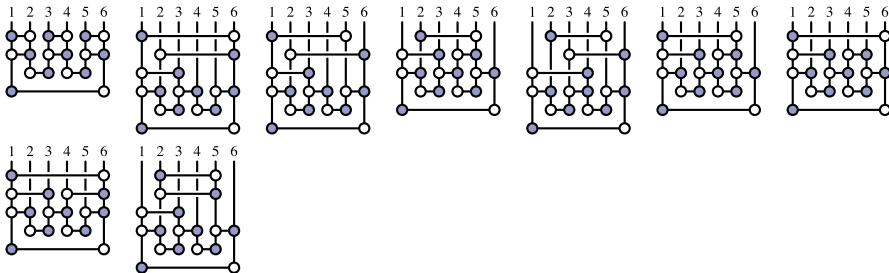
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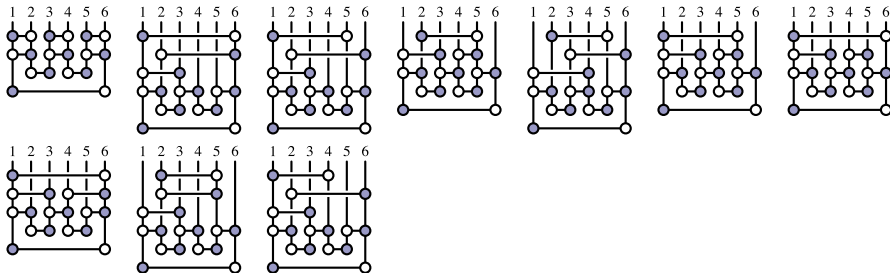
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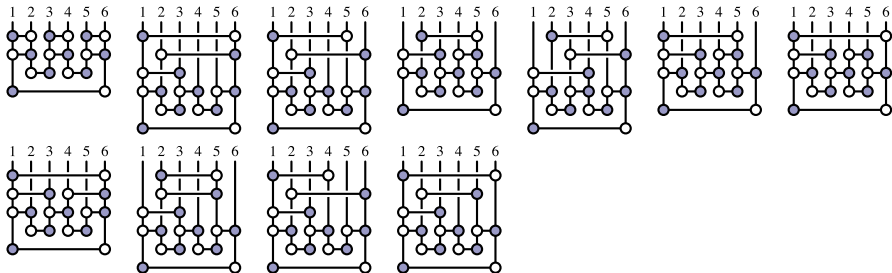
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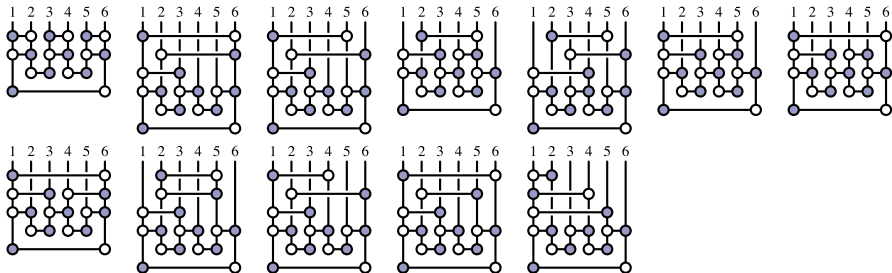
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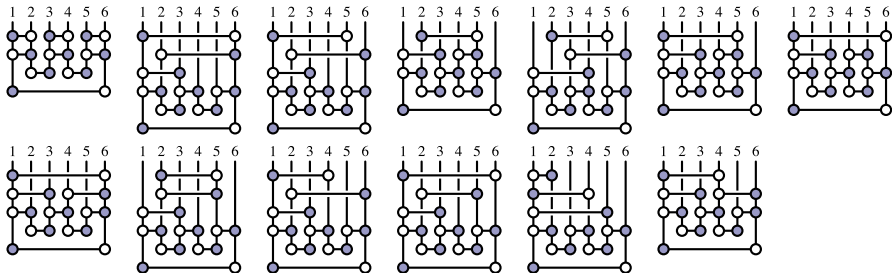


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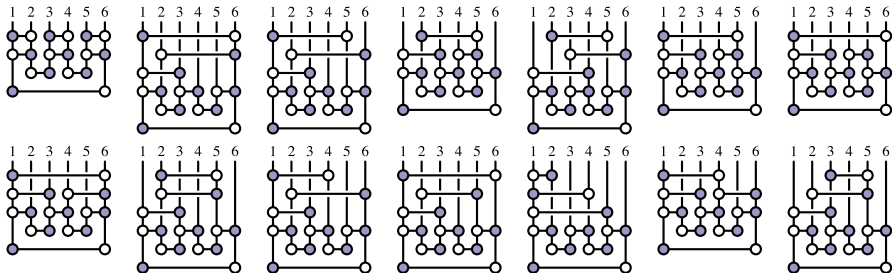




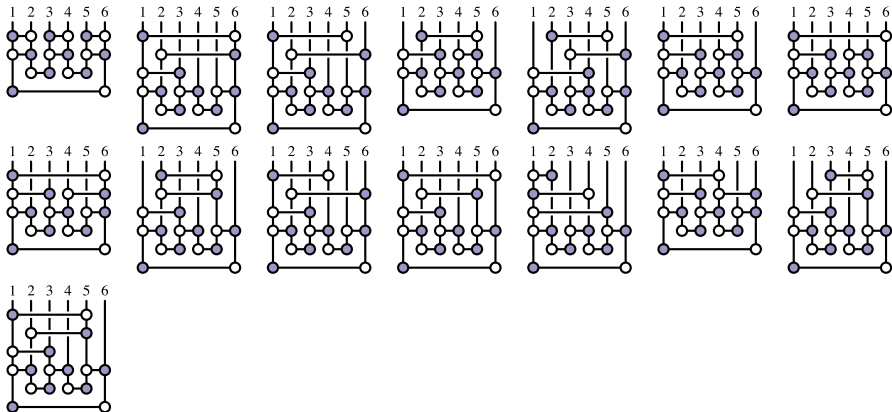
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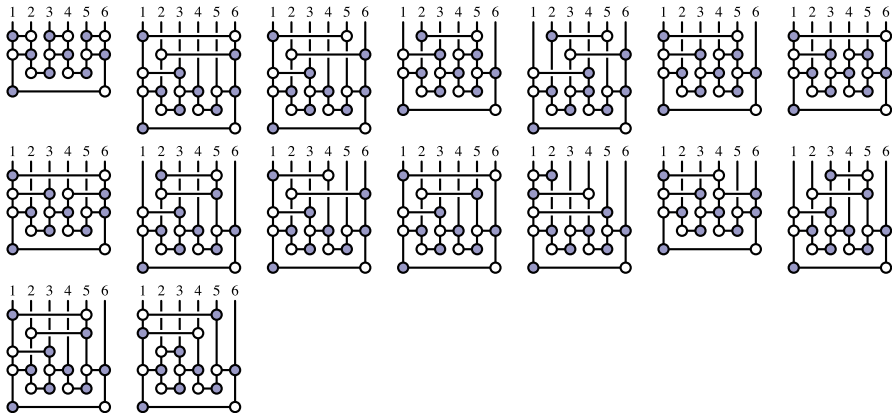
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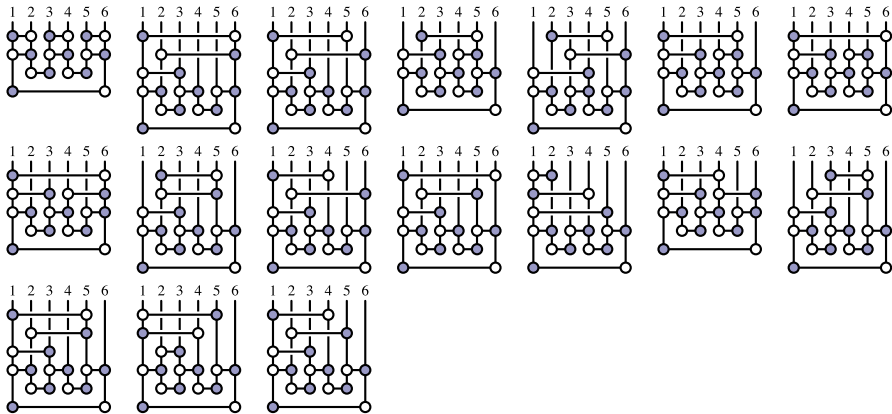
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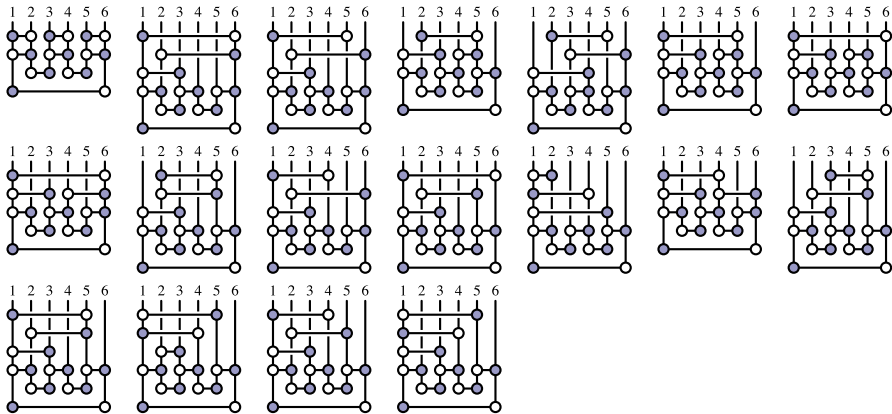
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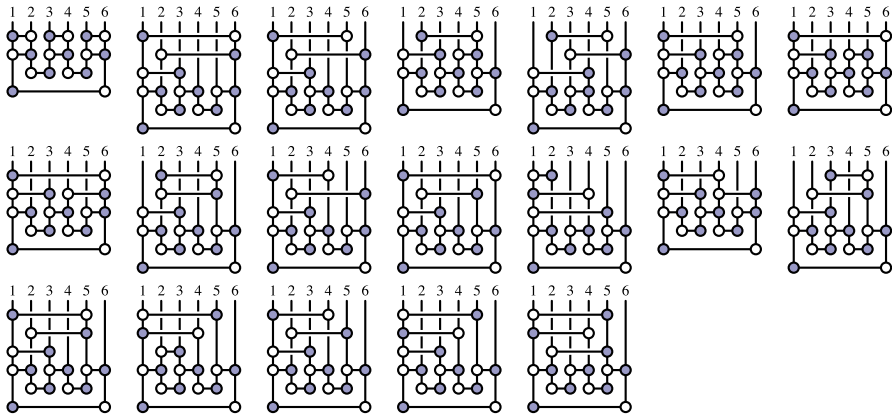
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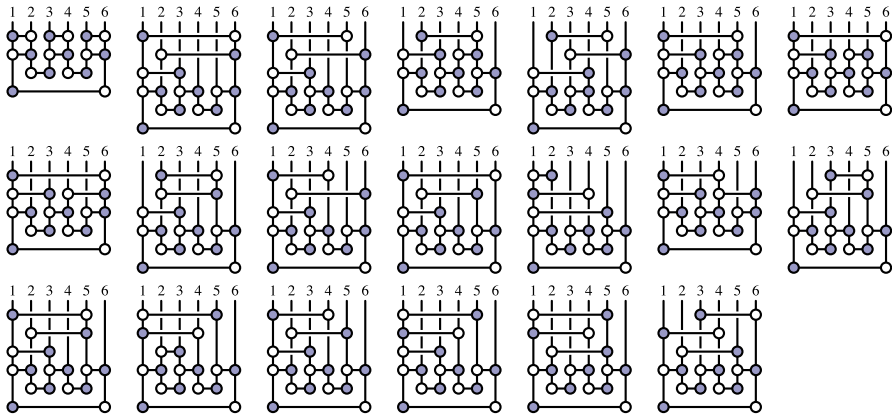
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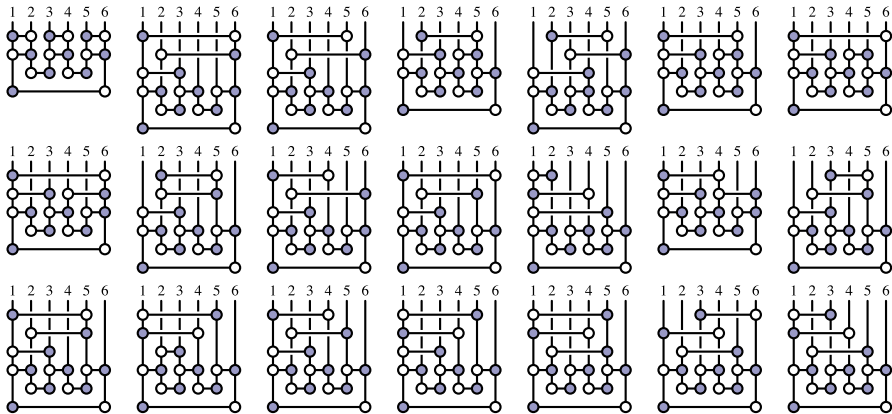


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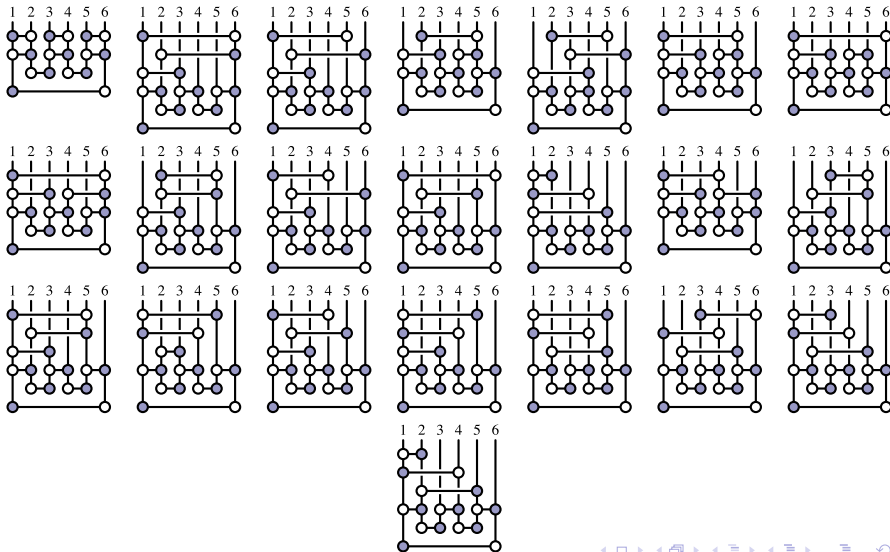




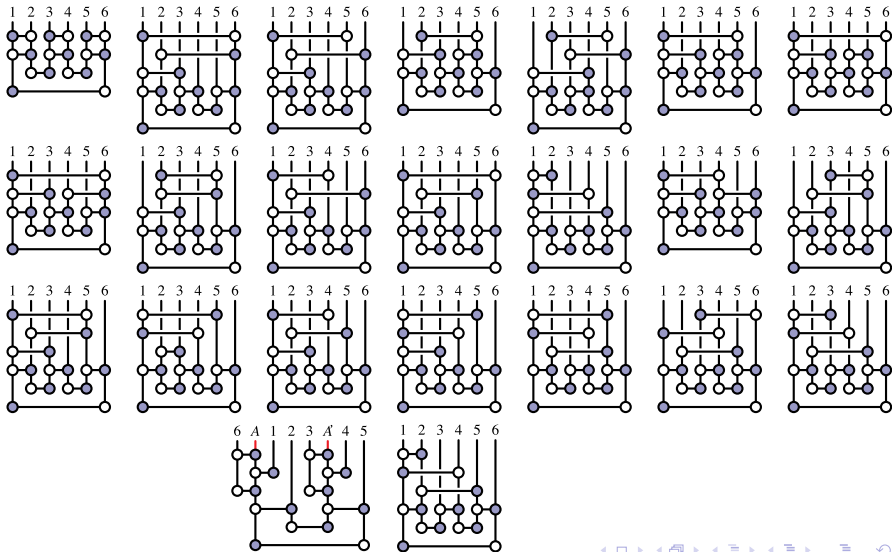
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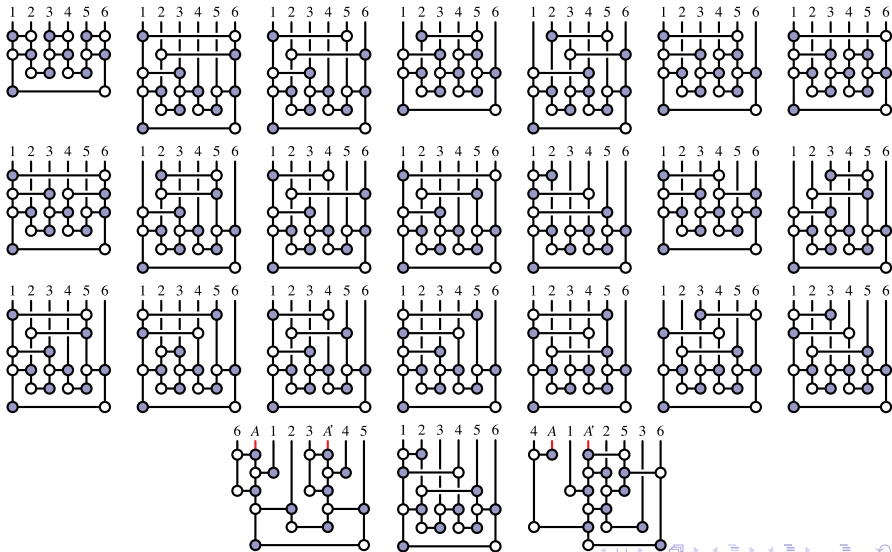
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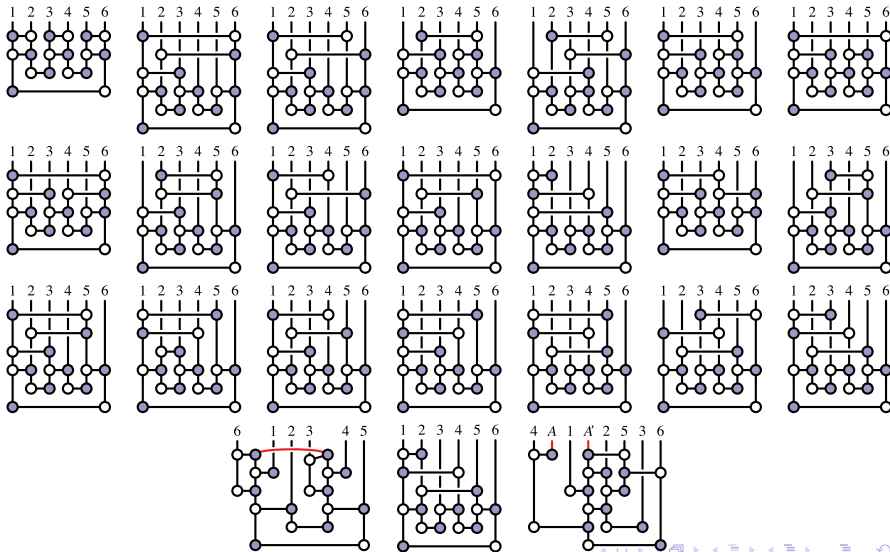
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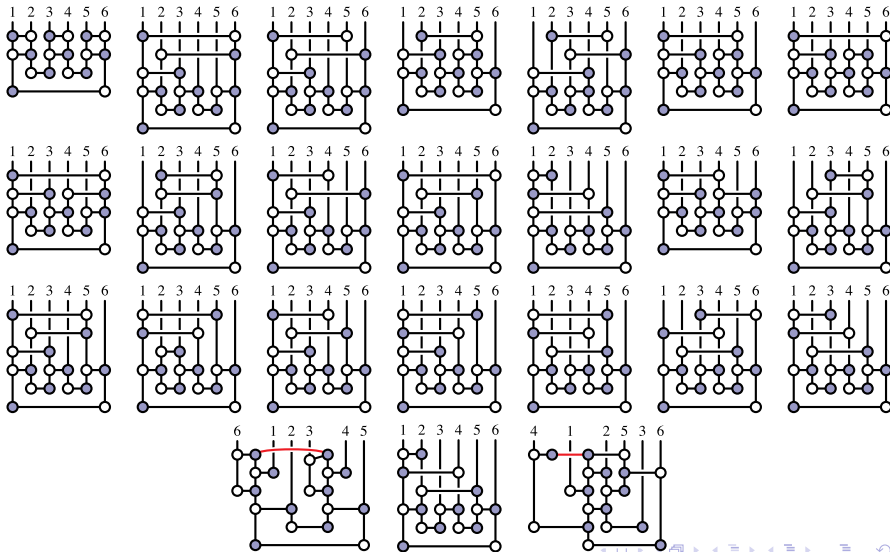
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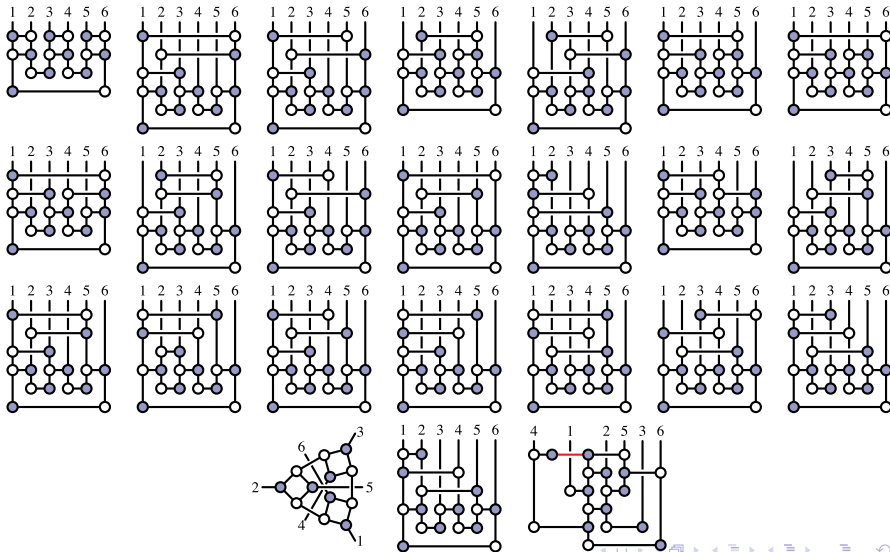
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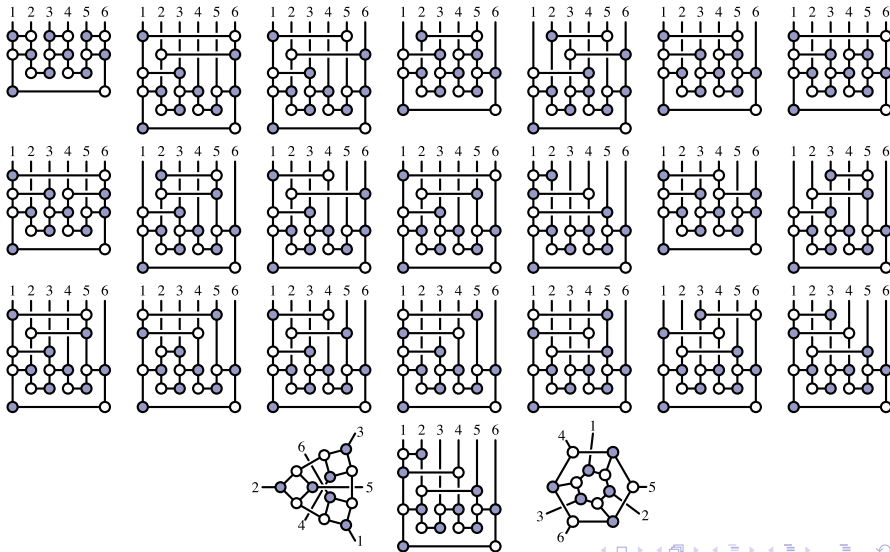
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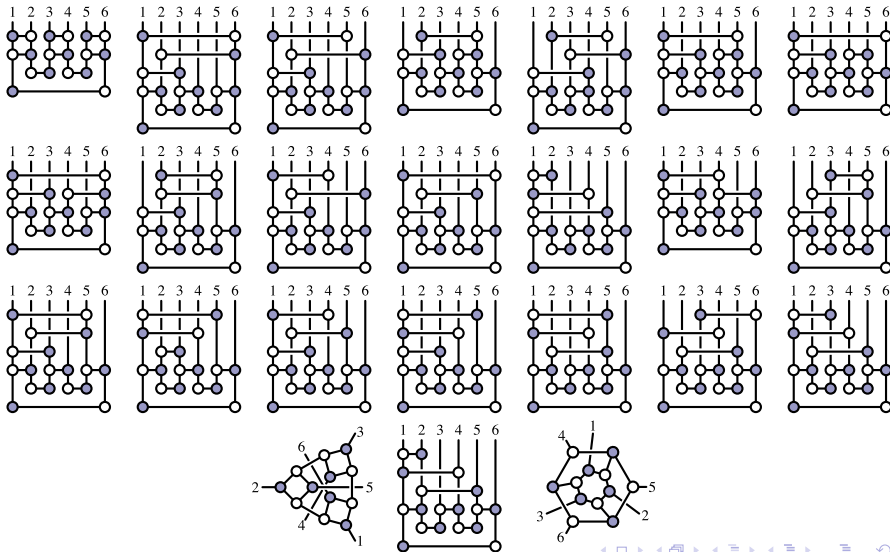


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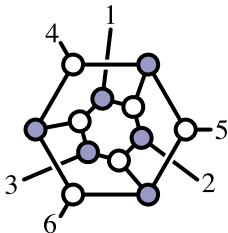


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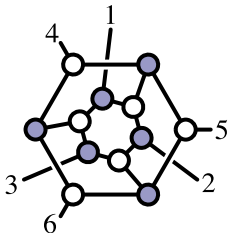
## Novel Boundary Structures for On-Shell Varieties in $G(3, 6)$

There is one especially interesting on-shell variety—associated with the graph:



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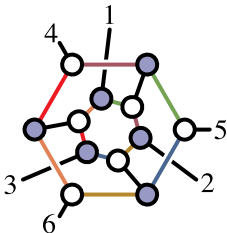
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It has **twelve** removable edges

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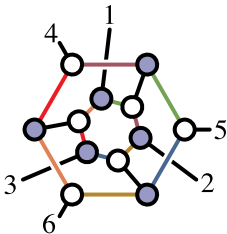
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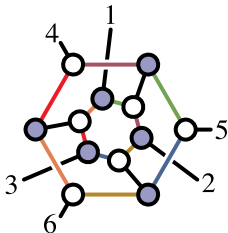
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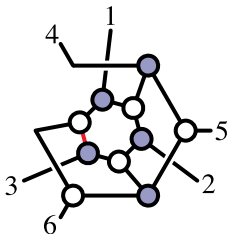
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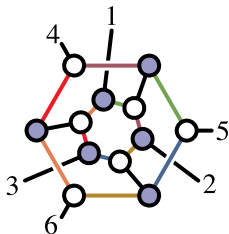


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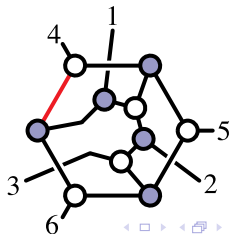
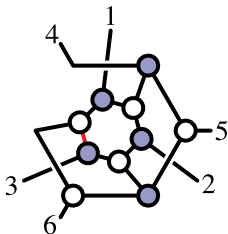


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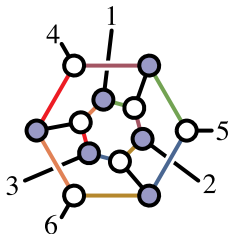


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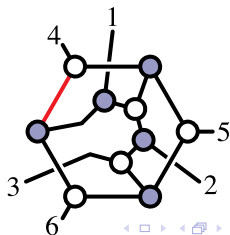
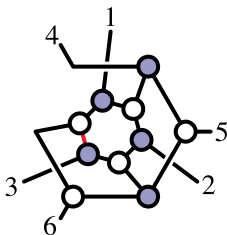


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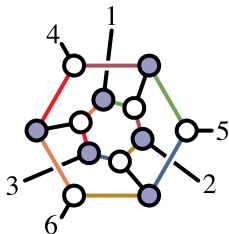
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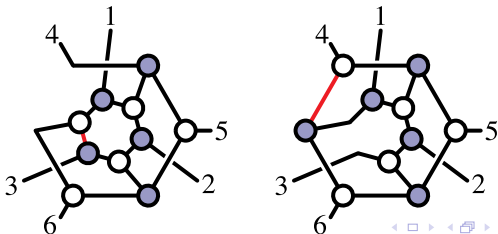


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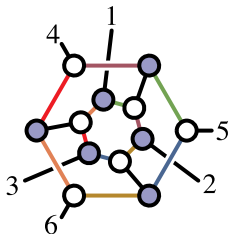


It has **twelve** removable edges, but only **six (non-isomorphic)** boundaries(!)

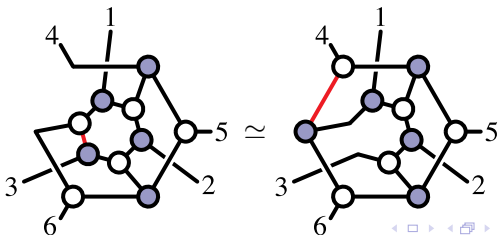


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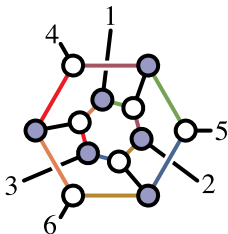


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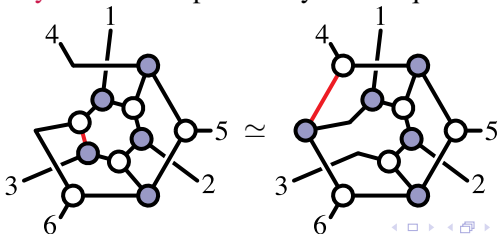


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It has **twelve** removable edges, but only **six (non-isomorphic)** boundaries(!)  
 They are **oppositely oriented**: separated by **three** square moves.



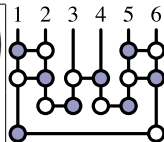
# Enumeration of (8-dim) ‘Leading Singularities’ of $G(3,6)$

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$$f_1 \equiv \oint_{(123)=0} \Omega_1 = \frac{\delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{(234)(345)(456)(561)(612)} \Big|_{C^*}$$

$$= \frac{\delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{\langle 23 \rangle [56] \langle 3|4+5|6 \rangle s_{456} \langle 1|5+6|4 \rangle \langle 12 \rangle [45]}$$

$$C^* \equiv \begin{pmatrix} \lambda_1^1 & \lambda_2^1 & \lambda_3^1 & \lambda_4^1 & \lambda_5^1 & \lambda_6^1 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 & \lambda_5^2 & \lambda_6^2 \\ 0 & 0 & 0 & [56] & [64] & [45] \end{pmatrix}$$

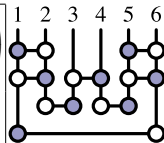


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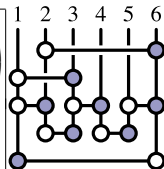
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$$f_2 \equiv \oint_{(123)=0} \Omega_2 = \frac{(235) \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{(136)(156)(234)(245)(256)(345)} \Big|_{C^*}$$

$$= \frac{\langle 23 \rangle [64] \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{\langle 13 \rangle [45] \langle 1|5+6|4 \rangle \langle 23 \rangle [56] \langle 2|4+5|6 \rangle \langle 2|5+6|4 \rangle \langle 3|4+5|6 \rangle}$$

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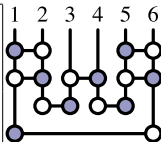


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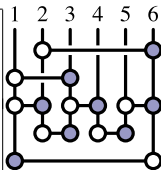
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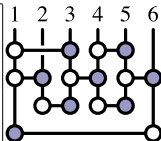
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$$f_3 \equiv \oint_{(123)=0} \Omega_4 = \frac{(145) \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{(124)(136)(156)(245)(345)(456)} \Big|_{C^*}$$

$$= \frac{\langle 1|4+5|6 \rangle \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{\langle 12 \rangle [56] \langle 13 \rangle [45] \langle 1|5+6|4 \rangle \langle 2|4+5|6 \rangle \langle 3|4+5|6 \rangle s_{456}}$$

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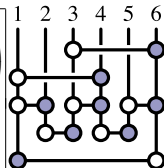


# Enumeration of (8-dim) ‘Leading Singularities’ of $G(3,6)$

$$f_4 \equiv \oint_{(123)=0} \Omega_5 = \frac{(135) \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{(124)(145)(156)(236)(345)(356)} \Big|_{C^*}$$

$$= \frac{\langle 13 \rangle [64] \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{\langle 12 \rangle [56] \langle 1|4+5|6 \rangle \langle 1|5+6|4 \rangle \langle 23 \rangle [45] \langle 3|4+5|6 \rangle \langle 3|5+6|4 \rangle}$$

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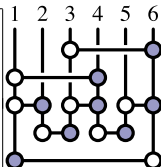


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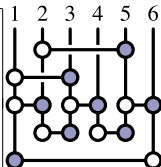
$$C^* \equiv \begin{pmatrix} \lambda_1^1 & \lambda_2^1 & \lambda_3^1 & \lambda_4^1 & \lambda_5^1 & \lambda_6^1 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 & \lambda_5^2 & \lambda_6^2 \\ 0 & 0 & 0 & [56] & [64] & [45] \end{pmatrix}$$



$$f_5 \equiv \oint_{(123)=0} \Omega_9 = \frac{(125) \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{(134)(156)(245)(256)(16(25) \cap (34))} \Big|_{C^*}$$

$$= \frac{\langle 12 \rangle [64] \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{\langle 13 \rangle [56] \langle 1|5+6|4 \rangle \langle 2|4+5|6 \rangle \langle 2|5+6|4 \rangle (\langle 23 \rangle [56] \langle 1|5+6|4 \rangle - \langle 12 \rangle [45] \langle 3|4+5|6 \rangle)}$$

$$C^* \equiv \begin{pmatrix} \lambda_1^1 & \lambda_2^1 & \lambda_3^1 & \lambda_4^1 & \lambda_5^1 & \lambda_6^1 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 & \lambda_5^2 & \lambda_6^2 \\ 0 & 0 & 0 & [56] & [64] & [45] \end{pmatrix}$$

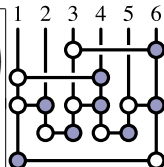


# Enumeration of (8-dim) 'Leading Singularities' of $G(3,6)$

$$f_4 \equiv \oint_{(123)=0} \Omega_5 = \frac{(135) \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{(124)(145)(156)(236)(345)(356)} \Big|_{C^*}$$

$$= \frac{\langle 13 \rangle [64] \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{\langle 12 \rangle [56] \langle 1|4+5|6 \rangle \langle 1|5+6|4 \rangle \langle 23 \rangle [45] \langle 3|4+5|6 \rangle \langle 3|5+6|4 \rangle}$$

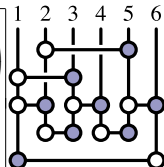
$$C^* \equiv \begin{pmatrix} \lambda_1^1 & \lambda_2^1 & \lambda_3^1 & \lambda_4^1 & \lambda_5^1 & \lambda_6^1 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 & \lambda_5^2 & \lambda_6^2 \\ 0 & 0 & 0 & [56] & [64] & [45] \end{pmatrix}$$



$$f_5 \equiv \oint_{(123)=0} \Omega_9 = \frac{(125) \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{(134)(156)(245)(256)(16(25) \cap (34))} \Big|_{C^*}$$

$$= \frac{\langle 12 \rangle [64] \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{\langle 13 \rangle [56] \langle 1|5+6|4 \rangle \langle 2|4+5|6 \rangle \langle 2|5+6|4 \rangle (\langle 23 \rangle [56] \langle 1|5+6|4 \rangle - \langle 12 \rangle [45] \langle 3|4+5|6 \rangle)}$$

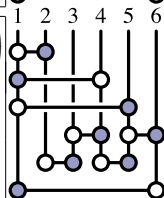
$$C^* \equiv \begin{pmatrix} \lambda_1^1 & \lambda_2^1 & \lambda_3^1 & \lambda_4^1 & \lambda_5^1 & \lambda_6^1 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 & \lambda_5^2 & \lambda_6^2 \\ 0 & 0 & 0 & [56] & [64] & [45] \end{pmatrix}$$



$$f_6 \equiv \oint_{(123)=0} \Omega_{12} = \frac{(134)^2 (456) \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{(124)(145)(146)(156)(234)(345)(346)(356)} \Big|_{C^*}$$

$$= \frac{\langle 13 \rangle^2 s_{456} \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{\langle 12 \rangle \langle 1|4+5|6 \rangle \langle 1|4+6|5 \rangle \langle 1|5+6|4 \rangle \langle 23 \rangle \langle 3|4+5|6 \rangle \langle 3|4+6|5 \rangle \langle 3|5+6|4 \rangle}$$

$$C^* \equiv \begin{pmatrix} \lambda_1^1 & \lambda_2^1 & \lambda_3^1 & \lambda_4^1 & \lambda_5^1 & \lambda_6^1 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 & \lambda_5^2 & \lambda_6^2 \\ 0 & 0 & 0 & [56] & [64] & [45] \end{pmatrix}$$

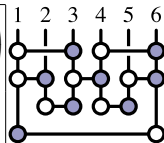


# Enumeration of (8-dim) ‘Leading Singularities’ of $G(3,6)$

$$f_{\tilde{\eta}} \equiv \oint_{(123)=0} \Omega_{13} = \frac{(145)^2 \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{(125)(134)(146)(156)(245)(345)(456)} \Big|_{C^*}$$

$$= \frac{\langle 1|4+5|6 \rangle^2 \delta^{3 \times 4}(C^* \cdot \tilde{\eta}) \delta^{2 \times 2}(\lambda \cdot \tilde{\lambda})}{\langle 12 \rangle [64] \langle 13 \rangle [56] \langle 1|4+6|5 \rangle \langle 1|5+6|4 \rangle \langle 2|4+5|6 \rangle \langle 3|4+5|6 \rangle s_{456}}$$

$$C^* \equiv \begin{pmatrix} \lambda_1^1 & \lambda_2^1 & \lambda_3^1 & \lambda_4^1 & \lambda_5^1 & \lambda_6^1 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 & \lambda_5^2 & \lambda_6^2 \\ 0 & 0 & 0 & [56] & [64] & [45] \end{pmatrix}$$

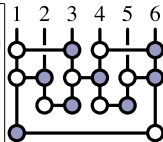


# Enumeration of (8-dim) ‘Leading Singularities’ of $G(3,6)$

$$f_7 \equiv \oint_{(123)=0} \Omega_{13} = \frac{(145)^2 \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{(125)(134)(146)(156)(245)(345)(456)} \Big|_{C^*}$$

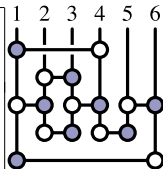
$$C^* \equiv \begin{pmatrix} \lambda_1^1 & \lambda_2^1 & \lambda_3^1 & \lambda_4^1 & \lambda_5^1 & \lambda_6^1 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 & \lambda_5^2 & \lambda_6^2 \\ 0 & 0 & 0 & [56] & [64] & [45] \end{pmatrix}$$

$$= \frac{\langle 1|4+5|6 \rangle^2 \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{\langle 12 \rangle [64] \langle 13 \rangle [56] \langle 1|4+6|5 \rangle \langle 1|5+6|4 \rangle \langle 2|4+5|6 \rangle \langle 3|4+5|6 \rangle s_{456}}$$



$$f_8 \equiv \oint_{(14(23) \cap (56))=0} \Omega_{16} = \int \frac{d\alpha_1}{\alpha_1} \wedge \dots \wedge \frac{d\alpha_8}{\alpha_8} \delta^{3 \times 4} (C(\alpha) \cdot \tilde{\eta}) \delta^{3 \times 2} (C(\alpha) \cdot \tilde{\lambda}) \delta^{2 \times 3} (\lambda \cdot C^\perp(\alpha))$$

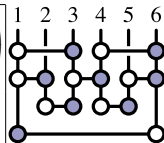
$$C(\alpha) \equiv \begin{pmatrix} 1 & \alpha_6 & \alpha_6 \alpha_7 & 0 & 0 & \alpha_1 \\ 0 & 1 & \alpha_5 + \alpha_7 & 0 & \alpha_2 & \alpha_2 \alpha_4 \\ \alpha_8 & 0 & 0 & 1 & \alpha_3 & \alpha_3 \alpha_4 \end{pmatrix}$$



# Enumeration of (8-dim) 'Leading Singularities' of $G(3,6)$

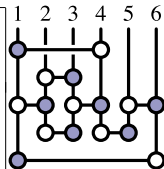
$$f_7 \equiv \oint_{(123)=0} \Omega_{13} = \frac{(145)^2 \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{(125)(134)(146)(156)(245)(345)(456)} \Big|_{C^*} \quad C^* \equiv \begin{pmatrix} \lambda_1^1 & \lambda_2^1 & \lambda_3^1 & \lambda_4^1 & \lambda_5^1 & \lambda_6^1 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 & \lambda_5^2 & \lambda_6^2 \\ 0 & 0 & 0 & [56] & [64] & [45] \end{pmatrix}$$

$$= \frac{\langle 1|4+5|6 \rangle^2 \delta^{3 \times 4} (C^* \cdot \tilde{\eta}) \delta^{2 \times 2} (\lambda \cdot \tilde{\lambda})}{\langle 12 \rangle [64] \langle 13 \rangle [56] \langle 1|4+6|5 \rangle \langle 1|5+6|4 \rangle \langle 2|4+5|6 \rangle \langle 3|4+5|6 \rangle s_{456}}$$



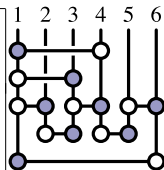
$$f_8 \equiv \oint_{(14(23) \cap (56))=0} \Omega_{16} = \int \frac{d\alpha_1}{\alpha_1} \wedge \dots \wedge \frac{d\alpha_8}{\alpha_8} \delta^{3 \times 4} (C(\alpha) \cdot \tilde{\eta}) \delta^{3 \times 2} (C(\alpha) \cdot \tilde{\lambda}) \delta^{2 \times 3} (\lambda \cdot C^\perp(\alpha))$$

$$C(\alpha) \equiv \begin{pmatrix} 1 & \alpha_6 & \alpha_6 \alpha_7 & 0 & 0 & \alpha_1 \\ 0 & 1 & \alpha_5 + \alpha_7 & 0 & \alpha_2 & \alpha_2 \alpha_4 \\ \alpha_8 & 0 & 0 & 1 & \alpha_3 & \alpha_3 \alpha_4 \end{pmatrix}$$



$$f_9 \equiv \oint_{(14(23) \cap (56))=0} \Omega_{18} = \int \frac{d\alpha_1}{\alpha_1} \wedge \dots \wedge \frac{d\alpha_8}{\alpha_8} \delta^{3 \times 4} (C(\alpha) \cdot \tilde{\eta}) \delta^{3 \times 2} (C(\alpha) \cdot \tilde{\lambda}) \delta^{2 \times 3} (\lambda \cdot C^\perp(\alpha))$$

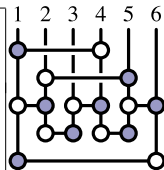
$$C(\alpha) \equiv \begin{pmatrix} 1 & \alpha_5 & \alpha_7 & 0 & 0 & \alpha_1 \\ 0 & 1 & \alpha_4 & 0 & \alpha_2 & \alpha_2 \alpha_6 \\ \alpha_8 & 0 & 0 & 1 & \alpha_3 & \alpha_3 \alpha_6 \end{pmatrix}$$



# Enumeration of (8-dim) ‘Leading Singularities’ of $G(3,6)$

$$f_{10} \equiv \oint_{z=0} \Omega_{20} = \int \frac{d\alpha_1}{\alpha_1} \wedge \dots \wedge \frac{d\alpha_8}{\alpha_8} \delta^{3 \times 4}(C(\alpha) \cdot \tilde{\eta}) \delta^{3 \times 2}(C(\alpha) \cdot \tilde{\lambda}) \delta^{2 \times 3}(\lambda \cdot C^\perp(\alpha))$$

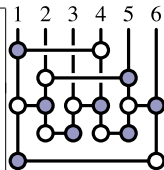
$$C(\alpha) \equiv \begin{pmatrix} \alpha_6 & \alpha_8 & \alpha_1 & 1 & \alpha_6 & \alpha_1 & \alpha_7 & 0 \\ \alpha_8 & 0 & 0 & 1 & \alpha_5 & \alpha_4 & & \\ \alpha_3 & \alpha_2 & 0 & 0 & \alpha_2 & \alpha_7 & 1 & \end{pmatrix}$$



# Enumeration of (8-dim) ‘Leading Singularities’ of $G(3,6)$

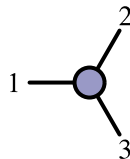
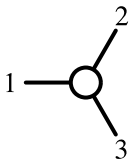
$$f_{10} \equiv \oint_{z=0} \Omega_{20} = \int \frac{d\alpha_1}{\alpha_1} \wedge \dots \wedge \frac{d\alpha_8}{\alpha_8} \delta^{3 \times 4}(C(\alpha) \cdot \tilde{\eta}) \delta^{3 \times 2}(C(\alpha) \cdot \tilde{\lambda}) \delta^{2 \times 3}(\lambda \cdot C^\perp(\alpha))$$

$$C(\alpha) \equiv \begin{pmatrix} \alpha_6 & \alpha_8 & \alpha_1 & 1 & \alpha_6 & \alpha_1 & \alpha_7 & 0 \\ \alpha_8 & 0 & 0 & 1 & \alpha_5 & \alpha_4 & & \\ \alpha_3 & \alpha_2 & 0 & 0 & \alpha_2 & \alpha_7 & 1 & \end{pmatrix}$$



## The (Lie-Algebra) ‘Coloring’ of On-Shell Diagrams

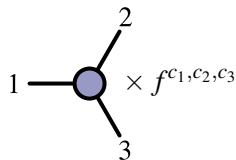
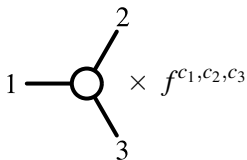
In Yang-Mills theory, states are labelled by (non-kinematic) ‘colors’  $c_a$ ;  
three-point amplitudes depend on these colors via a ‘coupling’  $f^{c_a, c_b, c_c}$





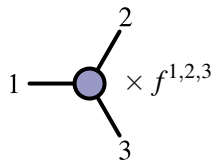
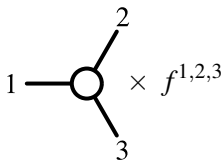
## The (Lie-Algebra) ‘Coloring’ of On-Shell Diagrams

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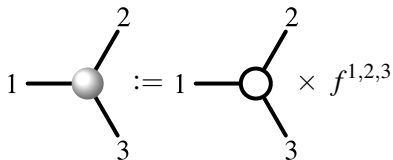
## The (Lie-Algebra) ‘Coloring’ of On-Shell Diagrams

In Yang-Mills theory, states are labelled by (non-kinematic) ‘colors’  $c_a$ ;  
three-point amplitudes depend on these colors via a ‘coupling’  $f^{a,b,c}$



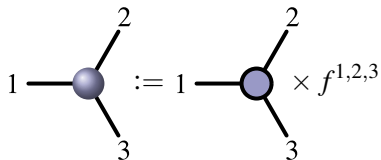
## The (Lie-Algebra) ‘Coloring’ of On-Shell Diagrams

In Yang-Mills theory, states are labelled by (non-kinematic) ‘colors’  $c_a$ ;  
three-point amplitudes depend on these colors via a ‘coupling’  $f^{a,b,c}$



A diagrammatic equation showing a color-stripped three-point vertex. On the left, a grey shaded vertex with three external lines labeled 1, 2, and 3. This is followed by a colon and equals sign, then a white unshaded vertex with the same three external lines, followed by a multiplication sign and the coupling  $f^{1,2,3}$ .

$$\text{Grey Vertex} := \text{White Vertex} \times f^{1,2,3}$$



A diagrammatic equation showing a color-dressed three-point vertex. On the left, a blue shaded vertex with three external lines labeled 1, 2, and 3. This is followed by a colon and equals sign, then a white unshaded vertex with the same three external lines, followed by a multiplication sign and the coupling  $f^{1,2,3}$ .

$$\text{Blue Vertex} := \text{White Vertex} \times f^{1,2,3}$$

## The (Lie-Algebra) ‘Coloring’ of On-Shell Diagrams

In Yang-Mills theory, states are labelled by (non-kinematic) ‘colors’  $c_a$ ;  
three-point amplitudes depend on these colors via a ‘coupling’  $f^{a,b,c}$

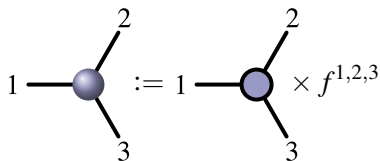
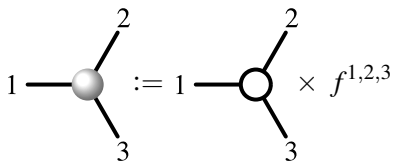
A diagrammatic equation showing a three-point vertex with a grey shaded circle. The left side is a vertex with an incoming line from the left labeled '1', and two outgoing lines to the top-right labeled '2' and bottom-right labeled '3'. This is followed by an equals sign and a diagram of the same vertex but with a white circle, followed by a multiplication sign and the coupling constant  $f^{1,2,3}$ .

A diagrammatic equation showing a three-point vertex with a blue shaded circle. The left side is a vertex with an incoming line from the left labeled '1', and two outgoing lines to the top-right labeled '2' and bottom-right labeled '3'. This is followed by an equals sign and a diagram of the same vertex but with a white circle, followed by a multiplication sign and the coupling constant  $f^{1,2,3}$ .

Consistency implies that these coupling constants obey **Jacobi relations**(!)

## The (Lie-Algebra) ‘Coloring’ of On-Shell Diagrams

In Yang-Mills theory, states are labelled by (non-kinematic) ‘colors’  $c_a$ ;  
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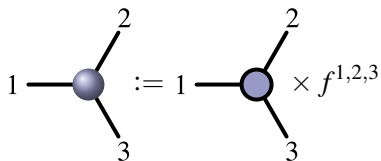
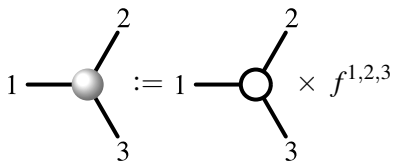


Consistency implies that these coupling constants obey **Jacobi relations**(!)

$$f^{\alpha,\beta,\gamma,\delta} + f^{\beta,\gamma,\alpha,\delta} + f^{\gamma,\alpha,\beta,\delta} = 0$$

## The (Lie-Algebra) ‘Coloring’ of On-Shell Diagrams

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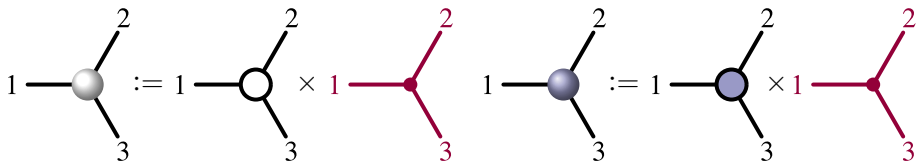


Consistency implies that these coupling constants obey **Jacobi relations**(!)  
 (therefore, these colors transform as the **adjoint** of some Lie algebra!)

$$f^{\alpha,\beta,\gamma,\delta} + f^{\beta,\gamma,\alpha,\delta} + f^{\gamma,\alpha,\beta,\delta} = 0$$

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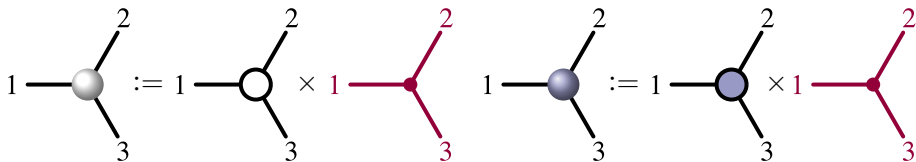


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# The (Lie-Algebra) 'Coloring' of On-Shell Diagrams

In Yang-Mills theory, states are labelled by (non-kinematic) 'colors'  $c_a$ ;  
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Consistency implies that these coupling constants obey **Jacobi relations**(!)  
 (therefore, these colors transform as the **adjoint** of some Lie algebra!)

$$f^{\alpha,\beta,\gamma} + f^{\beta,\gamma,\alpha} + f^{\gamma,\alpha,\beta} = 0$$

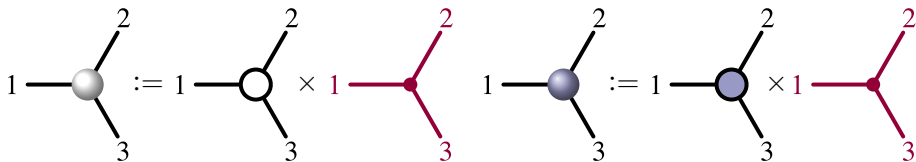
Diagrammatic representation of the Jacobi identity:

$$\text{Diagram 1} + \text{Diagram 2} + \text{Diagram 3} = 0$$



# The (Lie-Algebra) 'Coloring' of On-Shell Diagrams

In Yang-Mills theory, states are labelled by (non-kinematic) 'colors'  $c_a$ ;  
 three-point amplitudes depend on these colors via a 'coupling'  $f^{a,b,c}$



Consistency implies that these coupling constants obey **Jacobi relations**(!)  
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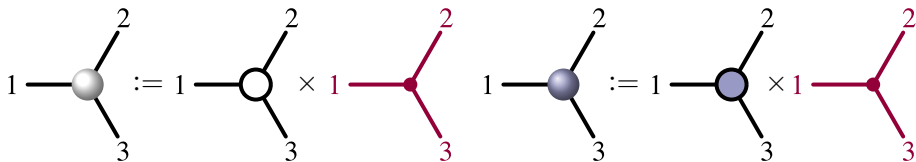
$$f^{\alpha,\beta,\gamma} f^{\gamma,\alpha,\delta} + f^{\beta,\gamma,\alpha} f^{\alpha,\delta,\beta} + f^{\gamma,\alpha,\beta} f^{\beta,\delta,\gamma} = 0$$

Diagrammatic representation of the Jacobi identity:

$$\begin{matrix} \beta \\ / \\ \text{red vertex} \\ \backslash \\ \alpha \end{matrix} \text{---} \begin{matrix} \gamma \\ / \\ \text{red vertex} \\ \backslash \\ \delta \end{matrix} + \begin{matrix} \gamma \\ / \\ \text{red vertex} \\ \backslash \\ \beta \end{matrix} \text{---} \begin{matrix} \alpha \\ / \\ \text{red vertex} \\ \backslash \\ \delta \end{matrix} + \begin{matrix} \alpha \\ / \\ \text{red vertex} \\ \backslash \\ \gamma \end{matrix} \text{---} \begin{matrix} \beta \\ / \\ \text{red vertex} \\ \backslash \\ \delta \end{matrix} = 0$$

# The (Lie-Algebra) 'Coloring' of On-Shell Diagrams

In Yang-Mills theory, states are labelled by (non-kinematic) 'colors'  $c_a$ ;  
 three-point amplitudes depend on these colors via a 'coupling'  $f^{a,b,c}$



Consistency implies that these coupling constants obey **Jacobi relations**(!)  
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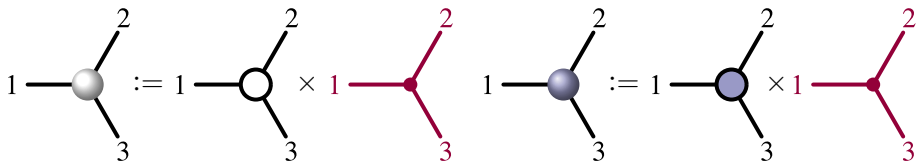
$$f^{\alpha,\beta,\gamma} f^{\gamma,\alpha,\delta} + f^{\beta,\gamma,\alpha} f^{\alpha,\delta,\beta} + f^{\gamma,\alpha,\beta} f^{\beta,\delta,\gamma} = 0$$

Diagrammatic representation of the Jacobi identity:

$$\text{red vertex} \begin{matrix} / \beta \\ \backslash \alpha \end{matrix} \text{---} \text{red vertex} \begin{matrix} / \gamma \\ \backslash \delta \end{matrix} - \text{red vertex} \begin{matrix} / \beta \\ \backslash \alpha \end{matrix} \text{---} \text{red vertex} \begin{matrix} / \gamma \\ \backslash \delta \end{matrix} - \text{red vertex} \begin{matrix} / \gamma \\ \backslash \alpha \end{matrix} \text{---} \text{red vertex} \begin{matrix} / \beta \\ \backslash \delta \end{matrix} = 0$$

# The (Lie-Algebra) 'Coloring' of On-Shell Diagrams

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Consistency implies that these coupling constants obey **Jacobi relations**(!)  
 (therefore, these colors transform as the **adjoint** of some Lie algebra!)

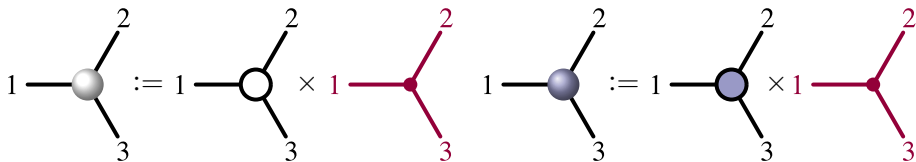
$$f^{\alpha,\beta,\gamma} f^{\gamma,\delta,\alpha} + f^{\beta,\gamma,\alpha} f^{\alpha,\delta,\beta} + f^{\gamma,\alpha,\beta} f^{\beta,\delta,\gamma} = 0$$

Diagrammatic representation of the Jacobi identity:

$$\text{Diagram 1} - \text{Diagram 2} - \text{Diagram 3} = 0$$

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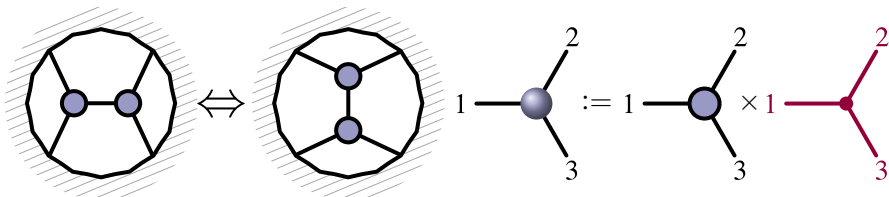
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$$\text{red vertex} \begin{matrix} / \beta \\ \backslash \alpha \end{matrix} \text{---} \text{red vertex} \begin{matrix} / \gamma \\ \backslash \delta \end{matrix} - \text{red vertex} \begin{matrix} / \beta \\ \backslash \alpha \end{matrix} \text{---} \text{red vertex} \begin{matrix} / \gamma \\ \backslash \delta \end{matrix} - \text{red vertex} \begin{matrix} / \gamma \\ \backslash \alpha \end{matrix} \text{---} \text{red vertex} \begin{matrix} / \beta \\ \backslash \delta \end{matrix} = 0$$

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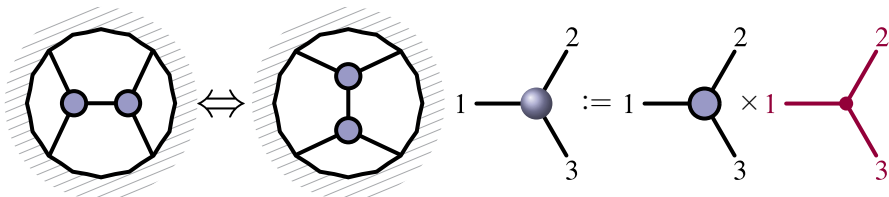
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The diagrammatic representation of the Jacobi identity shows three red vertices with legs  $\alpha, \beta, \gamma, \delta$ . The first vertex has legs  $\alpha, \beta, \gamma$  meeting at a central point, with  $\delta$  as a separate leg. The second vertex has legs  $\beta, \gamma, \alpha$  meeting at a central point, with  $\delta$  as a separate leg. The third vertex has legs  $\gamma, \alpha, \beta$  meeting at a central point, with  $\delta$  as a separate leg. The equation is shown as the first two vertices minus the third vertex equals zero.

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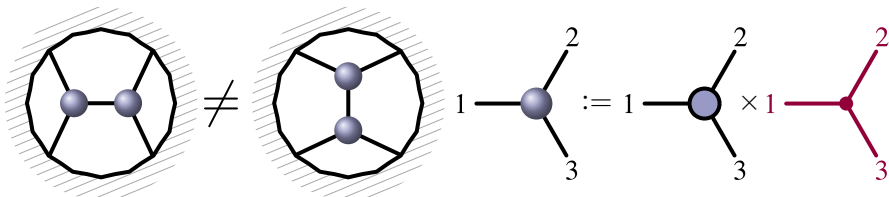


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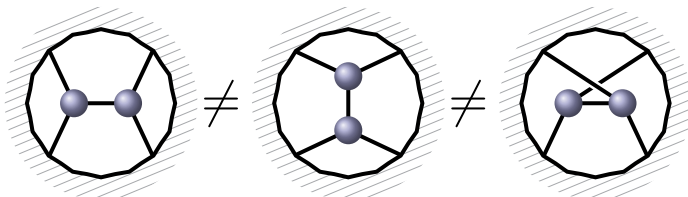
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The diagram shows three diagrams representing the Jacobi identity for three-point vertices. The first diagram is a tree-level diagram with three external legs labeled  $\alpha$ ,  $\beta$ , and  $\gamma$ , and one internal line labeled  $\delta$ . The second diagram is a tree-level diagram with three external legs labeled  $\alpha$ ,  $\beta$ , and  $\gamma$ , and one internal line labeled  $\delta$ . The third diagram is a tree-level diagram with three external legs labeled  $\alpha$ ,  $\beta$ , and  $\gamma$ , and one internal line labeled  $\delta$ . The equation is:  $\text{Diagram 1} - \text{Diagram 2} - \text{Diagram 3} = 0$ .

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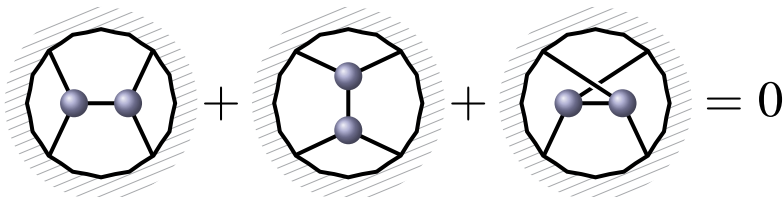
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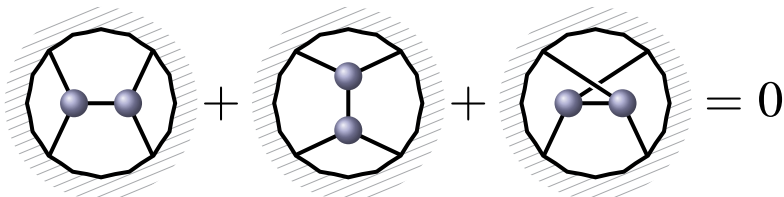


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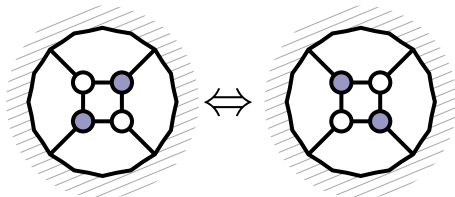


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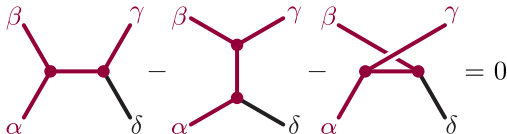
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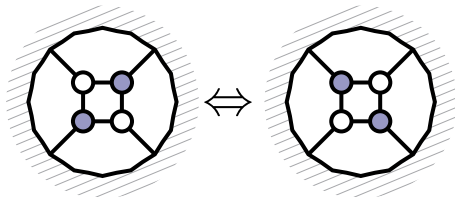
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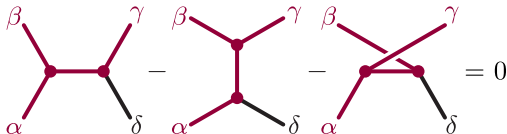
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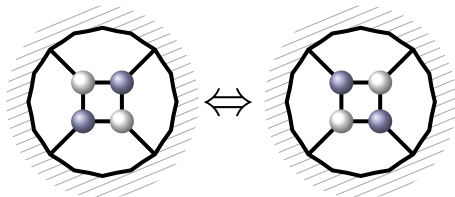
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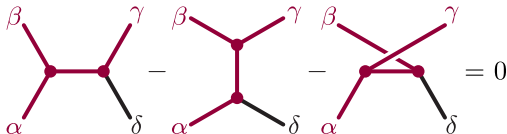
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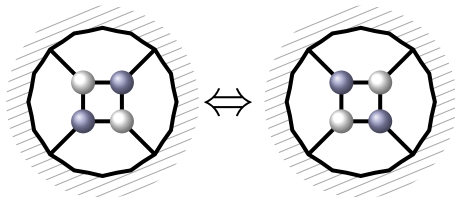
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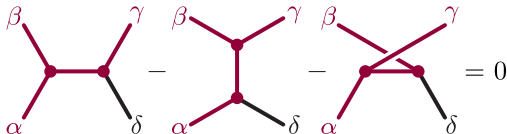
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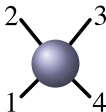
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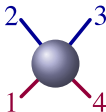
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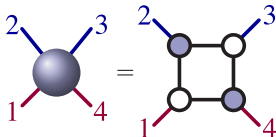
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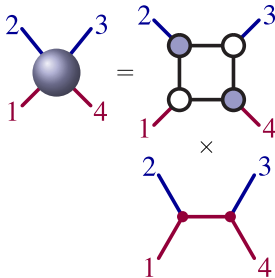
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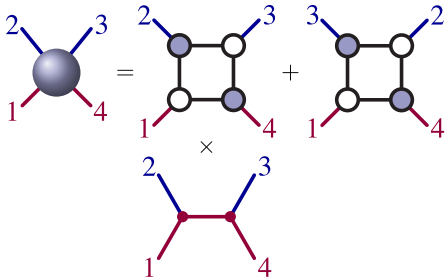
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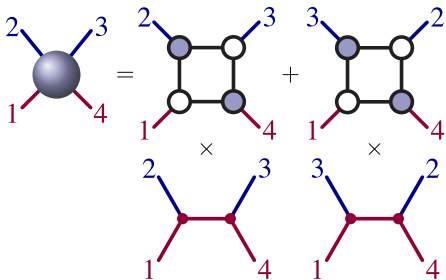
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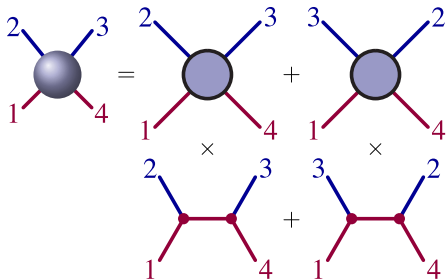
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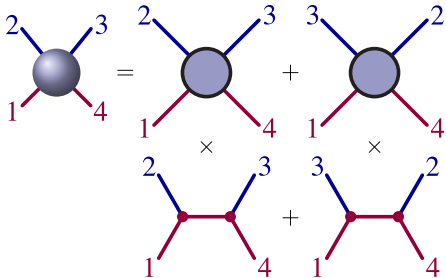
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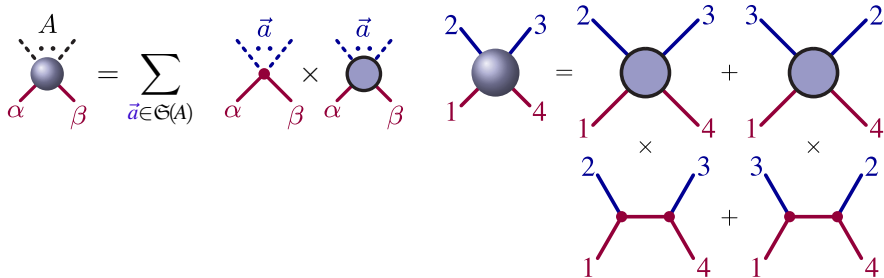


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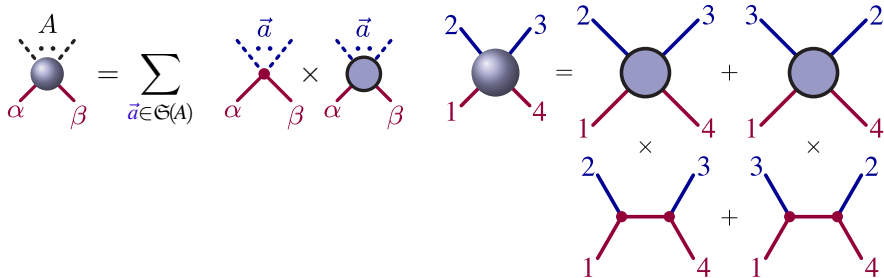


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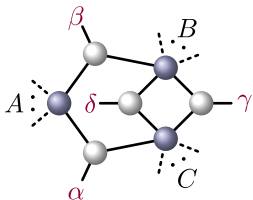
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$$A_{\alpha\beta} = \sum_{\vec{a} \in \mathfrak{S}(A)} A_{\alpha\beta}^{\vec{a}}$$

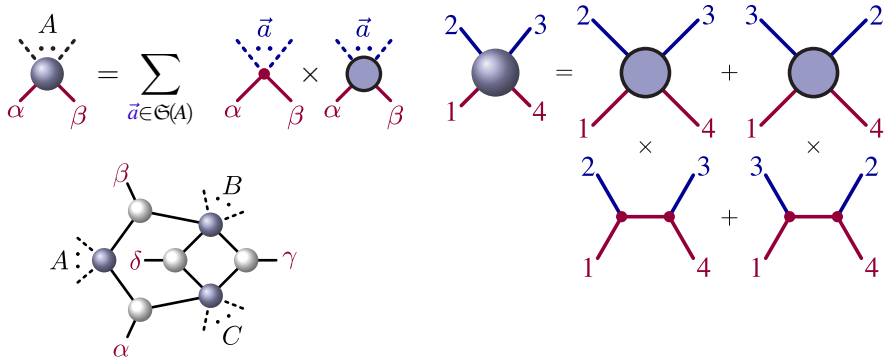


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$$A = \sum_{\vec{a} \in \mathfrak{G}(A)} \text{red vertex}(\alpha, \beta, \vec{a}) \times \text{grey vertex}(\alpha, \beta, \vec{a})$$

$$A = \sum_{\substack{\vec{a} \in \mathfrak{G}(A) \\ (\vec{b}_1 | \vec{b}_2) \in \mathfrak{G}(B) \\ (\vec{c}_1 | \vec{c}_2) \in \mathfrak{G}(C)}} \text{red loop}(\alpha, \beta, \gamma, \vec{a}, \vec{b}_1, \vec{b}_2, \vec{c}_1, \vec{c}_2) \times \text{grey loop}(\alpha, \beta, \gamma, \vec{a}, \vec{b}_1, \vec{b}_2, \vec{c}_1, \vec{c}_2)$$

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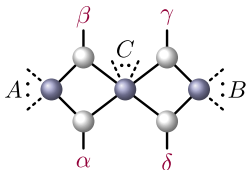
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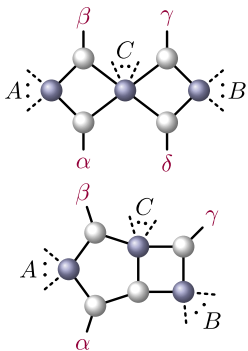
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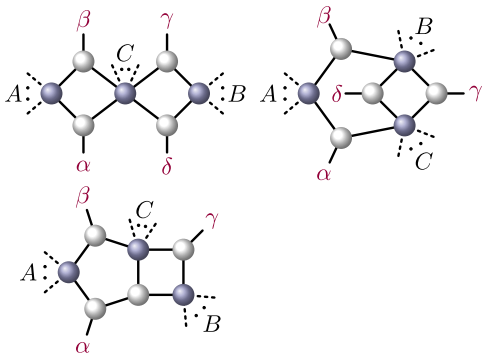
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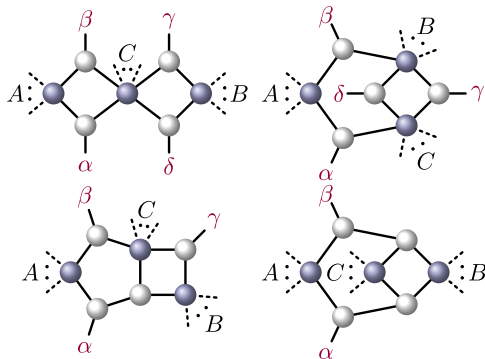
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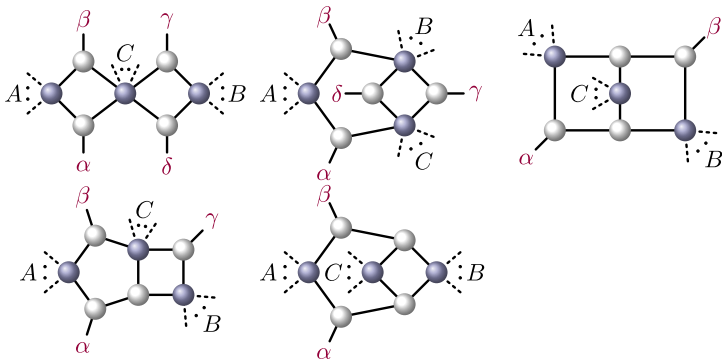
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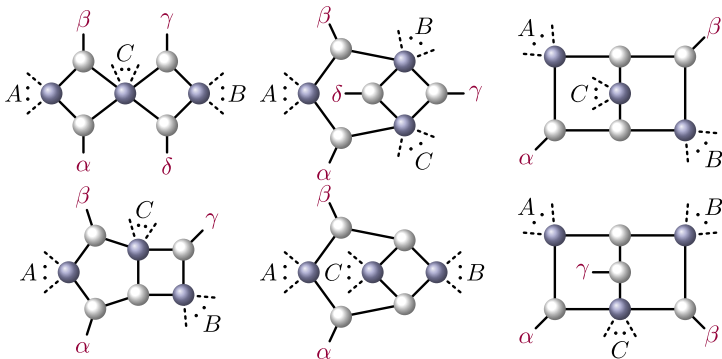
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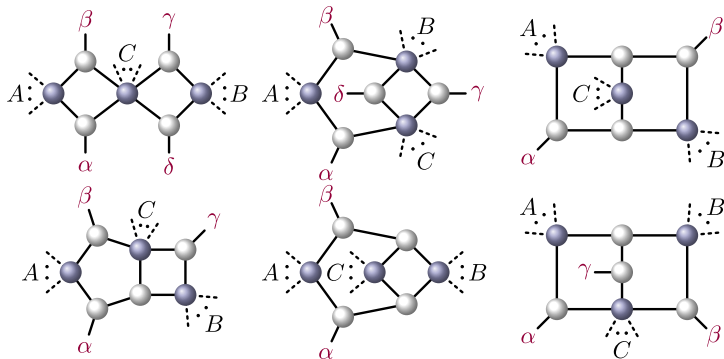
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Matching each of these ‘cuts’ (including degenerations) and the ensuring the absence of any other boundaries suffices to determine all-multiplicity MHV amplitudes at two loops!

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