From matroid subdivisions of hypersimplices to generalized Feynman diagrams

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Nick Early Matroid subdivisions and generalized Feynman diagrams

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Blades on the \mathcal{U} niversal \mathcal{O} ctahedron.

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 Background. I'll tell two parallel stories, both starting in 2012-2013, which ultimately joined forces in 2018/2019: my (math) Ph.D. thesis on symmetries and invariants for subdivisions of hypersimplices, and the CHY method for computing biadjoint scattering amplitudes.

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- Objective (0): interpret the biadjoint scalar scattering amplitude m^(k=2)(I_n, I_n) in terms of matroid subdivisions of a convex polytope known as the (second) hypersimplex, Δ_{2,n}.
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- Objective (3): show how these arrangements select a natural set of planar functions on the kinematic space for all *n* and *k*. These define a basis, the *planar basis*.
- *Remark:* These specialize for k = 2 to the planar basis introduced by [CHY2013] and denoted X_{ij} in [ABHY2017].

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A model for $m^{(k)}(\mathbb{I}_n,\mathbb{I}_n)$

The kinematic space K_{k,n} lives in the space of symmetric tensors in R⁽ⁿ⁾.

$$\mathcal{K}_{k,n} = \left\{ (s) \in \mathbb{R}^{\binom{n}{k}} : \sum_{J: J \ni a} s_J = 0 \text{ for each } a = 1, \dots, n
ight\}.$$

Goal: to construct m^(k)(I_n, I_n) inside K_{k,n} for m^(k)(I_n, I_n) using exactly two bits of information: one convex polytope, the hypersimplex

$$\Delta_{k,n} = ext{convex hull} \left\{ x \in \{0,1\}^n : \sum x_i = k
ight\}$$

and the facets of the simplex¹

$$\left\{x\in\mathbb{R}^n: 0\leq x_1\leq x_2\leq\cdots\leq x_n\leq 1\right\}.$$

¹More precisely, we need its normal fan. Nick Early Matroid subdivisions and generalized Feynman diagrams

Some history

• [CHY, 2013]. Scattering equations compute k = 2 biadjoint scalar scattering amplitudes: finite sum over critical points of a potential function in the moduli space of n points on the torus quotient of the Grassmannian $X(2, n) = G(2, n)/(\mathbb{C}^*)^n$,

$$\mathcal{S} = \sum_{1 \leq i < j \leq n} s_{ij} \log \left(\det \begin{bmatrix} x_i & x_j \\ y_i & y_j \end{bmatrix} \right),$$

where (s_{ij}) are symmetric matrices, with entries Mandelstam invariants; for well-definedness one assumes

$$\sum_{j\neq i} s_{ij} = 0 \text{ for all } i.$$

• One writes, schematically

$$m^{(2)}(\mathbb{I}_n,\mathbb{I}_n)=\int_{X(2,n)}\delta\left(\frac{\partial S}{\partial y}\right)PT(12\cdots n)^2,$$

where the SL(2)-measure is implicit.

Motivation for the generalized biadjoint scalar theory

 Key observation: duality for Grassmannians implies that CHY holds for both moduli spaces:

$$X(2, n) \longleftrightarrow \cdots \longrightarrow X(n-2, n),$$

where we identify $X(k, n) = G(k, n)/(\mathbb{C}^*)^n$.

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Basic ingredients of the generalized biadjoint scalar theory, (here for k=3)

- [CEGM March, 2019]. We generalized the CHY method, from n points on the Riemann sphere, X(2, n), to the configuration space X(k, n) of n points in \mathbb{CP}^{k-1} .
- This filled in the gap $X(2, n) \Leftrightarrow X(n-2, n)...$
- Along the way we discovered that some of our formulas appeared in the math literature, in the context of the tropical Grassmannian (and its positive part)!
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- Along the way we discovered that some of our formulas appeared in the math literature, in the context of the tropical Grassmannian (and its positive part)!
- Then the connection to matroid subdivisions quickly fell into place.
- Now define a (potential) function $\mathcal{S} : X(3, n) \to \mathbb{C}$:

$$S = \sum_{1 \le a < b < c \le n} s_{abc} \log (|abc|)$$

Introducing $m^{(3)}(\mathbb{I}_n,\mathbb{I}_n)$

- Generalized Mandelstam invariants s_{abc} are linear functions on the space of (symmetric) tensors, $\mathbb{R}^{\binom{n}{3}}$.
- Rem. The s_{abc} satisfy ∑_{(a<b)≠t} s_{abt} = 0 for each t if and only if S is well-defined on X(3, n).
- [CEGM2019]. The *k*-Parke Taylor factor (in the natural cyclic order) is

$$PT^{(3)}(1,2,\ldots,n) := \frac{1}{|123||234|\cdots|n12|}$$

and for $\textit{n}\text{-cycles}\ \alpha,\beta,$ the generalized biadjoint scalar amplitude is

$$m_n^{(3)}(\alpha|\beta) = \sum_{I=1}^{\mathcal{N}_n^{(3)}} \left(\frac{1}{\det' \Phi^{(3)}} \mathrm{PT}^{(3)}(\alpha) \mathrm{PT}^{(3)}(\beta) \right) \Big|_{x_a = x_a^{(I)}, y_a = y_a^{(I)}}$$

The generalized biadjoint scattering amplitude is computed by summing over the critical points of S, for a given choice of kinematics (s_{abc}) . Here $\Phi^{(3)}$ is the Hessian matrix for S.

• [CEGM, April 2019]. We solved the scattering equations directly, choosing kinematics s_{abc} to be large prime numbers, to obtain $m^{(3)}(\mathbb{I}_6, \mathbb{I}_6)$.

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- [CEGM, April 2019]. We solved the scattering equations directly, choosing kinematics s_{abc} to be large prime numbers, to obtain $m^{(3)}(\mathbb{I}_6,\mathbb{I}_6)$.
- Remark: by changing the integrand we also found a non-planar Feynman diagram (not in m⁽³⁾(I₆, I₆)),

*s*₁₂₃*s*₃₄₅*s*₅₆₁*s*₂₄₆

- For k = 2, pairwise pole compatibility ⇒ that every Feynman diagram has exactly n 3 propagators.
- Novel for $k \geq 3$:

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 $m^{(3)}(\mathbb{I}_6, \mathbb{I}_6) = \underbrace{\frac{1}{\underset{\substack{s_{123}s_{456}t_{1236}t_{3456}}{\underbrace{t_{1236}t_{3456}}_{4 \text{ compatible here}}}}_{4 \text{ compatible here}} + \underbrace{\frac{R_{12,34,56} + R_{12,56,34}}{\underbrace{t_{1234}t_{3456}t_{1256}R_{12,34,56}R_{12,56,34}}_{\text{but 5 here!}}}_{\text{but 5 here!}} + (46 \text{ more})$

Here

$$t_{1234} = s_{123} + s_{134} + s_{124} + s_{234}, \ R_{12,34,56} = t_{1234} + s_{125} + s_{126}.$$

Nontrivial linear relations among poles, e.g.

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Rest of the talk will be mostly combinatorial...

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- [Mizera, June 2017] and [ABHY, Nov 2017]: identification of $m^{(2)}(\mathbb{I}_n, \mathbb{I}_n)$ with an associahedron in the (k = 2) kinematic space.
- Circa December, 2017 and beyond. After ABHY's treatment of kinematic space and pole compatibility on the associahedron: the story connecting amplitudes to matroid subdivisions started to become coalesce...

The \mathcal{U} niversal \mathcal{O} ctahedron determines pole compatibility for $\Delta_{2,n}$ (and beyond)



Main example: the four tetrahedra now share a common edge connecting e_{13} to e_{24} , which is not a *root* $e_i - e_i$; this is <u>bad!</u>

Octahedron: Δ_{2,4} = convex hull{e_i + e_j : 1 ≤ i < j ≤ 4}. All edges are parallel to roots e_i − e_j.

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- Octahedron: Δ_{2,4} = convex hull{e_i + e_j : 1 ≤ i < j ≤ 4}. All edges are parallel to roots e_i − e_j.
- Three ways to split the octahedron into two half-pyramids $\Leftrightarrow \{\frac{1}{s_{12}}, \frac{1}{s_{23}}, \frac{1}{s_{13}}\}...$
- But only $\frac{1}{s_{12}}$ and $\frac{1}{s_{23}}$ appear in $m^{(2)}((1234), (1234))$.

What is a matroid subdivision?



Fact: A subdivision of $\Delta_{k,n}$ is (1) matroidal and (2) compatible with the cyclic order $(12 \cdots n)$, if and only if on any octahedral face it coincides with one of these two pictures, replacing (1 < 2 < 3 < 4) with any (a < b < c < d).

The construction using the gray rays of *blade arrangements* is new [E,Oct2019] and will be explained.

First clue: momentum conservation on the octahedron

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 $s_{12}+s_{13}+s_{14}=0, s_{21}+s_{23}+s_{24}=0, \ldots, s_{12}+s_{23}+s_{13}=0, \ldots$ This has a nice interpretation on $\Delta_{2,4}$:

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So, sum s_{ij} over any triangular face and get zero.

Second clue

 For more particles n ≥ 5, momentum conservation translates to averaging over the facets x_i = 1 of the 2nd hypersimplices

$$\Delta_{2,n} = \left\{ x \in [0,1]^n : \sum_{i=1}^n x_i = 2 \right\}.$$

• <u>Second clue</u>: the Mandelstam variables are reflection invariant; similarly, there is an invariant hyperplane:

$$(s_J = s_{J^c}) \Leftrightarrow \left\{ x \in \Delta_{2,n} : \sum_{j \in J} x_j = 1 = \sum_{j \in J^c} x_j \right\}.$$

 Each such invariant hyperplane divides Δ_{2,n} into a pair of convex polytopes.

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- <u>Third clue</u>: namely, the matroid polytopes $\sum_{j \in J} x_j \ge 1$ and $\sum_{j \in J} x_j \le 1!$
- Fourth clue: compatibility for poles of Feynman diagrams...

Compatible poles

- Following usual notation, Mandelstam invariants are sums of coordinate functions on the kinematic space: s_J = ∑_{(i<j)∈J} s_{ij} for J a subset of [n], and s_J = s_{J^c} by momentum conservation.
- Compatibility rule for k = 2 Feynman diagrams:

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- Compatibility rule for k = 2 Feynman diagrams: a product ¹/_{sJ1^sJ2} with subsets J₁ ≠ J₂ ⊂ [n] appears in the Feynman diagram expansion of m⁽²⁾(α, α) for some planar order α if and only if at least one intersection is empty: J₁ ∩ J₂, J₁ ∩ J₂^c, J₁^c ∩ J₂, J₁^c ∩ J₂^c.
- For example:

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- Compatibility rule for k = 2 Feynman diagrams: a product $\frac{1}{s_{J_1}s_{J_2}}$ with subsets $J_1 \neq J_2 \subset [n]$ appears in the Feynman diagram expansion of $m^{(2)}(\alpha, \alpha)$ for some planar order α if and only if at least one intersection is empty:
 - $J_1 \cap J_2, \ J_1 \cap J_2^c, \ J_1^c \cap J_2, \ J_1^c \cap J_2^c.$
- For example:

$$m^{(2)}(\mathbb{I}_5,\mathbb{I}_5) = \frac{1}{s_{12}s_{123}} + \frac{1}{s_{12}s_{34}} + \frac{1}{s_{23}s_{123}} + \frac{1}{s_{23}s_{234}} + \frac{1}{s_{34}s_{234}}$$

 Now it's easy to see that summands are in bijection with the five finest matroid subdivisions of Δ_{2,5} compatible with the cyclic order (12345).

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Matroid subdivisions and Feynman diagrams: bijection



Three 2-splits of $\Delta_{2,6}$: (1) $x_1 + x_2 = 1 \Leftrightarrow s_{12}$ (2) $x_1 + x_2 + x_3 = 1 \Leftrightarrow s_{123}$ (3) $x_1 + x_2 + x_3 + x_6 = 1 \Leftrightarrow s_{1236}$

³Key insight: these 2-splits are pairwise compatible! E.g. $(\{1,2,3\} \cap \{4,5\} = \emptyset)$, satisfying compatibility.

Three compatible hyperplanes \Leftrightarrow poles in $\frac{1}{s_{12}s_{123}s_{1236}}$

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Now easy to conclude: given a planar order $(12 \cdots n)$, finest positroidal subdivisions of $\Delta_{2,n}$ are in bijection with Feynman diagrams with legs ordered $(12 \cdots n)$.

In fact, the whole amplitude $m^{(2)}(id, id)$ is a sum over all finest positroidal subdivisions of $\Delta_{2,n}$.

Can the identification be made explicit? $\Delta_{k,n} = \{[0,1]^n : \sum_{i=1}^n x_i = k\}$?

Parametrizing $m^{(k)}(\mathbb{I}_n, \mathbb{I}_n)$ for any k with positroidal subdivisions

- Before introducing the planar basis and weakly separated collections, we'll need some general results...
- Defn. The kinematic space K_{k,n} is a codimension n subspace of ℝ⁽ⁿ⁾,

$$\mathcal{K}_{k,n} = \left\{ (s) \in \mathbb{R}^{\binom{n}{k}} : \sum_{J:J \ni a} s_J = 0 \text{ for each } a = 1, \dots, n
ight\}.$$

Hypersimplices, matroid polytopes & subdivisions

• A hypersimplex is an integral cross-section of a unit cube:

$$\Delta_{k,n} = \left\{ x \in [0,1]^n : \sum_{i=1}^n x_i = k \right\}, \ 1 \le k \le n-1.$$
$$= \text{convex hull} \left\{ e_J : J \in \binom{[n]}{k} \right\},$$

where $e_J = e_{j_1} + \cdots + e_{j_k}$ and J runs over all k-element subsets of $[n] = \{1, \ldots, n\}$.

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- For example, $\Delta_{1,4}, \Delta_{3,4}$ are tetrahedra, while $\Delta_{2,4}$ is an octahedron.
- A matroid polytope is...

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- For example, $\Delta_{1,4}, \Delta_{3,4}$ are tetrahedra, while $\Delta_{2,4}$ is an octahedron.
- A matroid polytope is... a subpolytope P of (some) Δ_{k,n} such that every edge of P is parallel to an edge of Δ_{i,j}: {e_i e_j : i ≠ j}.
- A matroid subdivision is a decomposition of $\Delta_{k,n}$ into matroid polytopes intersecting only on their common facets.

- **Defn/Example.** A 2-split (of $\Delta_{2,n}$) is a decomposition $\Pi_1 \cup \Pi_2 = \Delta_{2,n}$ into matroid polytopes sharing a common facet $\Pi_1 \cap \Pi_2$.
- For Δ_{2,n} these look like ∑_{j∈J} x_j = 1 with 2 ≤ |J| ≤ n − 2. The common facet is a Cartesian product of simplices of dimensions |J| − 1 and |J^c| − 1.
- \hookrightarrow 2-splits of $\Delta_{2,n}$ are well-understood mathematically, and familiar from $m^{(2)}(\mathbb{I}_n, \mathbb{I}_n)$.

The two subdivisions of an octahedron



The two nontrivial blade arrangements on the octahedron $\Delta_{2,4}$. Edges of the octahedron are in the directions $e_i - e_j$. Same for the pairs of square pyramids.

 There's a well-known compatibility rule for 2-splits of the second hypersimplex Δ_{2,n}...

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- There's a well-known compatibility rule for 2-splits of the second hypersimplex Δ_{2,n}...
- Maximal cells of the subdivision of Δ_{2,n} induced by the pair of hyperplanes ∑_{i∈J1} x_i = 1 and ∑_{i∈J2} x_i = 1 are matroid polytopes if and only if at least one intersection is empty: J₁ ∩ J₂, J₁ ∩ J₂^c, J₁^c ∩ J₂, J₁^c ∩ J₂^c.
- The compatibility rule for pairs of matroid subdivisions of $\Delta_{k,n}$ involves checking a condition on each little octahedral facet of $\Delta_{k,n}$!

Blades on a hexagon

- Recap: for Δ_{2,n}, poles are 2-splits and Feynman diagrams are superpositions of 2-splits.
- New for $k \ge 3$ subdivisions:

Blades on a hexagon

- Recap: for Δ_{2,n}, poles are 2-splits and Feynman diagrams are superpositions of 2-splits.
- New for k ≥ 3 subdivisions: poles correspond to splittings of Δ_{k,n} into more than 2 chambers!
- [E,Oct2019] Introduced a new method to induce splits:



1-split, 2-split, 3-split: induced by gluing a single blade ((1,2,3)) to a vertex of a hexagon.

Blades in higher dimensions



Blades ((1,2,3)) and ((1,2,3,4)). Left: bends of the function $h(x) = \min\{x_2 + 2x_3, x_3 + 2x_1, x_1 + 2x_2\}$. Definition due to my Ph.D. co-adviser, A. Ocneanu.

Blade Definition

 Definition [Ocneanu]. Fix an integer n ≥ 3. The blade ((1,2,...,n)) is the union of the boundaries of n polyhedral cones:

$$((1,2,\ldots,n)) = \bigcup_{j=1}^n \partial \left\{ \sum_{i\neq j} t_i (e_i - e_{i+1}) : t_i \geq 0 \right\}.$$

• Some related notions:

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- Some related notions:
- Prop[E,2019]. This is a particular kind of *tropical* hypersurface. It is also the (n − 2 skeleton of) the normal fan to the simplex x₁ ≤ ··· ≤ x_n ≤ x₁ + 1.

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Main constructions

- Definition. A blade arrangement is a superposition of several copies of a blade on a hypersimplex Δ_{k,n}.
- **Definition**. A matroidal blade arrangement is an arrangement of blades on some of the $\binom{n}{k}$ vertices $\sum_{j=1}^{k} e_{i_j}$ of a hypersimplex such that every maximal cell is matroidal: i.e., every edge of every maximal cell is in a root direction $e_i e_j$.
- **Prop**[E, Oct2019]. Any matroid subdivision that is induced by a matroidal blade arrangement is *positroidal*: locally it intersects the octahedron in one of the splits induced by one of the two (equatorial) squares, $x_1 + x_2 = 1$ or $x_1 + x_4 = 1$.
- Idea of proof: compute explicitly the internal facet inequalities. They should be of the form x_i + x_{i+1} + · · · + x_{i+j} ≥ a_{ij}, where the index sets are cyclic modulo n.

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Three blades arranged on $\Delta_{3,6}$ (seen projected into the plane)



Two arrangements of the blade ((1, 2, 3)) on the vertices of a hexagon. Blade arrangement on left induces the trivial subdivision. Blade arrangement on right induces a 6-chamber subdivision.

These are projections of matroidal blade arrangements on $\Delta_{3,6}$.

• **Definition.** (due to Leclerc-Zelevinsky; we rephrase for our purposes). A pair of *k*-element subsets $J_1, J_2 \in {[n] \choose k}$ is weakly separated² if $e_{J_1} - e_{J_2}$ avoids $(\dots + e_a - e_b + e_c - e_d + \dots)$ for the cyclic pattern a < b < c < d.

• Example
$$(k, n) = (3, 6)$$
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- **Definition.** (due to Leclerc-Zelevinsky; we rephrase for our purposes). A pair of *k*-element subsets $J_1, J_2 \in {[n] \choose k}$ is weakly separated² if $e_{J_1} e_{J_2}$ avoids $(\dots + e_a e_b + e_c e_d + \dots)$ for the cyclic pattern a < b < c < d.
- Example (k, n) = (3, 6). Then e₁₃₄ − e₂₄₅ = e₁ − e₂ + e₃ − e₅, so {134, 245} is not weakly separated.

²compare in what follows to the classical Steinmann-relations ($a \rightarrow b = 0$)

Main combinatorial result

- Thm[E,Oct.2019]. An arrangement of the blade
 ((1,2,...,n)) on the vertices e_{J1},..., e_{JN} ∈ Δ_{k,n} induces a
 matroid subdivision of Δ_{k,n} if and only if the collection
 {J₁,...,J_N} is weakly separated.
- Comments:

Main combinatorial result

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 matroid subdivision of Δ_{k,n} if and only if the collection
 {J₁,...,J_N} is weakly separated.
- Comments: This is actually really strong. For generic matroid subdivisions of $\Delta_{k,n}$ for large k and n we would have a large computational task to determine their compatibility.
- Can our construction can be used to leverage larger computations for generic matroidal subdivisions?
- We conclude with some illustrations...

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Numbers of finest positroidal subdivisions $\Delta_{k,n}$ induced by blade arrangements

The table below uses weakly separated collections to enumerate *subsets* of the set of finest positroidal subdivisions of $\Delta_{k,n}$. **Prop.** These map to arrays of Feynman diagrams from [CGUZ]. Notably,

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$n \setminus k$	2	3	4	5	6	7	8	9	10
4	2								
5	5	5							
6	14	34	14						
7	42	259	259	42					
8	132	2136	5470	2136	132				
9	429	18600	122361	122361	18600	429			
10	1430	168565	2889186	7589732	2889186	168565	1430		
11	4862	1574298	71084299			71084299	1574298	4862	
12	16796	15051702						15051702	16796

Blade arrangement on $\Delta_{3,7}$



Embedding of the blade arrangement $\{124,247,267,347,457,467\}$ on the 1-skeleton of $\Delta_{3,7}.$

Blade arrangements induce collections of Feynman diagrams



The seven boundaries of the blades labeled by the weakly separated collection $\{124, 247, 267, 347, 457, 467\}$. Each tree encodes

Blade arrangements induce collections of Feynman diagrams



The seven boundaries of the blades labeled by the weakly separated collection {124, 247, 267, 347, 457, 467}. Each tree encodes a matroid subdivision of a face of $\Delta_{3,7}$, i.e., a copy of $\Delta_{2,6}$. The boundary operator can be defined directly on sets of *k*-tuples (not obvious!).

• An essential question: which matroid subdivisions are induced by matroidal blade arrangements?

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Blades induce positroidal multi-splits

 An essential question: which matroid subdivisions are induced by matroidal blade arrangements? Denote
 e_{j1},...,j_k = e_{j1} + ··· + e_{jk}. Put ((1, 2, ..., n))_{ej} for the translation of the blade to the vertex e_j.

- An essential question: which matroid subdivisions are induced by matroidal blade arrangements? Denote
 e_{j1},...,j_k = e_{j1} + ··· + e_{jk}. Put ((1, 2, ..., n))_{ej} for the translation of the blade to the vertex e_j.
- Theorem[E, Oct2019] The blade ((1, 2, ..., n))_{e_J} induces a multi-split positroidal subdivision of Δ_{k,n}, where the maximal cells are nested matroids. The number of maximal cells in the subdivision equals the number of cyclically consecutive intervals in the labels in J.

Let
$$V_0^n \subset \mathbb{R}^n$$
 be the hyperplane $x_1 + \cdots + x_n = 0$.

Defn. Let $h: V_0^n \to \mathbb{R}$ be the piece-wise linear function $h(x) = \min\{L_1(x), \dots, L_n(x)\}$, where

$$L_j = x_{j+1} + 2x_{j+2} + \cdots (n-1)x_{j-1}.$$

Prop.[E,Oct2019].

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Prop.[E,Oct2019]. The blade ((1, 2, ..., n)) equals the bend locus of the function h(x). That is,

$$((1,2,\ldots,n)) = \{x \in V_0^n : (L_i(x) = L_j(x)) \le L_\ell(x) \text{ for all } \ell \neq i,j\}.$$

Defn.[E,Dec 2019]. At each vertex $e_J (= \sum_{j \in J} e_j) \in \Delta_{k,n}$, we'll glue a copy of ((1, 2, ..., n)) and define a linear form on $\mathcal{K}_{k,n}$:

³ frozen elements are zero: $\eta_{i,i+1,...,i+(k-1)} = 0$ Nick Early Matroid subdivisions and generalized Feynman diagrams **Defn.**[E,Dec 2019]. At each vertex $e_J (= \sum_{j \in J} e_j) \in \Delta_{k,n}$, we'll glue a copy of ((1, 2, ..., n)) and define a linear form on $\mathcal{K}_{k,n}$: set

$$\rho_J(x) = h(x - e_J), \text{ and } \eta_J = -\frac{1}{n} \sum_{e_I \in \Delta_{k,n}} \rho_J(e_I) s_I.$$

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[E, Dec2019]. The set $\{\eta_J : J \text{ is nonfrozen}\}\$ is a basis³, the *planar* basis, for the space of linear forms on the kinematic space $\mathcal{K}_{k,n}$. These objects η_J have some useful properties which we discuss now...

Warm up, k = 2. On the kinematic space $\mathcal{K}_{2,6}$

$$\eta_{24} = \frac{1}{4} \left(3s_{12} + 2s_{13} + s_{14} + s_{23} + 3s_{34} \right)$$

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Of course this all works beautifully for $k \ge 3$: e.g., (3,6):

$$\eta_{135} = \frac{1}{6} \left(3s_{123} + 2s_{124} + s_{125} + 6s_{126} + \dots + s_{356} + 6s_{456} \right)$$

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Why linear forms η_J ?

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$$\eta_{135} = \frac{1}{6} (3s_{123} + 2s_{124} + s_{125} + 6s_{126} + \dots + s_{356} + 6s_{456}) \\ \equiv s_{123} + s_{126} + s_{136} + s_{234} + s_{235} + s_{236}.$$

This is one of the new poles (" $R_{16,23,45}$ ") in $m^{(3)}(\mathbb{I}_6,\mathbb{I}_6)!$

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Nice "cubical" rule for expanding s_J as a sum of η_J's (k = 2 case familiar):

$$s_{25} = -(\eta_{14} - \eta_{15} - \eta_{24} + \eta_{25}).$$

• There is a generalization to $k \ge 3$:

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• There is a generalization to $k \ge 3$:

 $-s_{235} = \eta_{235} - \eta_{234} - \eta_{135} + \eta_{134}$

 $-s_{246} = \eta_{246} - \eta_{146} - \eta_{236} + \eta_{136} - \eta_{245} + \eta_{145} + \eta_{235} - \eta_{135}.$

Planar basis: explicit inversion formula

[E,Dec2019] Given a nonfrozen vertex e_J ∈ Δ_{k,n} with t(≥ 2) cyclic intervals, with cyclic initial points say j₁,..., j_t, consider the t-dimensional cube

$$C_J = \left\{ J_L = \{ j_1 - \ell_1, \dots, j_t - \ell_t \} : L = (\ell_1, \dots, \ell_t) \in \{0, 1\}^t \right\}.$$

Then the following "cubical" relation among linear functionals holds identically on $\mathbb{R}^{\binom{n}{k}}$, as well as on the subspace $\mathcal{K}_{k,n}$:

$$\sum_{L\in C_J} (-1)^{L\cdot L} \eta_{J_L} = -s_J,$$

where $L \cdot L$ is the number of 1's in the 0/1 vector L.

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• In the planar basis, $m^{(3)}(\mathbb{I}_6,\mathbb{I}_6)$ has the expression

$$m^{(3)}(\mathbb{I}_{6},\mathbb{I}_{6}) = \frac{1}{\eta_{125}\eta_{134}\eta_{135}\eta_{145}} + \frac{1}{\eta_{124}\eta_{125}\eta_{134}\eta_{145}} \\ + \frac{1}{\eta_{136}\eta_{145}\eta_{146}(-\eta_{135}+\eta_{136}+\eta_{145}+\eta_{235})} \\ + \frac{\eta_{136}+\eta_{145}+\eta_{145}+\eta_{235}}{\eta_{135}\eta_{136}\eta_{145}\eta_{235}(-\eta_{135}+\eta_{136}+\eta_{145}+\eta_{235})} + 44 \text{ more.}$$

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Thank you!



q-plate in dimension 3

Nick Early Matroid subdivisions and generalized Feynman diagrams

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